As a Robotic Hand Locating Pin Clamp

Model SWP

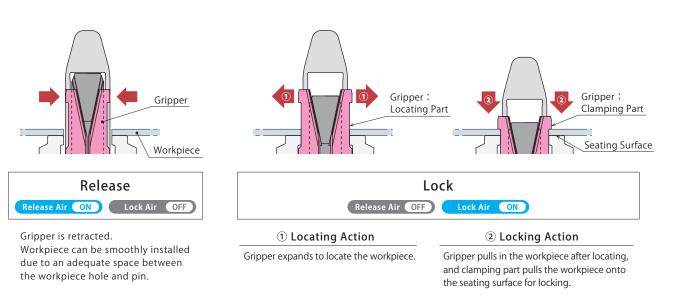


Expansion Pin Clamp allows for

PAT.

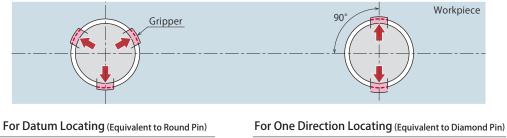
High-Accuracy Locating and Clamping of Thin Workpieces

Action Description



Functions

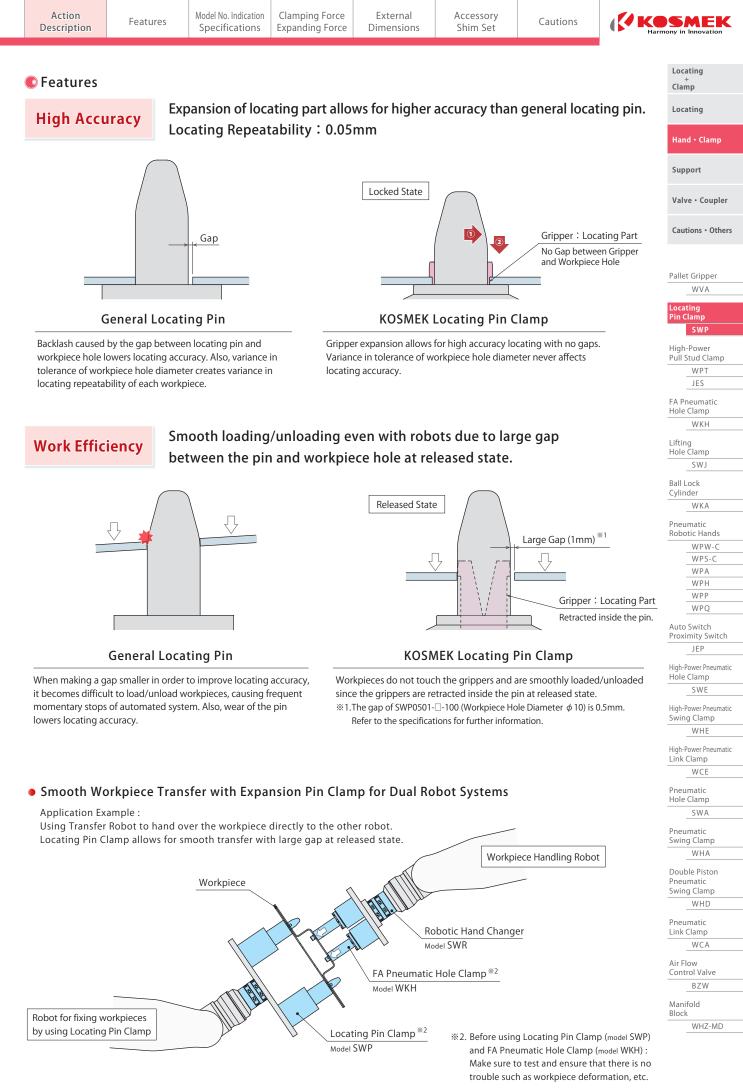
As general locating pin, Pin Clamp has two types: Datum Locating Pin (round pin) and One-Direction Locating Pin (diamond pin).

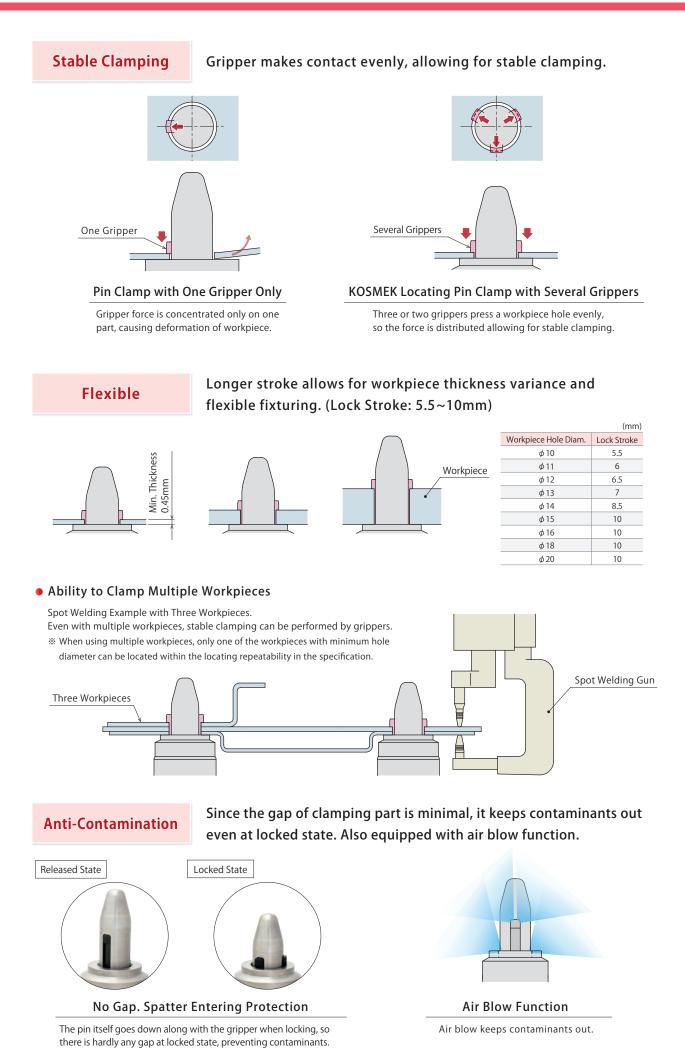


Workpiece hole and gripper make contact at three points for datum locating.



Workpiece hole and gripper make contact, perpendicular to the reference hole, at two points for one-direction locating.





Action Description	Features	Model No. Indication Specifications	Clamping Force Expanding Force	External Dimensions	Accessory Shim Set	Cautions	K	SMEK
Compac	t•Light	Short body	allows for m	nore compact	t and lighter	application	5.	Locating + Clamp Locating
	Weight : 7	700 g				/		Hand • Clamp
W-:		The second secon						Support
Weight : 380 g		L					1	Valve • Coupler
		135 mm d State)			/			Cautions • Others
Compact: 108 mm	(Released State)	Compact : 135 m (Released State)		Positioner		E C	P	Pallet Gripper
			Less Load to	the Positioner	Compact a	and Light Transf	er Hand	SWP
Ex. 1 SWP0501		-□-200-□ Hole Diam. ø 20)		h light Pin Clamp o the positioner.		d Light Locating Pir ble for transferring 1		High-Power Pull Stud Clamp WPT JES

• Compact and Light Locating Pin Clamp is also suitable for spot welding with a robot holding a workpiece.

(Workpiece Hole Diam. ϕ 10)

(Workpiece Hole Diam. ϕ 20)

Ball Lock Application Example for Work Efficiency and Space Saving : Cylinder One robot can both transfer and weld by using Locating Pin Clamp as a robotic hand. Compact and light body improves operability and reduces a load to the robot. Pneumatic Robotic Hands Robot for fixing workpiece by using Locating Pin Clamp Robotic Hand Changer Locating Pin Clamp Installation Plate Model SWR Allows for Extremely Thin Installation Plate Auto Switch Г Proximity Switch Spot Welding Gun High-Power Pneumatic Locating Pin Clamp $\overline{\mathbf{v}}$ Hole Clamp Model SWP Ē Ů High-Power Pneumatic Workpiece Swing Clamp High-Power Pneumatic Link Clamp Pneumatic Hole Clamp Pneumatic Swing Clamp Double Piston Pneumatic Swing Clamp Pneumatic Link Clamp Air Flow Control Valve Manifold Block

FA Pneumatic Hole Clamp WKH Lifting Hole Clamp SWJ

WKA

WPW-C

WPS-C WPA WPH WPP

WPQ

JEP

SWE

WHE

WCE

SWA

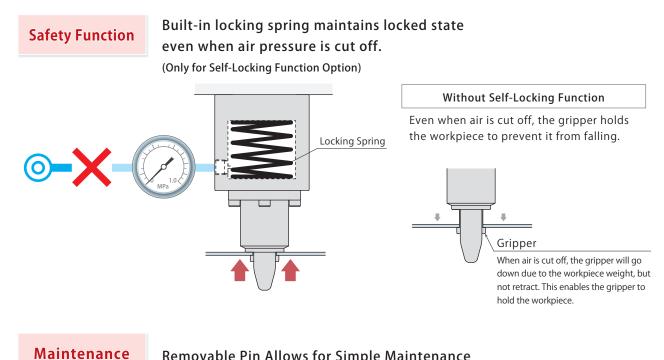
WHA

WHD

WCA

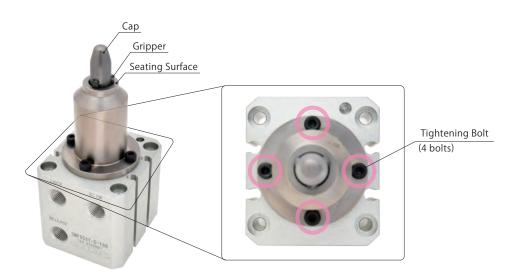
BZW

WHZ-MD



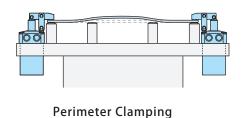
Removable Pin Allows for Simple Maintenance

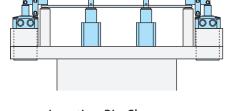
The gripper and cap can be replaced by removing tightening bolts on the seating part. No special tools or hard work are required for maintenance. It also helps customer prepare for replacements.



No Bending

Compared to perimeter clamping, Locating Pin Clamp is able to clamp the center of the workpiece without bending.





Locating Pin Clamp

Perimeter clamping can be the cause of bending.

No bending with Locating Pin Clamp by clamping workpiece holes.

Action Description	Features	Model No. Indication Specifications	Clamping Force Expanding Force	External Dimensions	Accessory Shim Set	Cautions	Harm	
								Locating
		Safely us	ed in autom	ation systen	ns with			Clamp
Action Co	nfirmation		nfirmation c					Locating
								Hand • Clamp
								Support
	Auto Swi	tch (Prepared by C	Customer)					Valve • Coupler
	Ability to Co	nfirm Lock/Release	Action	5.0				Cautions • Others
	Recommend	led Auto Switch						
		made by KOSMEK)		0				Pallet Gripper
	5	eld Resistant Model	:	1 5				WVA
	D-P3DWA (I	made by SMC)						Locating Pin Clamp
								SWP
								High-Power Pull Stud Clamp
								WPT JES
[Applicable	Auto Switch】							
	- P.414 for detailed	specifications						FA Pneumatic Hole Clamp
nelei lu P.405	- r.+14 IOI uetalled	specifications.						

[Applicable Auto Switch]

Please use D-P3DWA (made by SMC) for an environment which generates a magnetic field disturbance. When using an auto switch not made by Kosmek, check specifications of each manufacture. Auto Switch may be stuck out of the clamp depending on the installation position and direction.

Auto Switch Model No.	JEP0000-A2	JEP0000-A2L	JEP0000-B2	JEP0000-B2L	Ball Lock Cylinder	
Switch Type	Reed Au	ito Switch	Solid S	tate Auto Switch	WKA	
Wiring Method	2-'	Wire		3-Wire	Pneumatic	
Cable Length	1m	3m	1m	3m	Robotic Hands	
Specifications • Electric Circuit Diagram	Refer	to P.406	Re	efer to P.407	WPW-C WPS-C WPA WPH	
External Dimensions	Tight	× 0.45 Mounting Bolt ening Torque 0.25N • m Brown Cable (+) Blue Cable (-) LED Indicator		12.5×0.45 Mounting Bolt ightening Torque 0.25N • m Brown Cable (+) Black Cable (Output) Blue Cable (-) LED Indicator	WPP WPQ Auto Switch Proximity Swit JEP High-Power Pneur Bowe Swie Swie Swie Clamp	

Auto Switch Model No.	JEP0000-A2V	JEP0000-A2VL	JEP0000-B3	JEP0000-B3L	High-Power Pneumatic Link Clamp
Switch Type	Reed Aut	to Switch	Solid State	Auto Switch	WCE
Wiring Method Cable Length	2-V 1m	Vire 3m	3-V 1m	Vire 3m	Pneumatic Hole Clamp
Cable Lefigtri	1111	JIII		JII	SWA
Specifications Electric Circuit Diagram 	Refer to	o P.406	Refer t	o P.408	Pneumatic Swing Clamp
External Dimensions	M2.3 × 0.4 Mounting Bolt Tightening Torque 0.25N · m	LED Indicator Brown Cable $(+)$ Blue Cable $(-)$	2.8 (\$\$\phi_2.8\$) 	Rlack Cable (Output)	WHA Double Piston Pneumatic Swing Clamp WHD Pneumatic Link Clamp WCA Air Flow Control Valve BZW Manifold Block WHZ-MD

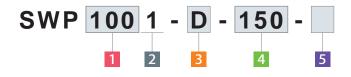
WKH

SWJ

WHE

Lifting Hole Clamp

Model No. Indication



1 Body Size ****** Refer to the Specifications, Clamping Force, Expanding Force and External Dimensions for further information.

050 : Select from Workpiece Hole Diameter ϕ 10, ϕ 11, ϕ 12, ϕ 13

100 : Select from Workpiece Hole Diameter ϕ 14, ϕ 15, ϕ 16, ϕ 18, ϕ 20

2 Design No.

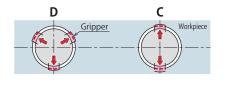
1 : Revision Number

3 Function

- **D**: Datum (For Datum Locating)
- C : Cut (For One Direction Locating)



- When selecting 1 Body Size 050 **100**: Workpiece Hole Diameter ϕ 10 \pm 0.2 **110**: Workpiece Hole Diameter ϕ 11 \pm 0.2
- **120**: Workpiece Hole Diameter ϕ 12 \pm 0.2
- **130**: Workpiece Hole Diameter ϕ 13 \pm 0.2





- **140**: Workpiece Hole Diameter ϕ 14 \pm 0.2
- **150**: Workpiece Hole Diameter ϕ 15 \pm 0.2
- **160**: Workpiece Hole Diameter ϕ 16 \pm 0.2
- **180**: Workpiece Hole Diameter ϕ 18 \pm 0.2
- **200**: Workpiece Hole Diameter ϕ 20 \pm 0.2





5 Self-Locking Function

- - Ν : Without Self-Locking Function
- Blank : With Self-Locking Function (Standard) * With self-locking function, the clamp is locked at OMPa. The ability of SWP varies depending on this function. Refer to the next page for further information.



Specifications

Model No.			SWP0501	SWP0501	SWP0501	SWP0501	SWP1001	SWP1001	SWP1001	SWP1001	SWP1001	
Model No.			-□-100-□	-□-110-□	-□-120-□	-□-130-□	-□-140-□	-□-150-□	-□-160-□	-□-180-□	-□-200-□	
	Hole Diameter		10 ±0.2	11 ±0.2	12 ±0.2	13 ±0.2	14 ±0.2	15 ±0.2	16 ±0.2	18 ±0.2	20 ±0.2	
Workpiece	Thickness	Min.					0.45					
mm	t	Max.	5.5	6	6.5	7	8.5		10			
Locating Repeata	ability *1	mm		-	-	0.05 (When	Combining	D and C)				
Cylinder Full Stro	ke	mm	12.1	13.8	14.3	14.8	16.3		17	7.8		
Lock Stroke		mm	5.5	6	6.5	7	8.5		10			
Cylinder Capacity	Lock Side		8.4	9.5	9.9	10.2	17.2		18.8			
cm ³	Release Sid	le	9.7	11.1	11.5	11.9	20.5		22	2.4		
5 Blank	Max. Operating	Pressure MPa		0.5								
Didilk	Min. Releasing Pressure MPa		0.2									
5 N	Operating Pr	essure MPa	0.2 ~ 0.5									
Withstanding Pre	essure	MPa	0.75									
Usable Fluid			Dry Air									
Recommended Air Blow Pressure MPa			0.1 ~ 0.2									
Operating Tempe	erature	°C					0~70					
Weight		g		3	80				700			

Notes :

%1. Locating repeatability under the same condition (no load).

1. This product locks and releases with air pressure.

2. When using with other clamps, make sure this product operates first by sequence control of a circuit.

Action Description	Features	Model No. Indication Specifications	Clamping Force Expanding Force	External Dimensions	Accessory Shim Set	Cautions	

Clamping Force • Expanding Force

					(N)			
Model No.		SWP	0501	SWP1001				
Model No.		5 Blank: With Self-Locking	5 N:Without Self-Locking	5 Blank: With Self-Locking	5 N:Without Self-Locking			
	Air Pressure 0.5 MPa	380	325	600	500	Hand • Clamp		
*2 *3	Air Pressure 0.4 MPa	315	260	500	400			
Clamping	Air Pressure 0.3 MPa	250	195	400	300	Support		
Force	Air Pressure 0 MPa	55	-	100	-			
	Calculated Value **5	Fc=650×P+55	Fc=650×P	Fc=1000×P+100	Fc=1000×P	Valve • Coupler		
	Air Pressure 0.5 MPa	1015	880	1600	1330			
×4 Evpapding	Air Pressure 0.4 MPa	840	700	1330	1060	Cautions • Othe		
Expanding	Air Pressure 0.3 MPa	670	530	1060	800			
Force	Air Pressure 0 MPa	145	-	260	-			
	Calculated Value *5	Fe=1740×P+145	Fe=1760×P	FE=2680×P+260	Fe=2660×P	Pallet Gripper		
	1			1		WVA		

Notes :

%2. Clamping force shows the pressing force against the seating surface.

The values in the table shows the calculated value when the workpiece thickness t is 0.45mm.

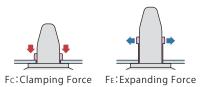
%3. When supplying air pressure to the air blow port, a clamping force may decrease due to internal pressure.

%4. Expanding force shows the force acting perpendicular to the pin's center axis.

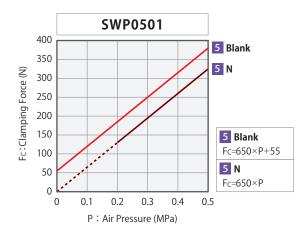
Expanding force shows the calculated value when the friction coefficient is $\,\mu$ 0.15.

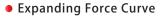
 $\%5. \ Fc: Clamping \ Force \ (N), \ Fe: Expanding \ Force \ (N), \ P: Air \ Pressure \ (MPa)$

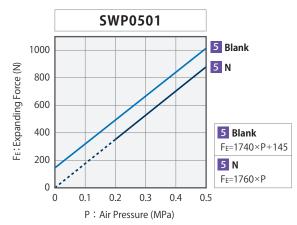
1. Depending on the material, thickness and chamfer shape of a workpiece hole, it can be deformed by clamping action, and the specifications will not be satisfied. Make sure to test clamping beforehand and adjust pressure accordingly.

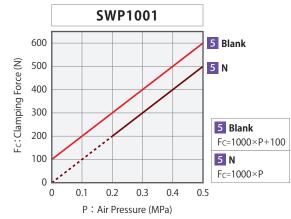


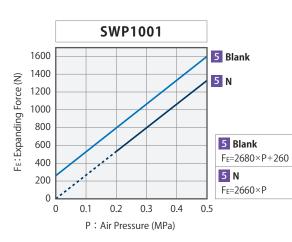
• Clamping Force Curve











High-Power Pull Stud Clamp JES FA Pneumatic Hole Clamp WKH Lifting Hole Clamp SWJ Ball Lock

cating n Clamp

SWP

Locating

Clamp

/h |

______WKA____ Pneumatic Robotic Hands

Cylinder

WPW-C WPS-C WPA WPH WPP WPQ

Auto Switch Proximity Switch JEP

High-Power Pneumatic Hole Clamp

SWE High-Power Pneumatic

Swing Clamp WHE

High-Power Pneumatic Link Clamp

WCE

Pneumatic Hole Clamp SWA

Pneumatic Swing Clamp WHA

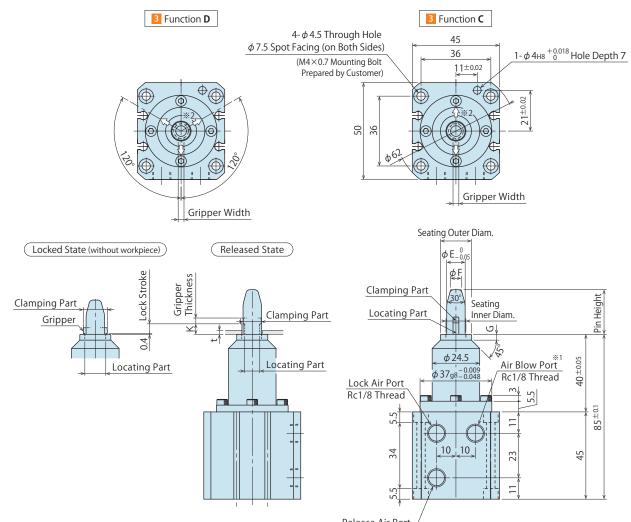
Double Piston Pneumatic Swing Clamp

WHD Pneumatic Link Clamp

WCA Air Flow Control Valve

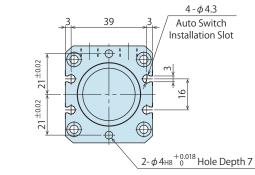
> BZW Manifold

Block WHZ-MD © External Dimensions:SWP0501 ※ This drawing shows the released state of SWP0501.



Release Air Port Rc1/8 Thread

C Exter	nal Di	men	sion Lis	t		(mm)		
			SWP0501	SWP0501	SWP0501	SWP0501		
Model No.			-□-100-□	-□-110-□	-□-120-□	-□-130-□		
	Hole Dia	ameter	10 ±0.2	11 ±0.2	12 ±0.2	13 ±0.2		
Workpiece	Thickness	Min.		0.45				
	t	Max.	5.5	6	6.5	7		
Pin Height			23	23.5	24	24.5		
Pin Outer D	iam. E		9.5	10	11	12		
Pin End Dia	m. F		5.5	6	7	8		
Clamping	At Relea	ased	9.3	9.8	10.8	11.8		
Part	At Locked	without workpiece	11.8	12.8	13.8	14.8		
Locating	At Relea	ased	7.7	8.2	9.2	10.2		
Part	At Locked	without workpiece	10.2	11.2	12.2	13.2		
Gripper	3 Functi	ion D	3	3.5	3.5	3.5		
Width	3 Functi	ion C	3.5	3.5	3.5	3.5		
Gripper Thi	ckness		3	3	3	3		
К			5.9	6.4	6.9	7.4		
Seating Inn	er Diam.		10.3	11.3	12.3	13.3		
Seating Ou	ter Diam	•	16	17	18	19		
Seating Par	t G		3	3	3	3		
Lock Stroke	2		5.5	6	6.5	7		





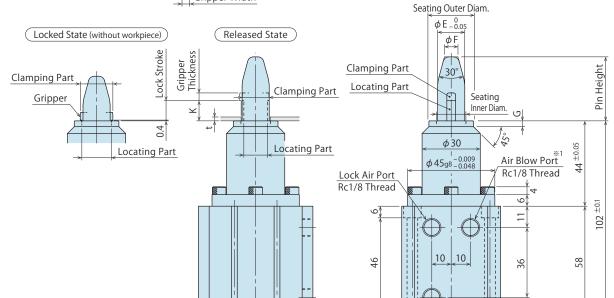
Cumulative accuracy of workpiece hole distance and clamp mounting distance must be within $\pm 0.4 \text{mm}^{\ast 3}.$

Notes :

%1. Continuously supply air pressure to the air blow port.

 ※2. The arrow □ in the drawing shows expanding direction of grippers. Since the clamping part is not a floating structure, when clamping a workpiece with two of these products, use them within ±0.4mm^{※3} of distance accuracy and with arrangement shown in the drawing on the right. With out-of specification distance accuracy, workpiece will interfere with the guide part causing damages.
 ※3. Cumulative accuracy for SWP0501-□-100-□ (Workpiece Hole Diameter φ 10) must be within ±0.15mm.

	Action Description	Features	Model No. Indication Specifications	Clamping Force Expanding Force	External Dimensions	Accessory Shim Set	Cautions	K	SMEK ony in Innovation
									1 1
(🕻 External D	imensions:	SWP1001 * 1	This drawing show	s the released state	e of SWP1001.			Locating + Clamp
		[3 Function D		Through Hole	3 Function C			Locating
					.8 Mounting Bolt	<u> </u>	> →		Hand • Clamp
				ггера	red by Customer)				Support
					-		A la		Valve • Coupler
				-)	- 40 59		±0.02		Cautions • Others
		1200		- -			56 ±		
				1	 ¢ 4н8 ^{+0.018} Hole Dep		per Width		Pallet Gripper WVA
			Gripper W	/idth	<i>ф</i> 4н8 ₀ Ноїе Dep	otn / ->+ I<			Locating



5

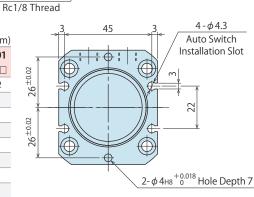
Release Air Port

C Exter	nal Di	men	sion Lis	t			(mm)		
Ma Jal Na			SWP1001	SWP1001	SWP1001	SWP1001	SWP1001		
Model No.			-□-140-□	-□-150-□	-□-160-□	-□-180-□	-□-200-□		
	Hole Dia	ameter	14 ±0.2	15 ±0.2	16 ±0.2	18 ±0.2	20 ±0.2		
Workpiece	Thickness	Min.		0.45					
	t	Max.	8.5		1	0			
Pin Height			31	33	33	33	33		
Pin Outer D	iam. E		13	14	15	17	19		
Pin End Dia	m. F		7	7	8	10	12		
Clamping	At Released		12.8	13.8	14.8	16.8	18.8		
Part	At Locked $_{\rm workpiece}^{\rm without}$		15.8	16.8	17.8	19.8	21.8		
Locating	At Released		11.2	12.2	13.2	15.2	17.2		
Part	At Locked without workpiece		14.2	15.2	16.2	18.2	20.2		
Gripper	3 Functi	ion D	4	4	4.5	5.5	5.5		
Width	3 Functi	ion C	4	4.5	4.5	5.5	5.5		
Gripper Thi	ckness		3.5	4	4	4	4		
К			8.9	10.4	10.4	10.4	10.4		
Seating Inn	Seating Inner Diam. Seating Outer Diam.			15.3	16.3	18.3	20.3		
Seating Ou				23	24	25	27		
Seating Par	t G		3	3	3	4	4		
Lock Stroke	2		8.5	10	10	10	10		

Notes :

※1. Continuously supply air pressure to the air blow port.
※2. The arrow □ in the drawing shows expanding direction of grippers.

Since the clamping part is not a floating structure, when clamping a workpiece with two of these products, use them within \pm 0.4mm^{**3} of distance accuracy and with arrangement shown in the drawing on the right. With out-of specification distance accuracy, workpiece will interfere with the guide part causing damages.



1



Cumulative accuracy of workpiece hole distance and clamp mounting distance must be within \pm 0.4mm.

Pull Stud Clamp
WPT
JES
FA Pneumatic Hole Clamp
WKH
Lifting Hole Clamp
SWJ
Ball Lock Cylinder
WKA
Pneumatic Robotic Hands
WPW-C
WPS-C
WPA
WPH
WPP
WPQ
Auto Switch Proximity Switch
JEP
High-Power Pneumatic Hole Clamp
SWE
High-Power Pneumatic Swing Clamp
WHE
High-Power Pneumatic Link Clamp
WCE
Pneumatic Hole Clamp
SWA
Pneumatic Swing Clamp
WHA
District District

Pin Clamp SWF

High-Power

Double Piston Pneumatic Swing Clamp WHD

Pneumatic Link Clamp

WCA Air Flow Control Valve

BZW Manifold Block

WHZ-MD

Accessory : Shim Set

A set of shims for level adjustment of the seating surface.

Model No. Indication



1 Body Size

050: For SWP050

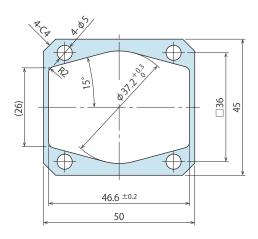
100: For SWP100

2 Design No.

1 : Revision Number

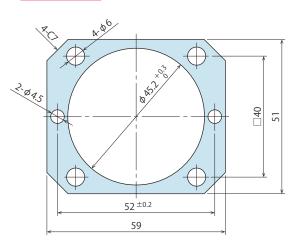
• External Dimensions

SWPZ0501-S Contents 2 of 0.5mm-thick shims, 2 of 1.0mm-thick shims





Contents | 2 of 0.5mm-thick shims, 2 of 1.0mm-thick shims

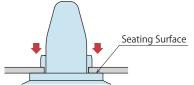


Note : 1. Material : SUS304

Action Description	Features	Model No. Indication Specifications	Clamping Force Expanding Force	External Dimensions	Accessory Shim Set	Cautions	
							Locating +
							+ Clamp Locating
							Hand • Clamp
							Support
							Valve • Coupler
							Cautions • Others
							Pallet Gripper
							Locating Pin Clamp SWP
							High-Power Pull Stud Clamp
							WPT JES
							FA Pneumatic Hole Clamp WKH
							Lifting Hole Clamp
							SWJ Ball Lock Cylinder
							WKA
							Pneumatic Robotic Hands WPW-C
							WPS-C WPA WPH
							WPP WPQ
							Auto Switch Proximity Switch JEP
							High-Power Pneumatic Hole Clamp
							SWE High-Power Pneumatic
							Swing Clamp WHE
							High-Power Pneumatic Link Clamp WCE
							Pneumatic Hole Clamp SWA
							Pneumatic Swing Clamp
							WHA Double Piston
							Pneumatic Swing Clamp WHD
							Pneumatic Link Clamp
							BZWManifold
							Block WHZ-MD

Cautions

- Notes for Design
- 1) Check Specifications
- Please use each product according to the specifications.
- This product is air double acting model which locks and releases with air pressure. In case of Self-Locking Function Option, the clamp will be locked by spring force when release air pressure is released.
- 2) Reference Surface towards Z-axis
- This product has the seating surface for workpiece and locates in Z direction.

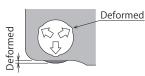


- 3) Clamping Force and Expanding Force
- Clamping force shows the pressing force against the seating surface, and expanding force shows the gripping force generated inside workpiece hole.

Make sure to test clamping and adjust pressure accordingly. Insufficient clamping force and/or expanding force leads to locking malfunctions and accuracy failure.

- 4) Wall Thickness around Workpiece Hole
- Thin wall around the workpiece hole could be deformed by locking action, and clamping force and/or locating repeatability will not fill the specification.

Please test clamping and adjust pressure accordingly before use.



 Workpiece hole size and thickness should be within the range of the specification.

When workpiece hole diameter is larger than specification.	Expansion stroke is insufficient leading to accuracy failure and locking malfunction.
When using it with insufficient clamping force.	Leads to locking malfunction.
When workpiece hole diameter is smaller than specification.	Difficult to attach/detach the workpiece leading to damage.
Workpiece is thin.	Leads to locking malfunction.
Workpiece is thick.	Leads to locking malfunction.

- 6) Installation of the Clamp
- The arrow ▷ in the drawing shows expanding direction of grippers. Since the clamping part is not a floating structure, when clamping a workpiece with two of these products, use them within ±0.4mm^{**} of distance accuracy and with arrangement shown in the drawing below. With out-of specification distance accuracy, workpiece will interfere with the guide part causing damages.

Contact us when using more than three of these products.

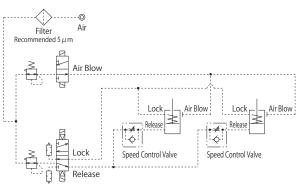


Cumulative accuracy of workpiece hole distance and clamp mounting distance must be within \pm 0.4mm^{*}.

‰ Cumulative accuracy for SWP0501-□-100-□ (Workpiece Hole Diameter ϕ 10) must be within ±0.15mm.

- 7) Refer to the drawing below for air circuit.
- Excessive locking action speed leads to possible damage to the grippers and internal parts. Adjust the flow control valve with check valve (meter-out) to set the locking action time at 0.5 ~ 1 sec.

When using two Locating Pin Clamps for locating a workpiece, adjust the action procedure so that Datum Cylinder (Function D) locks before Cut Cylinder (Function C).



8) Fall Prevention Measures

 When using for transfer, etc., please prepare fall prevention measures for safety in case of an accident such as detachment of a workpiece.

9) For Use of Auto Switch

 Magnet is built in the cylinder of this product, so the clamp action can be detected by auto switch.
 Refer to the following for the position of the built-in magnet.

			(mm)
	Model No.	l	_
	Model No.	At Released	At Locked workpiece
	SWP0501100	24.7	12.6
i i	SWP0501110	24.7	10.9
	SWP0501120	24.7	10.4
	SWP0501130	24.7	9.9
	SWP1001140	27.8	11.5
	SWP1001150	27.8	10
	SWP1001160	27.8	10
	SWP1001180	27.8	10
	SWP1001200	27.8	10
Θ			
Magne	et		

Select an auto switch depending on the environment. Recommended Auto Switch: JEP0000 (made by KOSMEK) Please use D-P3DWA (made by SMC) for an environment which generates a magnetic field disturbance.

An auto switch may be stuck out of the clamp depending on the installation position and direction.

The auto switch detection part (magnet) is interlocked with the piston movement, so it does not detect the gripper movement.

10) Continuously supply air pressure to the air blow port.

- When using under environment with cutting chips, air blow is recommended in order to prevent spatter.
 When supplying air pressure to the air blow port, clamping force may decrease due to internal pressure.
- 11) All clamps must be fully released before loading and unloading a workpiece.
- When a workpiece is loaded and unloaded during lock or release operation, it will lead to damage of clamp or fall of workpiece.

Action Description	Features	Model No. Indication	Specifications	External Dimensions	Cautions	KOSM Harmony in Inno
						Locating + Clamp
Installation N	lotes					Locating

- 1) Check the fluid to use.
- Please supply filtered clean dry air.
- Also, install the drain removing device such as aftercooler, air dryer, etc. Oil supply with a lubricator, etc. is unnecessary.
- Oil supply with a lubricator may cause loss of the initial lubricant. The operation under low pressure and low speed may be unstable. (When using secondary lubricant, please supply lubricant continuously. Otherwise, the initial grease applied from KOSMEK will be removed from the secondary lubricant.)
- 2) Preparation for Piping
- The pipeline, piping connector and fixture circuits should be cleaned and flushed thoroughly. The dust and cutting chips in the circuit can lead to fluid leakage and malfunction.
- There is no filter provided with this product to prevent contamination in the circuit.
- 3) Applying Sealing Tape
- Wrap with tape 1 to 2 times following the screwing direction.
- Pieces of the sealing tape can lead to air leakage and malfunction.
- In order to prevent contamination during the piping work, it should be carefully cleaned before working.
- 4) Mounting Locating Pin Clamp
- When mounting the product use four hexagonal socket bolts (with tensile strength of 12.9 or more) and tighten them with the torque shown in the table below. Tightening with greater torque than recommended can dent the seating surface or break the bolt.

Model No.	Tightening Bolt Size	Tightening Torque (N·m)
SWP0501	M4×0.7	3.2
SWP1001	M5×0.8	6.3

- 5) Port Position of Locating Pin Clamp
- The name of each port is marked on the flange surface. Be careful with the mounting direction of piping.
 - LOCK : Air Lock Port
 - RELEASE: Air Release Port
 - BLOW : Air Blow Port
- 6) It is recommended to use air piping with outer diameter \$\phi 6\$ (inner diameter \$\phi 4\$) or larger for air blow.
- Level Adjustment of the Seating Surface If requiring level adjustment of the seating surface, use a shim set for level adjustment (sold separately).

Notes on Handling

- 1) It should be handled by qualified personnel.
- The hydraulic machine and air compressor should be operated and maintained by qualified personnel.
- Do not operate or remove the product unless the safety protocols are ensured.
- ① The machine and equipment can only be inspected or prepared when it is confirmed that the safety devices are in place.
- ② Before the product is removed, make sure that the above-mentioned safety devices are in place. Shut off the pressure and power source, and make sure no pressure exists in the air circuits.
- ③ After stopping the product, do not remove until the temperature drops.
- ④ Make sure there is no trouble/issue in the bolts and respective parts before restarting the machine or equipment.

- 3) Do not touch a clamp while it is working.
- Otherwise, your hands may be injured due to clinching.
 In case of Self-Locking Function Option, the clamp will be locked when air pressure is cut off. Be careful not to pinch your hands.



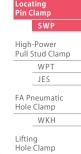
- 4) When transferring a workpiece, secure the safety of environment in case of a workpiece detachment.
- 5) Do not modify or disassemble the air cylinder.
- Built-in spring is very strong and can be dangerous.

Maintenance and Inspection

- 1) Please refer to P.715 for general maintenance and inspection.
- 2) Regularly clean the area around the gripper and seating surface.
 If it is used when the surface is contaminated with dirt, it may lead to malfunctioning, accuracy failure and air leakage.



- If there is malfunction even after cleaning the product from outside, there may be contaminants or damage within internal parts. In this case, overhaul is required. Please call us or overhaul by yourself following to the replacement procedure. Contact us for the replacement procedure for grippers. (If overhauled by unauthorized personnel, the warranty will be void even the period is still active.)
- Friction on the gripper leads to locking malfunction and lower locating repeatability.
- Replacement period differs depending on operating pressure, workpiece material, and shape of hole. When you find friction on gripper locating part, the gripper needs to be replaced. Please contact us for replacement, or replace the parts following to the replacement procedure. Regularly apply lubricant oil or grease on the gripper locating part in order to prevent friction and extend the gripper's operational life.
- Please contact us for overhaul and repair.
 Built-in spring is very strong and can be dangerous.



Hand • Clamp

Valve • Coupler

Cautions • Others

Pallet Gripper

WVA

Support

Ball I Cylin		
	WKA	
	imatic otic Hands	
	WPW-C	
	WPS-C	
	WPA	
	WPH	
	WPP	

SWJ

 ximity Switch
JEP
-Power Pneumatic e Clamp
SWE

High-Power Pneumatic

WPO

o Switcl

Swing Clamp WHE High-Power Pneumatic

Link Clamp WCE

Pneumatic Hole Clamp SWA

Pneumatic Swing Clamp WHA

Double Piston Pneumatic Swing Clamp

WHD

Pneumatic Link Clamp WCA

Air Flow Control Valve BZW

Model No. Indication



1 Design No.

: Revision Number 0

2 Switch Type

- A1 : 2-Wire Reed Auto Switch
- A2 : 2-Wire Reed Auto Switch
- A2V : 2-Wire L-Shaped Reed Auto Switch
- **B1** : 3-Wire Solid State Auto Switch
- **B2** : 3-Wire Solid State Auto Switch
- B3 : 3-Wire L-Shaped Solid State Auto Switch

Note :

- Ρ : 3-Wire Proximity Switch for Gripping Detection (Length 32mm)
- **P2** : 3-Wire Proximity Switch for Gripping Detection (Length 16mm)

3 Electric Cable Length *1

Blank : 1m L : 3m

%1. 3 Electric Cable Length is chosen only for A \square /B \square Auto Switch of 2 Switch Type. For $P\Box$: Proximity Switch for Gripping Detection, electric cable length is all 2m.

Application Table

Switch Type	2-Wire Reed Auto Switch		3-Wire Solid State Auto Switch			
Model No.	JEP0000-A1		JEP0000-B1	JEP0000-B2	JEP0000-B3	
SWJ2000		•		•	•	
SWP050		•		•	•	
SWP100		•		•	•	
WKH2000		•		•	•	
WPA0120		•		•	•	
WPA0160		•		•	•	
WPA0200		•		•	•	
WPA0250		•		•	•	
WPH0100		•		•	•	
WPH0160		•		•	•	
WPH0200	•		•			
WPS0160-C		•		•	•	
WPS0200-C		•		•	•	
WPW0500-C		•		•	•	
WPW0600-C		•		٠	•	

Switch Type	3-Wire Proximity Switch for Gripping Detection		
Model No.	JEP0000-P	JEP0000-P2	
WPP0300	•	•	
WPP0400	•	•	
WPP0500	٠	•	
WPP0600	٠		
WPP0800	٠		
WPP1000	٠		
WPP1250	٠		
WPQ0200	٠		
WPQ0250	٠	•	
WPQ0300	٠		
WPQ0400	٠		
WPQ0500	•		
WPQ0600	•		
WPQ0800	•		
WPQ1000	٠		

	Model No. Indication	Application Table	Specifica	tions	Electric uit Diagram	External Dimensions	Cautions P.411		SMEK
	€ JEP0000-A□□ (2-Wire Reed Auto Switch)								
	© Specifications							Locating	
	Model No.	IFI	P0000-A1	JEP0000-A1L	JEP0000-A	2 JEP0000-A2L	JEP0000-A2V	JEP0000-A2VL	Hand • Clamp
	Name					uto Switch			Support
	Wiring Type 2-Wire								
	Applicable Load Relay, Programmable Logic Controller (PLC)						Valve • Coupler		
Load Voltage / Load Current			Less than DC24V / 40mA					Cautions • Others	
	Load voltage / Lo	bad Current	Less than AC100V / 20mA						

Less than 3V

1ms

-10 ~ 70℃

AC1500V (There should be no abnormalities in 1 min. application.)

0

30G

None

IP67 (IEC Standard)

Red LED illuminates when turned ON

3m

1m

~			
	Electric	Circuit	Diagram

Internal Voltage Drop

Ambient Temperature

Withstand Voltage

Leakage Current

Shock Resistance

Protection Circuit

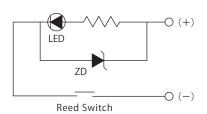
Protection Grade

Electric Cable Length

6.2

Indicator Light

Operating Time



1m

Note :

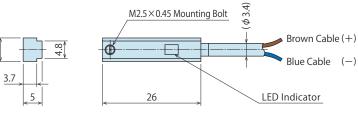
3m

1. Auto switch will instantly break due to over loading current if turning on the auto switches without connecting the load. (Refer to Notes on Wiring 4) and 5) on P.413.)

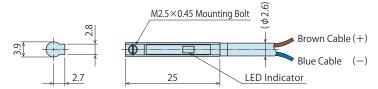
1m

3m

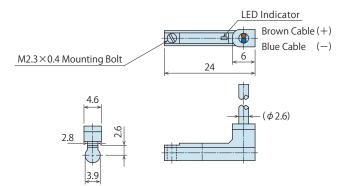
€ External Dimensions:JEP0000-A1□



External Dimensions : JEP0000-A2



External Dimensions : JEP0000-A2V



WPP WPQ Auto Switch Proximity Switch JEP High-Power Pneumatic Hole Clamp SWE

High-Power Pneumatic Swing Clamp WHE

Pallet Gripper

Locating Pin Clamp

High-Power

WVA

SWP

Pull Stud Clamp WPT

JES

FA Pneumatic Hole Clamp

Lifting Hole Clamp SWJ

Ball Lock Cylinder

Pneumatic

Robotic Hands

WPW-C

WPS-C

WPA

WPH

WKH

WKA

High-Power Pneumatic Link Clamp WCE

> Pneumatic Hole Clamp SWA

Pneumatic Swing Clamp WHA

Double Piston Pneumatic Swing Clamp

WHD

Pneumatic Link Clamp WCA

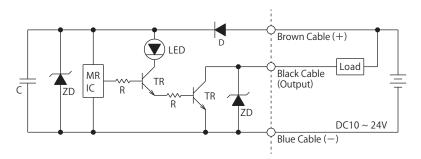
Air Flow Control Valve BZW

● JEP0000-B□□ (3-Wire Solid State Auto Switch)

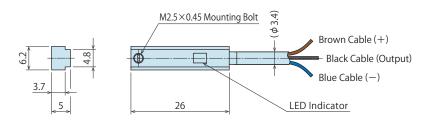
Specifications

Model No.	JEP0000-B1	JEP0000-B1L	JEP0000-B2	JEP0000-B2L
Name		Solid State	Auto Switch	
Wiring Type		3-W	/ire	
Applicable Load		Relay, Programmable	Logic Controller (PLC))
Output Type		NF	PN	
Load Voltage / Load Current		Less than DC10	~ 24V / 100mA	
Internal Voltage Drop		Less th	an 0.7V	
Operating Time	1ms			
Ambient Temperature		-10 ~	- 70℃	
Withstand Voltage	AC2000V (T	here should be no abi	normalities in 1 min. a	pplication.)
Leakage Current		()	
Shock Resistance		30)G	
Protection Grade	IP67 (IEC Standard)			
Indicator Light	Red LED illuminates when turned ON			
Electric Cable Length	1m	3m	1m	3m

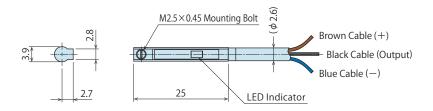
Electric Circuit Diagram



External Dimensions : JEP0000-B1



💿 External Dimensions:JEP0000-B2🗆

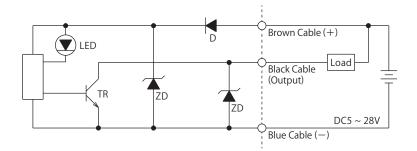


Model No. Indication	Application Table	Specifications	Electric Circuit Diagram	External Dimensions	Cautions P.411	
						Locating

Specifications

Model No.	JEP0000-B3	JEP0000-B3L	
Name	Solid State Auto Switch		
Wiring Type	3-Wire		
Applicable Load	Relay, Programmable Logic Controller (PLC)		
Output Type	NPN		
Load Voltage / Load Current	Less than DC5 ~ 28V / 0.1 ~ 40mA		
Internal Voltage Drop	Max. 0.5V		
Leakage Current	Max. 50 μ A (DC24V)		
Current Consumption	Max. 10 mA		
Response Time	Max. 1ms		
Ambient Temperature	0 ~ 60°C		
Withstand Voltage	AC1500V (There should be no abnormalities in 1 min. application.)		
Insulation Resistance	More than 100M Ω / DC500V (Between the Case and Signal Cable)		
Shock Resistance	30G		
Protection Grade	IP67(IEC Standard)		
Indicator Light	Red LED illuminates when turned ON		
Electric Cable Length	1m 3m		

C Electric Circuit Diagram

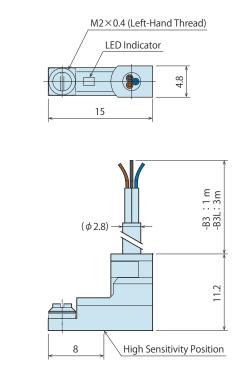


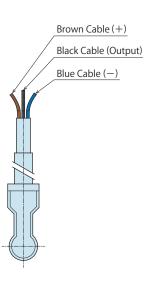
€ External Dimensions : JEP0000-B3□

2.8

3.9

5.7





Cautions • Others
Pallet Gripper
WVA
Locating Pin Clamp
SWP
High-Power Pull Stud Clamp
WPT
JES
FA Pneumatic

Clamp Locating

Hand • Clamp

Valve • Coupler

Support

Hole Clamp WKH

Lifting Hole Clamp SWJ

Ball Lock Cylinder WKA

Pneumatic Robotic Hands WPW-C WPS-C WPA WPH WPP

Auto Switch Proximity Switch JEP

WPQ

High-Power Pneumatic Hole Clamp SWE

High-Power Pneumatic Swing Clamp WHE

High-Power Pneumatic Link Clamp WCE

Pneumatic Hole Clamp SWA

Pneumatic Swing Clamp

WHA Double Piston Pneumatic Swing Clamp

WHD

Pneumatic Link Clamp WCA

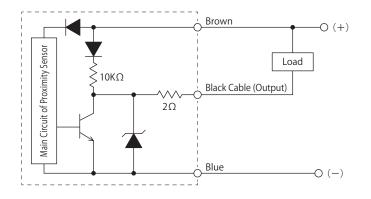
Air Flow Control Valve BZW

● JEP0000-P□ (3-Wire Proximity Switch for Gripping Detection)

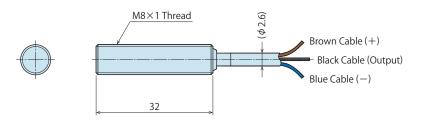
Specifications

Model No.	JEP0000-P	JEP0000-P2
Name	Proximity Switch for Gripping Detection	
Wiring Type	3-Wire	
Output Type	NPN	
Moving Distance	1.5±0.15mm	
Voltage Range	DC10 ~ 30V	
Opening / Closing Voltage	Less than 200mA	
Current Consumption	Less than 10mA	
Response Frequency	800Hz	
Ambient Temperature	−25 ~ 70°C	
Withstand Voltage	AC2000V (There should be no ab	normalities in 1 min. application.)
Protection Grade	IP67 (IEC	Standard)
Indicator Light	Red LED illuminates when turned ON	
Electric Cable Length	2m	

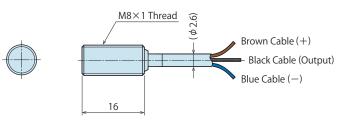
C Electric Circuit Diagram



External Dimensions : JEP0000-P



External Dimensions : JEP0000-P2



Model No. Indication	Application Table	Specifications	Electric Circuit Diagram	External Dimensions	Cautions P.411	
C MEMO						Locating + Clamp
						Locating
						Hand • Clamp
						Support
						Valve • Coupler
						Cautions • Others
						Pallet Gripper WVA
						Locating Pin Clamp SWP
						High-Power Pull Stud Clamp WPT
						JES FA Pneumatic Hole Clamp
						Hole Člamp SWJ Ball Lock
						Cylinder WKA
						Pneumatic Robotic Hands WPW-C
						WPS-C WPA WPH
						WPP WPQ
						Auto Switch Proximity Switch
						JEP High-Power Pneumatic Hole Clamp
						SWE High-Power Pneumatic Swing Clamp
						WHE High-Power Pneumatic
						Link Clamp WCE
						Pneumatic Hole Clamp SWA
						Pneumatic Swing Clamp
						WHA Double Piston Pneumatic Swing Clamp
						WHD
						Pneumatic Link Clamp WCA
						Air Flow Control Valve BZW
						Manifold

Cautions

- Notes for Design
- 1) Check the Specifications
- Please use each product according to the specifications. The product may be damaged or malfunction if used outside the range of load or specifications.
- 2) Notes on Use in the Interlock Circuit
- When the auto switch is used for an interlock signal that requires high reliability, please use a double interlock system by providing a mechanical protection function. Or by using another switch (sensor) together with the auto switch. Also, please perform periodic maintenance and confirm proper operation.
- 3) Wiring should be prepared as short as possible.
- For the reed auto switch, if the wiring length to the load is longer, inrush current to the auto switch increases and the life span will be shortened. (Remains ON)
- If the wiring length of the solid state auto switch is long, we recommend installing the ferrite core on both ends of the electric cable for noise control.
- 4) Please avoid using loads that generate surge voltage.
- If driving loads that generate surge voltage such as relay, please use the auto switch equipped with junction protective circuit or install protective box.
- If surge voltage is repeatedly applied to the auto switch even with the Zener Diode for surge protection, it may damage the contact. When directly driving loads generating surge voltage, such as solenoid valves, use the auto switch equipped with surge absorption element.
- The magnet switch is equipped with surge absorption element. However, please provide an absorption element, such as varistor, if there is large surge-generating equipment. Example: Motors or welding machines.
- 5) Leakage Current
- In case of 2-wire solid state auto switch, the leakage current that activates internal circuit of the auto switch may flow even in OFF state. If the load operating current (the controller is in OFF state) does not satisfy the specified leakage current, it may result in restoration defect (remains ON state).
 If it does not satisfy the specifications, please use 3-wire auto switch. Also, n parallel connections will multiply leakage current flowing to the load by n times.
- 6) Internal Voltage Drop of the Auto Switch
- Due to voltage drop (refer to internal voltage drop on the specifications) caused by internal resistance of LED, voltage drop of n auto switches connected in series will be multiplied by n times.

As a result, in some cases the load will not activate even if the auto switch drives properly.

- When wiring is disconnected, or when forcibly activating the auto switch for action confirmation, carefully design the circuit to avoid reverse current.
- The auto switch may malfunction or be damaged when reverse current occurs.

- 8) When multiple cylinders or robotic hands are placed close together.
- Please provide enough space when using multiple actuators such as cylinders or robotic hands equipped with auto switches. (If allowable distance of each actuator is specified please follow specified instructions.) If they are too close, auto switches may malfunction due to magnetic interference.
- 9) Secure space for maintenance and inspection
- Please secure space for maintenance and inspection of auto switches when setting actuators such as cylinders and robotic hands equipped with auto switches.





Locating + Clamp Locating

Hand · Clamp

Valve • Coupler

Cautions • Others

Pallet Gripper

Pin Clamp SWP

High-Power Pull Stud Clamp

_____WVA

Support

Notes on Operating Environment

1) Never use the product in an atmosphere with explosive gases.

- Auto switches are not designed to prevent explosion. Do not use the product in an atmosphere with explosive gases since it may cause serious explosions.
- 2) Do not use the product in an area where a magnetic field is generated.
- Auto switches may malfunction, or internal magnet actuators, such as cylinders or robotic hands, equipped with auto switches will be demagnetized.
- 3) Do not use the product in an environment where the auto switches are continuously exposed to water or coolant.
- Although IEC standard IP67 structure is satisfied, please avoid using auto switches in an environment where continuously exposed to water or coolant. This may cause insulation failure or malfunction.
- 4) Do not use the product in an environment with oil or chemicals.
- If auto switches are used in an environment with coolant or cleaning solvent, even in a short time, they may be adversely affected by improper insulation, malfunction due to swelling of potting resin and/or hardening of electric cable.
- Do not use the product in an environment subject to large temperature cycle.
- Heat cycles other than ordinary changes in temperature may adversely affect the internal structure of auto switches.
- Avoid accumulation of steel dust and close connection of magnetic materials.
- An amount of steel chips or steel dusts, such as sputters of welding accumulate around an actuator. Cylinders, robotic hand equipped with auto switches and or magnetic materials (those attracted by magnet) are gathered closely to the actuator. These can weaken internal magnet actuators.
- 7) Do not use the product in an environment with excessive impact.
- Under the condition of the excessive impact of more than 30G, the contact of the reed auto switch will malfunction and the indicator light may signal or may be disconnected.

Installation Notes

- 1) Do not drop or bump.
- Do not drop, bump or apply excessive impact on auto switches. The auto switches may be damaged and cause malfunction.
- 2) Tighten auto switches with appropriate tightening torque.
- Please follow the tightening torque below.
- Excessive tightening torque may damage the mounting screw, fitting or main body of the auto switch.

Also, mounting position may be shifted due to insufficient tightening torque.

Mounting Screw Size	Tightening Torque (N ⋅ m)
M2×0.4	0.1
M2.5×0.45	0.25
M3×0.5	0.5

- Do not carry cylinders or robotic hands by holding the electric cable of the auto switch.
- It may break the electric cable or damage the internal element.
- Do not fix auto switches with the mounting screws other than attached in main body of the auto switches.
- Using non-designated screws may damage auto switches.

5) Install the auto switches at the center of the operating area.

- Installation position of auto switches should be adjusted so that a detected object (piston etc.) stops at the center of operating range. (Installation position shown in the catalog shows the most suitable fixed position of stroke end.) Please refer to P.345 for WPS, P.355 for WPA, P.363 for WPH, P.375 for WPP and P.391 for WPQ. If the auto switches are installed at the edge of operating range (near the boundary of ON and OFF), output movement may be unstable.
- 6) Installation position of the auto switches should be adjusted by checking actual operating state.
- Depending on the installation environment, actuators such as cylinders and robotic hands may not operate properly even if they are installed to the appropriate position. Make sure to check the operating condition even when mounting them at the middle of the stroke.

WPT JES FA Pneumatic Hole Clamp WKH Lifting Hole Clamp SWJ Ball Lock Cylinder WKA Pneumatic Robotic Hands WPW-C WPS-C WPA WPH WPP WPO Auto Switch Proximity Switch

Proximity Switch JEP

High-Power Pneumatic Hole Clamp SWE High-Power Pneumatic Swing Clamp WHE

High-Power Pneumatic Link Clamp WCE

Pneumatic Hole Clamp SWA

Pneumatic Swing Clamp WHA

Double Piston Pneumatic Swing Clamp

WHD Pneumatic

Link Clamp WCA Air Flow

Control Valve BZW

Cautions

Notes on Wiring

- 1) Check the insulation of wiring.
- Insulation failure (interference with other circuit, ground fault, and insulation failure between terminals) may send excessive voltage or current to the auto switches causing damage.
- 2) Do not place wires and auto switch cables close to other cables and high voltage cables.
- Otherwise, surge voltages will be induced creating noise and leading to malfunctions.
- 3) Repeated bending stress or stretching force should be avoided on electric cables.

 Wiring with bending stress or stretching force repeatedly applied on electric cables will prematurely breakdown.
 Bending stress or stretching force applied on the connecting area of electric cables and main body of the auto switches will damage the electric cables.

Auto switches or wires should not be moving especially near the connecting areas.

 Make sure to check the load state (connection and current value) before turning on the power.

• For 2-Wire Type

Auto switches will instantly break due to over loading current if turning on the auto switches without connecting the load (Shorted Load Circuit). The above statement is also applied to the condition when the brown cable (+, output) of 2-wire type is directly connected to the (+) power terminal of a fixture and etc.

- 5) Avoid shorted load circuit.
- Reed Auto Switch

Auto switches will instantly break due to over loading current if turning on the auto switch in load short circuit condition. Solid State Auto Switch

Be aware of auto switch breakages when products with PNP output is not equipped with short-circuit protection.

- 6) Avoid wrong wiring
- Reed Auto Switch

The electric circuit has polarities. The brown cable is "+", and the blue cable is "-". The reed switch can operate even with reversed connection, but LED light will not illuminate. Also, flowing excessive current will damage LED and it will not operate properly.

Solid State Auto Switch

In case of 2-wire type, even if connected reversely, the auto switch will not be damaged due to protection circuit, but it is always ON.

If reversely connected under short circuit condition, the auto switch will be damaged.

In case of 3-wire type, even if the connections are reversed (power supply line "+" and "-"), the auto switch will be protected by a protection circuit.

However, if connecting the power supply "+" to the blue cable and "-" to the black cable, the auto switch will be damaged.

Notes on Handling

- 1) It should be operated by qualified personnel.
- Machines and devices with hydraulic and pneumatic equipment should be operated and maintained by qualified personnel.
- 2) Do not operate or remove the product unless the safety protocols are ensured.
- ① The machine and equipment can only be inspected or prepared when it is confirmed that the safety devices are in place.
- ② Before the product is removed, make sure that the abovementioned safety devices are in place. Shut off the pressure and power source, and make sure no pressure exists in the air and hydraulic circuits.
- ③ After stopping the product, do not remove until the temperature drops.
- ④ Make sure there is no trouble/issue in the bolts and respective parts before restarting the machine or equipment.
- 3) Do not disassemble or modify.
- If the equipment is taken apart or modified, the warranty will be voided even within the warranty period.



Locating + Clamp

Locating

Hand • Clamp

Support

Valve • Coupler

Cautions • Others

Pallet Gripper WVA

Locating Pin Clamp SWP

High-Power

Pull Stud Clamp WPT JES

FA Pneumatic Hole Clamp WKH

Lifting Hole Clamp

SWJ Ball Lock

Cylinder WKA

Pneumatic Robotic Hands WPW-C WPS-C WPA

> WPH WPP

> WPO

Auto Switch Proximity Switch

High-Power Pneumatic Hole Clamp

SWE

High-Power Pneumatic Swing Clamp WHE

High-Power Pneumatic Link Clamp WCE

> Pneumatic Hole Clamp

> > SWA

Pneumatic Swing Clamp WHA

Double Piston Pneumatic Swing Clamp WHD

Pneumatic

Link Clamp WCA

Air Flow Control Valve BZW

> Manifold Block WHZ-MD

Maintenance • Inspection

Conduct the below maintenances and inspections periodically in order to avoid unintended malfunctions and to ensure the safety.

- 1) Removal of the Product and Shut-off of Pressure Source
- Before removing the product, make sure that safety devices and preventive devices are in place. Shut off the pressure and power source, and make sure no pressure exists in the air and hydraulic circuits.
- Make sure there is no trouble/issue in the bolts and respective parts before restarting.
- 2) Never touch terminals while the power is on.
- It will cause electric shock, malfunction and damage to the auto switches.
- 3) Retightening of Mounting Screws
- Retighten the screws after adjusting the mounting position when the mounting position of the auto switches is shifted due to the looseness of the mounting screws.
- 4) Check if the electric cable is damaged or not.
- Damaged cables may cause insulation failure.
 Exchange the auto switch or repair the reed if there is damage on the electric cable.
- 5) Check the setting position of the detector.
- Confirm the set position is stopped at the center of the detecting range (the area that red LED illuminates).
- 6) Cleaning Auto Switches
- The auto switch should be clean. Do not use benzene, paint thinner or alcohol for cleaning. Doing so will cause scratches on the product and indications may be erased. If it is hard to remove stains from the product, wipe it out with a cloth soaked in a neutral detergent diluted with water. Wipe with a dry cloth to remove wet residue.
- 7) Product Storage
- Keep the product out of direct sunlight in a cool area where it is protected from water and humidity.
- 8) Please contact us for auto switch replacements.

• Warranty

Cautions

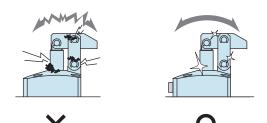
- Notes on Handling
- 1) It should be operated by qualified personnel.
- The hydraulic machine and air compressor should be operated and maintained by qualified personnel.
- 2) Do not operate or remove the product unless the safety protocols are ensured.
- ① The machine and equipment can only be inspected or prepared when it is confirmed that the safety devices are in place.
- ② Before the product is removed, make sure that the above-mentioned safety devices are in place. Shut off the pressure and power source, and make sure no pressure exists in the air and hydraulic circuits.
- ③ After stopping the product, do not remove until the temperature drops.
- ④ Make sure there is no trouble/issue in the bolts and respective parts before restarting the machine or equipment.
- Do not touch a clamp (cylinder) while it is working.
 Otherwise, your hands may be injured.



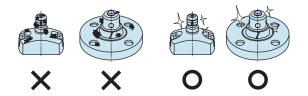
- 4) Do not disassemble or modify.
- If the equipment is taken apart or modified, the warranty will be voided even within the warranty period.

Maintenance and Inspection

- 1) Removal of the Machine and Shut-off of Pressure Source
- Before removing the product, make sure that the safety devices are in place. Shut off the pressure and power source and make sure no pressure exists in the air and hydraulic circuits.
- Make sure there is no trouble/issue in the bolts and respective parts before restarting.
- 2) Regularly clean the area around the piston rod and plunger.
- If it is used when the surface is contaminated with dirt, it may lead to packing seal damage, malfunctioning, fluid leakage.



- Regularly clean the reference surfaces (taper reference surface and seating surface) of locating products (SWT/SWQ/SWP/VRA/ VRC/VX/VXE/VXF/WVS/VWH/VWM/VWK).
- Locating products (except VRA/VRC/VX/VXE/VXF and SWR without air blow port) can remove contaminants with the cleaning function. When installing a workpiece or a pallet, make sure there are no contaminants such as thick sludge.
- Continuous use with dirt on components will lead to locating failure, fluid leakage and malfunction.



- 4) Regularly tighten pipe, mounting bolt, nut, snap ring, cylinder and others to ensure proper use.
- 5) Make sure the hydraulic fluid has not deteriorated.
- 6) Make sure there is a smooth action without an irregular noise.
- Especially when it is restarted after left unused for a long period, make sure it can be operated correctly.
- The products should be stored in the cool and dark place without direct sunshine or moisture.
- 8) Please contact us for overhaul and repair.

Warranty



Locating

Warranty

- 1) Warranty Period
- The product warranty period is 18 months from shipment from our factory or 12 months from initial use, whichever is earlier.
- 2) Warranty Scope
- If the product is damaged or malfunctions during the warranty period due to faulty design, materials or workmanship, we will replace or repair the defective part at our expense.
 Defects or failures caused by the following are not covered.
- ① If the stipulated maintenance and inspection are not carried out.
- ② Failure caused by the use of the non-confirming state at the user's discretion.
- ③ If it is used or operated in an inappropriate way by the operator.
 (Including damage caused by the misconduct of the third party.)
- 4 If the defect is caused by reasons other than our responsibility.
- (5) If repair or modifications are carried out by anyone other than Kosmek, or without our approval and confirmation, it will void warranty.
- ⑥ Other caused by natural disasters or calamities not attributable to our company.
- ⑦ Parts or replacement expenses due to parts consumption and deterioration.

(Such as rubber, plastic, seal material and some electric components.)

Damages excluding from direct result of a product defect shall be excluded from the warranty.

Clamp Locating

Hand • Clamp

Support

Valve • Coupler

Cautions • Others

Cautions Installation Notes Maintenance/ Inspection Warranty

Company Profile Company Profile

> Our Products History

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Sales Offices



Sales Offices across the World

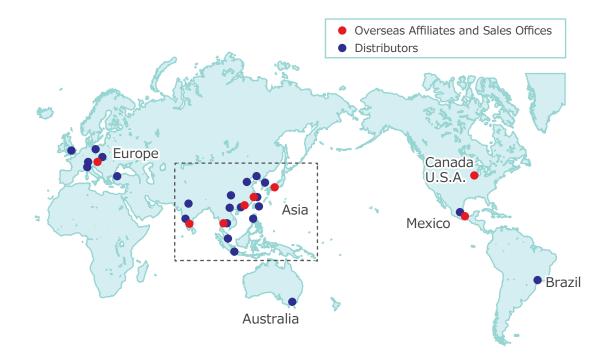
JAPAN HEAD OFFICE Overseas Sales	TEL. +81-78-991-5162 KOSMEK LTD. 1-5, 2-chome, Murotani, Nis 〒651-2241 兵庫県神戸市西区室谷2丁目1番5		
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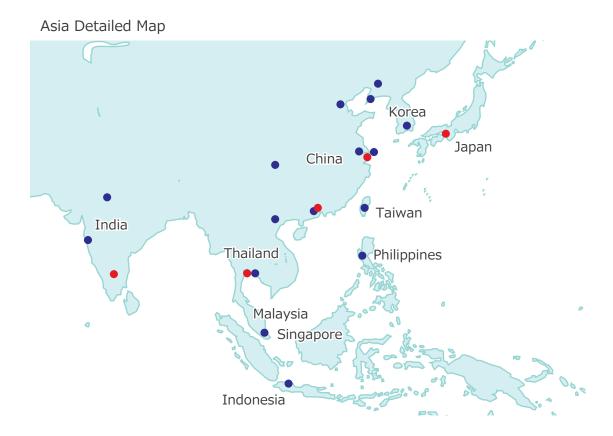
KOSMEK

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