Robotic Hand Changer

Smaller, Lighter, and Stronger!!

Model SWR





PAT.

Payload:3kg, 7kg, 12kg, 25kg, 50kg, 75kg, 120kg, 230kg Repeatability:3μm High Rigidity:Zero Backlash High Durability:More than 2 Million Cycles

High-accuracy Robotic Hand Changer enables multiple functions of robots and setup time reduction.

It enhances the productivity of automated production line.





High Accurate Repeatability

Repeatability : 3 μ m

High-accuracy locating with dual contact by the taper sleeve. It enables high accurate repeatability.





Soldering

Sealing Minimum Core Deflection

Minimum deflection of the tool end enables accuracy process.

Prevents Core Deflection and Chattering

No clearance or backlash with dual contact by the taper sleeve. It prevents core deflection and chattering due to the work load, and enhances productivity.



Deburring Screw Tightening Machining (Drilling)

Suitable for the work which generates high torque.

Features

Light • Compact

Suitable for robotic hands which are severe on weight limits. Light Weight yet Large Load Capacity!!

High Durability and Rigidity

Zero backlash when connecting and the durability is 2 million cycles. Even after 2 million cycles, repeatability 3 μ m is maintained.



| Features Application Examples | Cross Section Action Description | Model No. Indication | Specifications Performance Curve | External Dimensions | External Option | Port Option Joint Option | Exclusive Cases | Cautions | |
|----------------------------------|-------------------------------------|-------------------------|-------------------------------------|------------------------|--------------------|-----------------------------|--------------------|----------|--|
| | | | | - | | | | | |

Repeatability is 3μ m.

Internal Spring



Movable Taper Sleeve



Self-Locking prevents tools from falling.

Even when pressure is at zero, self-locking function prevents tools from falling.

% Usually it should be connected with spring force and air pressure.

High Accuracy Repeatability 0.003mm

Dual contact with movable taper sleeve enables high accuracy locating.

Only slight fluctuation at the end of tool allowing for precise operation.

Hand • Clamp

Locating

Clamp Locating

ИЕК

Support

Valve • Coupler

Cautions • Others

Robotic Hand Changer SWR Payload 3kg ~ 360kg SWR0010

Payload 0.5kg ~ 1kg

Manual Robotic Hand Changer SXR

Pneumatic Location Clamp SWT

Compact Pneumatic Location Clamp



Lift up (Detaching) function protects locating part

When connecting, lift up function prevents damage of the locating function part (seat surface and taper surface). When disconnecting, the piston rod detaches tool adaptor preventing moment stop caused by adhesion and galling. High-Power Pneumatic Pallet Clamp WVS

Seat Surface /

Taper Surface





Minimal Fluctuation even with Longer Arm

With 3μ m repeatability, it minimizes fluctuation on the long arm tip, and prevents workpiece gripping errors or interference caused by displacement when transferring.

%Reference fluctuation value when the arm length =500mm with dimension conditions of SWR0250. The result may differ depending on dimensions of a changer. Excluding displacement caused by load.

A Variety of Electrode/Air Joint Options

We offer a wide variety of options to meet your needs.



Cross Section

High Accuracy / High Rigidity / Long Operational Life



Supply air to the release side. The piston rod is pushed down with thrust force caused by release air. At this time the steel balls are free to move (set inside). When the master cylinder is lowered and stopped at the amount of lift ~+0.5mm, it is in setting state. At this time there is a moderate gap at taper reference surface and seating surface. It prevents locating mechanism part from damage. When detached, the piston pushes out A part to prevent moment stop caused by fixation or galling.

%1. Refer to the caution "Most Suitable Gap b/w Master Cylinder and Tool Adapter Just Before Connection (When Setting)" on P.79. Stop the release air pressure and supply air to the lock port. The piston rod will be pulled up with piston thrust and an internal spring, and the tool adapter will be pulled to the seating surface by the steel balls. When the tool adapter is pulled, the taper reference surface and phasing taper sleeve are centered in a reference axis (body), and locating is completed.



Electrode Option

When the master cylinder and tool adapter are connected, the electrode (option) is in the connected state. At this time, it is able to transmit electrical signal and supply electricity between the robot and tool.



Model No. Indication







Tool Adapter (Tool Side)



Payload 120kg ~ 230kg (360kg)



Payload 0.5 ~ 1kg

SWR0010-T-

Refer to P.83 for further information.

| atures Ition Examples | Cross Section Action Description | Model No. Indication | Specifications Performance Curve | External Dimensions | External Options | Port Joint Sp | Optior ecification | is Ex | clusiv Cases | e | Cautio | ons | | KOSMEK Harmony in Innovation |
|--------------------------|-------------------------------------|---------------------------------|-------------------------------------|------------------------|---------------------|------------------|-----------------------|-------|-----------------|------------|--------|-------|-------|----------------------------------|
| | | | | | | | | | | | | | | Locating |
| | | | | | | | | | | | | | | Locating |
| Payloa | d % Payloa | d at 0.5MPa | | | | | | | | | | | | Hand • Clamp |
| 003 | : 3 kg | | Refer to P.8 | 3 for 001 : 0 | .5 ~ 1 kg Payl | oad m | odel. | | | | | | | Common de |
| 007 | : 7 kg | | | | | | | | | | | | | Support |
| 012 | : 12 kg | | | | | | | | | | | | | Valve • Coupler |
| 025 | : 25 kg | | | | | | | | | | | | | |
| 050 | : 50 kg | | | | | | | | | | | | | Cautions • Other |
| 075 | : 75 kg | | | | | | | | | | | | | |
| 120 | : 120 kg | | | | | | | | | | | | | Robotic Hand Changer |
| 230 | : 230 kg | | | | | | | | | | | | | SWR Payload 3kg ~ 360l |
| Design | No. | | | | | | | | | | | | | SWR0010 Payload 0.5kg ~ 1k |
| 0 | : Revision N | Number | | | | | | | | | | | | Manual Robotic Hand Changer |
| | | | | | | | | | | | | | | SXR |
| Port O | otion * Th | e port option | is applicable t | o the master o | cylinder only. | | | | | | | | | Pneumatic Location Clamp |
| Blank | : No Port | | | | | | | • = | Availa | ble Op | tion | | | SWT |
| _ | (Only Blank o | can be chosen f | or SWR0030.) | | | 3ka | 7ka | 12ka | 25ka | 50ka | 75ka | 120ka | 230ka | Compact Pneumatic |
| F | : Standard | (with Seat Cl | heck Port) | | 3 Port Option | SWR | SWR | SWR | SWR | SWR | SWR | SWR | SWR | SWQ |
| A | : With Air B | low Port | | | Symbol | 0030 | 0070 | 0120 | 0250 | 0500 | 0750 | 1200 | 2300 | High-Power Pneumati |
| A۲ | : With Air B (Only AF opt | IOW Port + S ion can be chos | eat Check Poi en for SWR1200/S | rt SWR2300.) | Blank | • | | | | | | | | Pallet Clamp |
| | (2) | | | | F | | • | • | • | • | • | | | VV V S |
| | | | | _ | Α | | • | • | • | • | • | | | |
| | | | | | AF | | | | | | | • | | |
| F: | Standard (wit | h Seat Chec | k Port) <u>Ma</u> | aster Cylinder | A | A | : With | Air B | low P | ort Air | r Blow | Port | | |

Action confirmation can be conducted by detecting differential pressure with the air catch sensor. % Refer to P.67 for further information. Locating mechanism part can be cleaned with the air blow.

*Refer to P.67 for further information.

4 External Option Symbols (Electrode/Air Joint)

Refer to P.23 ~ P.24 for model number symbols.



Tool Adapter

5 Joint Option (Air Port Part) * Refer to P.68 for detail of the joint option.

| Blank | : No | Check | Valve | (Standard) |
|-------|------|-------|-------|------------|
|-------|------|-------|-------|------------|

- **S** : With Check Valve
- ※ Option Symbol of Tool Adapter Side : Specify with "-S" only when selecting SWR1200 / SWR2300 with check valve. Since the tool adapter of SWR0070 / SWR0750 is shared, the symbol is "Blank" regardless of the use of check valve.

| | | | =Available Option | | | | | | | |
|---------------------------|------------|-------------|-------------------|-------------|-------------|-------------|-------------|-------------|-------------|-------------|
| | 5 Joint Or | tion Symbol | 3kg | 7kg | 12kg | 25kg | 50kg | 75kg | 120kg | 230kg |
| | Master | Master Tool | | SWR 0070 | SWR 0120 | SWR 0250 | SWR 0500 | SWR 0750 | SWR 1200 | SWR 2300 |
| No Check Valve (Standard) | Blank | Blank Blank | | | | | | | ٠ | |
| With Chock Valvo | S | Blank | | | | ٠ | | | | |
| | S | S | | | | | | | ٠ | |



4 External Option Symbols (Electrode/Air Joint)^{***}

• Electrode

| • EI | • Electrode | | | | | | | | | | =Available Option | | | | | | |
|------------------------|-----------------------|--|--|--------------------------|---------------------|-------------------------------------|--------------------|--------------------|---------------------|---------------------|---------------------|---------------------|----------------------|----------------------|--|--|--|
| Rated Voltage | Rated Current | External Options (Detail Pa | ge) | Number | of Poles | Option Symbol | 3kg SWR 0030 | 7kg SWR 0070 | 12kg SWR 0120 | 25kg SWR 0250 | 50kg SWR 0500 | 75kg SWR 0750 | 120kg SWR 1200 | 230kg SWR 2300 | | | |
| - | - | Standard:No External Atta | achment | | _ | Blank | • | • | • | • | • | • | • | • | | | |
| | *2 2A/1A | Resin Connector P.37 | 0 | 16 Poles | | J | • | • | • | • | • | • | • | • | | | |
| | | Solder Terminal | 1 | 15 Poles 30 Poles | | B | • | • | • | • | • | | • | | | | |
| | | P.41 | 2 | (2 Sets of 15 | Poles) | • B2 | | | | ו | ו | ~ | ~ | | | | |
| | | | | 15 Poles | | C01 | | | | | | | | | | | |
| | | Solder Terminal with Cable | | 20 Delec | Cable 1m | | • | | | • | | | | | | | |
| DC24V | | P.43 | | (2 Sets of | Cable 111 | • C012 | | | | | | | | | | | |
| | 3A **2 | Simple Waterproof Electrode | | 151 0(03) | Cable 1m | C022 | | | | | | | | | | | |
| | | Only when connected : IP54 | | 16 Poles | Cable 111 | | | | | | | | | | | | |
| | | P.47 | | | | 002 | | | | | | | | | | | |
| | | D-sub Connector | | 15 Poles | | D | | | | | | | • | • | | | |
| | | P.51 Circular Connector | | | | | | | | | | | | | | | |
| | | (Connector Based on JIS C 5432) | | 15 Poles | | G | | | | | | | • | • | | | |
| | | P.52 | | 4 Polos | | K | | | | | | | ×3 | | | | |
| | | | | 4 Polos | | • JK / | | | | • | | | **3 | | | | |
| | | Compact Electric Power Transmission Option | | 4 Polos | | BK BK | | | | | | | **3 | | | | |
| | 5A %2 | P.53 | | 4 Polos L FL | | • C01K | | | | | | | *3 | | | | |
| AC200V | | | | | ectrode CO 7 | | | | | | | | *3 | | | | |
| DC200V | | Power Transmission Option (Connector Based on MIL-DTL-5015) P.57L | | 8 Poles | | E | | | | • | • | • | • | • | | | |
| | 13A **2 | High Current Transmission Option (Connector Based on MIL-DTL-5015) P.57R | | 10 Poles | | Н | | | | • | • | • | • | • | | | |
| for Power AC/DC240V | for Power 20A | Servo Electrode | 🍋 🍝 | 6 Poles for | r Power Supply | Cable 1m F01 | | | | | | | | | | | |
| for Signal DC24V | for Signal 3A | P.59 | | 1 Pole Fun | ctional Ground | Cable 5m F05 | | | | • | | | • | • | | | |
| Nonc | ontact W | /aterproof Electrode | | Number of | NPN | W | • | | | | | | ₩3 | • | | | |
| P.59 | Compact | Model | | Signals : 4 | PNP | WX ^{**4} | • | • | • | • | • | • | ₩3 | • | | | |
| Nonc | ontact W | /aterproof Flectrode | | | NPN | Cable 2m *Tool Adapter Side : 1m | | | | • | • | • | • | | | | |
| IP67 | ontact w | | | Number of Signals: 12 | | Cable 5m V5 | | | | | | | | | | | |
| P.61 | | | | | PNP | Cable 5m VX5 ^{*5} | | | | • | | | • | | | | |
| Grou Rateo P.62 | nd Elect d Capacit | rode y 500A (Activity Ratio 50%) | 5 | 1 Pole | | т | | | | | • | • | • | • | | | |
| Ether | rnet Elec | trode | | 4 Poles | | L | | | | • | • | • | • | • | | | |
| P.63 | | | All the second s | | | | | | | | | | | | | | |

% Refer to P.24 "General Cautions for Selecting External Options".

| Features Application Examples | Cross Section Action Description | Model No. Indication | Specifications Performance Curve | External Dimensions | External Options | Port Options Joint Specifications | Exclusive Cases | Cautions | |
|----------------------------------|-------------------------------------|-------------------------|-------------------------------------|------------------------|---------------------|--------------------------------------|--------------------|----------|--|
| | | | | | | | | | |
| | | | | | | | | | |

| | | | | | | | | | | | | Clamp |
|-----------------------------------|--|-----------------------|---------------------|-------------|-------------|-------------|-------------|-------------|-------------|-------------|-------------|------------------------------|
| • Air la | oint | | | | | | | | | | | Locating |
| | JIII | | | | | | =Ava | ilable | Opti | on | | |
| Number of Doute | | Additional | Ontion | 3kg | 7kg | 12kg | 25kg | 50kg | 75kg | 120kg | 230kg | Hand • Clamp |
| (Min. Passage Area) | External Options (Detail Page) | Electrodes | ⁴ Symbol | SWR 0030 | SWR 0070 | SWR 0120 | SWR 0250 | SWR 0500 | SWR 0750 | SWR 1200 | SWR 2300 | Support |
| | Air Joint (Able to extend electrodes $I/B/C$) | None (Air Joint Only) | R | | | | | | | *3 | *3 | Valve • Counter |
| 3 Ports | | Electrode J | • JR • JR2 | | | | | | | *3 | *3 | varve Coupler |
| (Equal to $\phi 6 \times 1$ port) | | Electrode B | • BR • BR2 | | | | % | % | % | *3 | *3 | Cautions • Other |
| Equal to $\phi 2 \times 2$ port | - Contraction of the contraction | Electrode C01 | CO1R CO1R2 | | | | % | % | % | *3 | *3 | Robotic |
| | P 64 | Electrode C02 | CO2R CO2R2 | | | | | | | *3 | *3 | Hand Changer |
| | Air Joint (Able to extend electrodes I/B/C) | None (Air Joint Only) | P | | • | • | • | • | • | *3 | *3 | SWR Payload 3kg ~ 360k |
| | | Electrode J | • JP | | | | % | % | % | *3 | *3 | SWR0010 Payload |
| 4 Ports (Equal to $\phi = 1.6$) | | Electrode B | • BP • BP2 | | | | | | | *3 | *3 | 0.5kg ~ 1kg |
| (2934) 10 \$ 110) | A DE . MAR | Electrode C01 | • C01P • C01P2 | | | | % | % | % | *3 | *3 | Hand Changer |
| | P.65 | Electrode C02 | CO2P CO2P2 | | | | | | | *3 | *3 | SXR |
| | Air Joint | | | | | | | | | | | Pneumatic Location Clamp |
| 2 Ports (Equal to $\phi 4$) | | None (Air Joint Only) | Q | | | | | | | *3 | *3 | SWT |
| | P.66 | | | | | | | | | | | Compact Pneumatic |

【 General Cautions for Selecting External Options 】

Difference between • and • is mounting positions of external options, because SWR0250 ~ SWR2300 have two mounting surfaces for external options. Refer to the following example of external option model number for further information.

- *1. For the combination of external options, the symbols should be specified in alphabetical order. (Ex: 'JR2' and 'E', it is 'EJR2'.)
- *2. For the electrode options, check the total current capacity and contact resistance shown in the specifications of each option.
- %3. Please contact us for the options of SWR1200/SWR2300 marked with %3.
- **. The option symbol 'WX' is only for master cylinder. The option symbol of the tool adapter is 'W' for both NPN/PNP.
- *5. The option symbol 'VX/VX5' is only for master cylinder. The option symbol of the tool adapter is 'V' for both NPN/PNP.

Option Mounting Surface and External Option Model No. Example

SWR0030 / SWR0070 / SWR0120 has Option Mounting Surface : 1 part

Example : Solder Terminal 30 Poles (2 sets of 15 poles)

(Ex.) Model : SWR0070 - MF - **BB**



SWR0250 / SWR0500 / SWR0750 / SWR1200 / SWR2300 has Option Mounting Surface : 2 parts

(Ex. 1) When selecting 'BB' for SWR0250~SWR2300, electrode 'B' is mounted on each the first and second option mounting surface.
(Ex. 2) When selecting 'B2' for SWR0250~SWR2300, electrode 'B' is extended to electrode 'B' on the first option mounting surface.
(Ex. 3) When selecting 'BK2' and 'B', the symbols should be specified in alphabetical order as '<u>B BK2</u>'. The arrangement is as follows : Electrode 'B' on the first option mounting surface, electrode 'BK2' ('B' extended to 'K') on the second option mounting surface.



%6. Check the external dimensions on P.34 for option mounting surface of SWR2300.

.ocating

SWQ

High-Power Pneumation Pallet Clamp

WVS

Specifications

| Model No. | | | SWR0030 | SWRY0010 | SWR0070 | SWR0120 | SWR0250 | SWR0500 | SWR0750 | SWR1200 | SWR2300 |
|--------------------------|-----------------------|-----------------|-------------------------|--------------------------|------------------------------|------------------------------|------------------------------|------------------------------|------------------------------|-------------------------------|-------------------------------|
| | at 0.5MPa | kg | 3 | 3 | 7 | 12 | 25 | 50 | 75 | 120 | 230 |
| Payload *1 | at 0.7MPa | kg | - | - | - | - | - | - | - | - | 360 |
| | at 1MPa | kg | 6 | 5 | 12 | 20 | 45 | 90 | 140 | 200 | - |
| Repeatabil | ity | mm | | | | | 0.003 | | | | |
| Lift Stroke (| Detaching Stroke) | mm | 0. | .8 | 0.8 | 0.8 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 |
| Cylinder | Lock | cm ³ | 0.6 | 54 | 1.50 | 2.38 | 6.08 | 14.38 | 22.98 | 38.44 | 89.54 |
| Capacity | Release | cm ³ | 0.7 | 72 | 1.72 | 2.69 | 6.68 | 15.39 | 25.45 | 42.76 | 100.73 |
| 0 | Max. Pressure | MPa | 1. | .0 | | | 1 | .0 | | | 0.7 |
| Operating | Min. Pressure | MPa | 0. | .4 | | | 0. | 35 | | | 0.35 |
| Air Pressure | Withstanding Pressure | MPa | 1. | .5 | | | 1 | .5 | | | 1.05 |
| Holding Fo | rce | | Refer to P.26 | Refer to P.70 | | | Refer 1 | to P.26 | | | Refer to P.26 |
| Lifting Ford | e (Detaching Forc | e) | Refer to P.26 | Refer to P.70 | | | Refer 1 | to P.26 | | | Refer to P.26 |
| AU 11 ×1 | Bending (at 0.5MPa) | N∙m | 5 | 5 | 14 | 27 | 74 | 194 | 380 | 725 | 1800 |
| Allowable *** | Bending (at 1.0MPa) | N∙m | (1 | 0) | (25) | (45) | (135) | (350) | (700) | (1400) | - |
| Static Moment | Twisting | N∙m | 15 | 12 | 23 | 45 | 100 | 175 | 300 | 700 | 1400 |
| M I I #2 | Bending (at 0.5MPa) | N∙m | 1 | 0 | 28 | 54 | 148 | 388 | 760 | 1450 | 3600 |
| | Bending (at 1.0MPa) | N∙m | (2 | 0) | (50) | (90) | (270) | (700) | (1400) | (2800) | - |
| Moment | Twisting | N∙m | 30 | 24 | 46 | 90 | 200 | 350 | 600 | 1400 | 2800 |
| Operating | Temperature | °C | | | | | 0~70 | | | | |
| Usable Flui | d | | | | | | Dry Air | | | | |
| Woight ^{%3} | Master Cylinder | g | 70 | 85 | 180 | 250 | 500 | 1000 | 1650 | 3800 | 7100 |
| weight | Tool Adapter | g | 45 | 60 | 120 | 160 | 300 | 750 | 1100 | 2600 | 4800 |
| Number of | Thread Size \times | | M3×0.5×2 Ports | M3×0.5×6 Ports | M5×0.8×6 Ports | M5×0.8×6 Ports | M5×0.8×6 Ports | M5×0.8×2 Ports | | | |
| Air Ports ^{**4} | Number of Ports | | *5 | | | | | Rc1/8×4 Ports | Rc1/8×9 Ports | Rc1/4×9 Ports | Rc3/8×10 Ports |
| Air Port | 5 Joint Option | | 1.1 (Equal to (61.2) | 1.1 (Equal to (6.1.2) | 2.0 | 2.0 | 2.0 | 7.1 | 7.1 | 63.6 | 63.6 |
| Minimum | ыапк | mm² | | (Equal to \$\$ 1.2) | (εqual to ψ 1.6) | (Εqual to φ 1.6) | (Εqual to ψ 1.6) | (Εqual to ψ 3.0) | (Equal to ψ 5.0) | (Equal to \$9.0) | (Ľquai ιΟ ψ 9.0) |
| Passage Area | 5 Joint Option S | mm ² | _ | _ | 1.7 (Equal to ϕ 1.5) | 1.7 (Equal to ϕ 1.5) | 1.7 (Equal to ϕ 1.5) | 3.4 (Equal to ϕ 2.1) | 3.4 (Equal to ϕ 2.1) | 13.0 (Equal to ϕ 4.1) | 13.0 (Equal to ϕ 4.1) |
| Electrode C | Option | | | | | Refer t | o P.37 ~ P.6 | 56 | | | |
| Allowable | Offset while Teach | ina | | | | Ref | er to P 78 | | | | |

Notes :

%1. Please consider both the payload and allowable static moment when selecting the product.

*2. The product must be used within Allowable Static Moment (*1). Using within Max. Load Moment will not fill the specifications.

%3. Weight of the body without external options.

%4. Refer to P.20 for air port use.

**5. We offer SWRY0010 with 6 air ports (see P.69) for those who require additional number of air ports for SWR0030.





* Refer to P.17 for further explanation.

|--|

Holding Force Curve

| Holding Force | | | SWR0030 SWRY0010 | SWR0070 | SWR0120 | SWR0250 | SWR0500 | SWR0750 | SWR1200 | SWR2300 | Locating |
|---------------|-----------------------|----|------------------|---------|---------|---------|---------|---------|---------|---------|-----------------|
| | At OMPa ^{%6} | kN | 0.12 | 0.15 | 0.32 | 0.57 | 0.95 | 1.29 | 1.97 | 2.78 | Hand & Clamp |
| | At 0.35MPa | kΝ | _ | 0.68 | 1.14 | 2.31 | 4.44 | 6.87 | 9.84 | 19.56 | naliu • Clallip |
| Holding Force | At 0.4MPa | kΝ | 0.45 | 0.75 | 1.26 | 2.56 | 4.94 | 7.67 | 11.00 | 21.96 | Support |
| | At 0.5MPa | KN | 0.50 | 0.90 | 1.50 | 3.05 | 5.94 | 9.26 | 13.33 | 27.72 | |
| | At 1MPa | kN | 0.90 | 1.64 | 2.67 | 5.53 | 10.92 | 17.24 | 24.95 | _ | Valve • Coupler |

Note :

%6. It indicates holding force when air pressure is at OMPa after connecting and may not fill the specification.



Note :

1. Tables and graphs shown are the relationship between supply air pressure (MPa) and holding force (kN).

C Lifting Force (Detaching Force)

| Model No. | | | SWR0030 | SWRY0010 | SWR0070 | SWR0120 | SWR0250 | SWR0500 | SWR0750 | SWR1200 | SWR2300 |
|-------------------|------------|----|---------|-----------|---------|---------|---------|---------|---------|---------|---------|
| Lifting Force | At 0.35MPa | kN | (0.03:a | t 0.4MPa) | 0.11 | 0.16 | 0.38 | 0.77 | 1.45 | 2.22 | 4.53 |
| Lifting Force | At 0.5MPa | kΝ | 0.08 | | 0.20 | 0.30 | 0.68 | 1.34 | 2.41 | 3.62 | 7.18 |
| (Detaching Force) | At 1MPa | kΝ | 0.23 | | 0.51 | 0.78 | 1.66 | 3.27 | 5.59 | 8.28 | - |



Note :

1. Tables and graphs shown are the relationship between supply air pressure (MPa) and lifting force (kN).

Locating

Cautions • Others

+ Clamp

External Dimensions (SWR0030)

% This drawing shows the released state of SWR0030. Refer to P.71 for External Dimensions of SWRY0010.





External Dimensions (SWR0120)

% This drawing shows the released state of SWR0120.



Tool Adapter SWR0120-T



Tool Adapter SWR0250-T

External Dimensions (SWR0500)

% This drawing shows the released state of SWR0500.



Tool Adapter SWR0500-T



External Dimensions (SWR1200)

% This drawing shows the released state of SWR1200.



Tool Adapter (Standard / with Check Valve) SWR1200-T-□ / SWR1200-T-□-S

(Make sure to select the same option as the master cylinder.)



Tool Adapter (Standard / with Check Valve) SWR2300-T-□ / SWR2300-T-□-S % The different part between the standard and check valve option.

The Joint Structure

(Make sure to select the same option as the master cylinder.)

💿 Option Mounting Dimensions (SWR0030 ~ SWR0120)

Electrodes and fixtures provided by other than Kosmek, can be mounted with option mounting bolts. This drawing shows the connected state of the master side and tool side.



 \approx 1. Recommended width of option side is 6 $^{+0.10}_{+0.05}$.



 \approx 2. Recommended width of option side is 14 $^{+0.15}_{+0.05}$.



 \approx 2. Recommended width of option side is 14 $^{+0.15}_{+0.05}$.



DC 24V

2A: Pin 1,3,5,7,9,11,13,15

1A: Pin 2,4,6,8,10,12,14,16

DF11-16DP-2DS(52) (HIROSE ELECTRIC)

 $30m\Omega$ or less

10A

16

Gold Coating Electrode 13q Bracket for SWR0030-M : 10g

Bracket for SWR1200-M: 18g

Electrode 11g Bracket for SWR0030-T : 8g

Bracket for SWR1200-T:16g

SWZ0J0-CL (Refer to P.39)

Master Cylinder Side

External Option : Resin Connector





Specifications

The cable side (connecter, contact, cable) is not included.

Please prepare the cable with applicable connector (SWZ0J0-CL) on P.39, or design them yourself referring to the following list.

| Cable Side Connector Model No. | Cable Side Contact Model No. | Recommended Wire Size | Protect Manual Crimping Tool | ive Tool Contact Removal Tool | Maker |
|-----------------------------------|---------------------------------|--------------------------|---------------------------------|----------------------------------|-----------------|
| DE11 1(DC 2C | DF11-22SCA | AWG22 | DF11-TA22HC | | |
| DFTT-T6DS-2C | DF11-2428SCA | AWG24 ~ 28 | DF11-TA2428HC | DE-C-DO(R) | HIROSE ELECTRIC |
| | | | 1 | | 1 |

Notes: 1. Refer to HIROSE ELECTRIC catalogs for the detailed specifications and the rated current based on wire size. 2. The model number of connector required for the master cylinder and the tool adapter is the same.

External Dimensions (SWR0070/SWR0120/SWR0250/SWR0500/SWR0750/SWR2300)



Notes :

1. Inform us with the model number shown above if you require an electrode only. (SWRZ0J0-D: one set is one electrode.)

2. Prepare additional mounting bolts by customer when extending another electrode. See P.35 ~ P.36 for mounting thread depth.

| Features Application Examples | Cross Section Action Description | Model No. Indication | Specifications Performance Curve | External Dimensions | External Options | Port Options Joint Specifications | Exclusive Cases | Cautions | |
|----------------------------------|-------------------------------------|-------------------------|-------------------------------------|------------------------|---------------------|--------------------------------------|--------------------|----------|--|
| | 1 | | | | | | | | |

• External Dimensions (SWR0030)



| | Tool Adapter | Side |
|---------------------|--|--------------------------|
| SWR0030-T -J | ■ SWRZ0S0-T is i | mounted for SWR0030-T-J. |
| | 10 8 10 8 10 8 10 10 8 10 10 10 10 10 10 10 10 10 10 | |

Locating

Locating

Support

Hand · Clamp

Valve • Coupler

Cautions • Others

Robotic Hand Changer

Manual Robotic

SXR

Location Clamp

SWT

Compact Pneumatic

SWQ

High-Power Pneumati Pallet Clamp

WVS

Location Clamp

Hand Changer

Pneumatic

SWR Payload 3kg ~ 360

SWR0010 Payload 0.5kg ~ 1kg

Clamp

| | | | | Quantity |
|-----------|---|---------------------|---------------------------------|------------|
| Model No. | No. | Name | | J:16 poles |
| | 8 | Electrode (Tool | 1 | |
| SWRZ0J0-T | 9 | Spacer | | 1 |
| | 3 | Parallel Pin | ϕ 1.5×4 B Type (SUS) | 2 |
| | (a) Electrode (Tool Side) (b) Spacer (c) Parallel Pin (c) Hexagon Socket Bolt (c) Bracket (Tool Side) (c) Bracket (Tool Side) (c) Parallel Pin (c) Parallel Pin | 2 | | |
| | 10 | Bracket (Tool Side | 2) | 1 |
| SWRZ0S0-T | 6 | Parallel Pin | ϕ 2 $	imes$ 6 B Type (SUS) | 1 |
| | \bigcirc | Hexagon Socket Bolt | M3×0.5×6 (SUS) | 1 |

Note :

1. Inform us with the model number shown above if you require an electrode only. (SWRZ0J0-D: one set is one electrode.)





| | | | | Quantity |
|---------------|------|--|----------|------------|
| Model No. | No. | Name | | J:16 poles |
| SWRZ0J0-T | 8 | Electrode (Tool Side) | 1 | |
| | 9 | Spacer | 1 | |
| | 3 | Parallel Pin ϕ 1.5×4 B Ty | pe (SUS) | 2 |
| | 4 | Hexagon Socket Bolt M3×0.5×2 | 0 (SUS) | 2 |
| SWRZOBO-120TB | (14) | Bracket (Tool Side) | 1 | |
| | (12) | Parallel Pin ϕ 3×6 B Typ | e (SUS) | 2 |
| | (13) | Hexagon Socket Bolt M4 \times 0.7 \times 1 | 0 (SUS) | 2 |
| | | | | |

Notes :

(13)

Hexagon Socket Bolt M4×0.7×10 (SUS)

1. Inform us with the model number shown above if you require an electrode only. (SWRZ0J0-[] : one set is one electrode.)

2. Prepare additional mounting bolts by customer when extending another electrode. See P.36 for mounting thread depth.

1

© External Option : Cable with Connector for Resin Connector





Note: Wire/Cable Procedure and Wiring

Make sure to fix the wire and cable so that they are not pulled while a robot is moving or turning around.
 External force should not be applied on the connector part since it leads to breaking of wire, detaching of connector and contact failure.



Prevention Cover

27

Prevention Cover

27



Master Side

Tool Side

6

57

External Dimensions (SWR0070/SWR0120/SWR0250/SWR0500/SWR0750/SWR2300)

67

16.5



Note: 1. Inform us with the model number shown above if you require an electrode only. (SWRZ0B0-D: one set is one electrode.) For SWRZ0B0-M/SWRZ0B0-T, the bolt and bolt cover marked with %2 are not included.



High-Power Pneumati Pallet Clamp

WVS

• External Dimensions (SWR1200)



Note: 1. Inform us with the model number shown above if you require an electrode only. (SWRZOBO-□: one set is one electrode.) For SWRZOB0-M / SWRZOB0-120MB / SWRZOB0-T / SWRZOB0-120TB, the bolt and bolt cover marked with %2 are not included.

External Option : Solder Terminal with Cable



Specifications

| Rated Value (per contact) | 5 | DC 24V 3A | | | | | |
|------------------------------|-------------------------|---|--|--|--|--|--|
| Contact Resis | tance (Initial Value) | 100mΩ or less | | | | | |
| Total Currer | nt Capacity | 10A | | | | | |
| Number of Pol | es (per electrode) | 15 | | | | | |
| Lead Wire S | Size | Refer to P.45 and P.46 | | | | | |
| Lead Wire | -C01 | 1m | | | | | |
| Length | -C02 | 2m | | | | | |
| Wainh+ %1 | Master Cylinder Side | Electrode -C01 : 120g / -C02 : 230g Bracket for SWR0030-M : 10g Bracket for SWR1200-M : 18g | | | | | |
| weight×1 | Tool Adapter Side | Electrode -C01 : 110g / -C02 : 220g Bracket for SWR0030-T : 8g Bracket for SWR1200-T : 16g | | | | | |

%1. Weight per electrode. Bracket weight shows the weight of SWRZ0S0
, SWRZ0B0-120
B.



Please refer to P.45 and P.46 for the pin numbers, the wire colors and the cable specifications.

External Dimensions (SWR0070/SWR0120/SWR0250/SWR0500/SWR0750/SWR2300)



Notes: 1. Inform us with the model number shown above if you require an electrode only. (SWRZOCO- : one set is one electrode.) For SWRZ0C0-M / SWRZ0S0-M, the bolt and bolt cover marked with %2 are not included.

2. The connected part of the solder terminal and lead wire is isolated with a thermal contraction tube.

3. For SWRZ0C0-_01/02 the lead wire length is different from its shown in the specifications.

(SWRZ0C0-D01:Lead Wire Length 1m, SWRZ0C0-D02:Lead Wire Length 2m)



2. The connected part of the solder terminal and lead wire is isolated with a thermal contraction tube. 3. For SWRZ0C0-01/02 the lead wire length is different from its shown in the specifications.

(SWRZ0C0-01: Lead Wire Length 1m, SWRZ0C0-02: Lead Wire Length 2m)



Notes: 1. Inform us with the model number shown above if you require an electrode only. (SWRZOCO--: one set is one electrode.)

For SWRZ0C0-M / SWRZ0B0-120MB / SWRZ0C0-T / SWRZ0B0-120TB, the bolt and bolt cover marked with %2 are not included.

2. The connected part of the solder terminal and lead wire is isolated with a thermal contraction tube.

3. For SWRZ0C0-01/02 the lead wire length is different from its shown in the specifications.

(SWRZ0C0-01: Lead Wire Length 1m, SWRZ0C0-02: Lead Wire Length 2m)

High-Power Pneumat Pallet Clamp

WVS

External Option : Solder Terminal with Cable (Continued)



• Pin Numbers







| Wire Color | Blue | White | Yellow | Brown | Green | Black | Red | Gray | Violet | Orange | Blue | Brown | Yellow | Black | Green | Gray |
|------------|---------|-------|--------|---------|-------|---------|-------|---------|--------|---------|-------|---------|--------|---------|--------|---------|
| | | | | | | | | | | | | | | | | |
| | Twisted | | Twist | ed Pair | Twist | ed Pair | Twist | ed Pair | Twist | ed Pair | Twist | ed Pair | Twiste | ed Pair | Twiste | ed Pair |

© External Option : Waterproof Electrode (Simple Waterproof Option)

| External Option Symbol: | U01/U02 |
|---|--|
| Master Cylinder model SWR 0-M - U01 U02 | Tool Adapter model SWR 0-T - U01 U02 |
| | |

• Specifications

| Rated Value (per contact) | 2 | DC 24V 3A | | | | |
|------------------------------|-------------------------|--|--|--|--|--|
| Contact Resist | tance (Initial Value) | 100mΩ or less | | | | |
| Total Currer | nt Capacity | 10A | | | | |
| Number of Pole | es (per electrode) | 16 | | | | |
| Lead Wire S | Size | Refer to P.49 and P.50 | | | | |
| Lead Wire | -U01 | 1m | | | | |
| Length | -U02 | 2m | | | | |
| W/=:=b+%1 | Master Cylinder Side | Electrode -U01 : 140g / -U02 : 260g Bracket for SWR0030-M : 10g Bracket for SWR1200-M : 18g | | | | |
| weight×i | Tool Adapter Side | Electrode - U01 : 140g / - U02 : 250g Bracket for SWR0030-T : 8g Bracket for SWR1200-T : 16g | | | | |
| Protection | Grade %2 | Equivalent to IP54 | | | | |

*1. Weight per electrode. Bracket weight shows

*2. The protection grade is equivalent to IP54 at connected state (fit state) of the master cylinder and tool adapter.



Please refer to P.49 and P.50 for the pin numbers, the wire colors and the cable specifications.

• External Dimensions (SWR0070/SWR0120/SWR0250/SWR0500/SWR0750/SWR2300)



Notes: 1. Inform us with the model number shown above if you require an electrode only. (SWRZOU0: one set is one electrode.)
2. For SWRZOU001/02 the lead wire length is different from its shown in the specifications.

(SWRZ0U0-_01:Lead Wire Length 1m, SWRZ0U0-_02:Lead Wire Length 2m)

| | Features Application Examples | Cross Section Action Descriptic | Model No. Indication | Specifications Performance Curve | External Dimensions | External Options | Port C Joint Spe | Options Excl ecifications Ca | usive ses Caut | tions | K | SMEK | | | |
|---|----------------------------------|---|--------------------------------|-------------------------------------|------------------------|---------------------|---------------------|---------------------------------|------------------------------------|----------|-------------------------------------|---|--|--|--|
| | • External Dimensions (SWR0030) | | | | | | | | | | | | | | |
| | | | | Master C | ylinder Side | Tool Ad | Tool Adapter Side | | | | | | | | |
| | SWR0030-M | 1- U □ | nly for SWR0030-N | ∕I-U□, SWRZ0S0-N | A is mounted. | SWROC |)30-T -l | J 🗌 🛛 💥 Only fo | r SWR0030-T-U | , SWRZ0S | 0-T is mounted. | Hand • Clamp | | | |
| | F. J. | | | 2) | | - |) | | | <u> </u> | | Support | | | |
| C | | 59 | | 3) I | | | | | | | | | | | |
| | | m | <u> </u> | | 7 | \mathcal{O} | m t | | _ | Ŭ | Cautions • Others | | | | |
| | | | | | | | | | | | | Robotic Hand Changer | | | |
| 0 | с р . | 5 | | | | | | 0 | 27 | | _6 | Payload 3kg ~ 360kg SWR0010 Payload 0.5kg ~ 1kg | | | |
| | Model No. | No. Name | | (| Quantity | Model No. | No. | Name | | | Quantity | Manual Robotic Hand Changer | | | |
| | SWRZ0U0 | 1 Electroo | le (Master Side) | T. (0110) | 1 | SWRZOUO | 7 | Electrode (Too | l Side) | | 1 | SXR | | | |
| | -M01/M02 | Parallel Hexagon S | Pin Ø3×6B ocket Bolt M3×0.5 | 1ype (SUS) ×25 (SUS) | 2 | -T01/T02 | 3 | Hexagon Socket Bol | M3×0.5×25 (S | SUS) | 2 | Pneumatic | | | |
| | | ④ Bracket | Master Side) | | 1 | | 8 | Bracket (Tool Sid | de) | | 1 | SWT | | | |
| | SWRZ0S0-M | 5 Parallel I | Pin \$\$\phi_2\times 6B\$ | Type (SUS) | 1 | SWRZ0S0-T | 5 | Parallel Pin | n $\phi 2 \times 6$ B Type (SUS) 1 | | 1 | | | | |
| | | 6 Hexagon S | ocket Bolt M3×0.5 | 1 | · | 6 | Hexagon Socket Bol | M3×0.5×6 (SL | JS) | 1 | Compact Pneumatic Location Clamp | | | | |
| | Notes : 1. I | nform us with | the model numb | er shown above | if you require an | electrode only. (| SWRZ | | t is one electrode | e.) | | SWQ | | | |

2. For SWRZ0U0- \Box 01/02 the lead wire length is different from its shown in the specifications. (SWRZ0U0-01:Lead Wire Length 1m, SWRZ0U0-02:Lead Wire Length 2m)

High-Power Pneumatic Pallet Clamp

WVS

(10)

Master Cylinder Side Tool Adapter Side SWR1200-MAF**-U** % Only for SWR1200-MAF-U□, SWRZ0B0-120MB SWR1200-T**-U** % Only for SWR1200-T-U \Box , SWRZ0B0-120TB is mounted. is mounted. 9 (3 3 24.5 ⊕ ⊕ ⊕ ¢ ¢ ¢ ¢ ¢ ¢ 14.5 0.5 27 \sim 27 50 50 50 50 (11)(11) Model No. No. Name Quantity Electrode (Master Side) 1 1 SWRZ0U0 2 Parallel Pin ϕ 3 \times 6 B Type (SUS) 1 -M01/M02 3 Hexagon Socket Bolt M3 \times 0.5 \times 25 (SUS) 2 Bracket (Master Side) 9 1 SWRZ0B0-120MB (10) Parallel Pin ϕ 3 imes 6 B Type (SUS) 2 S١ 11 Hexagon Socket Bolt M4 \times 0.7 \times 10 (SUS) 2 Hexago (13) Parallel Pin ϕ 2 \times 8 B Type (SUS) Notes : 1. Inform us with the model number shown above if you require an electrode only. (SWRZ0U0- : one set is one electrode.) 2. For SWRZ0U0-01/02 the lead wire length is different from its shown in the specifications.

External Dimensions (SWR1200)

2

(SWRZ0U0-01:Lead Wire Length 1m, SWRZ0U0-02:Lead Wire Length 2m)

| Model No. | No. | Name | Quantity |
|---------------------|------|---|----------|
| SWRZ0U0 -T01/T02 | 0 | Electrode (Tool Side) | 1 |
| | 3 | Hexagon Socket Bolt M3 \times 0.5 \times 25 (SUS) | 2 |
| WRZ0B0-120TB | (12) | Bracket (Tool Side) | 1 |
| | 10 | Parallel Pin ϕ 3 × 6 B Type (SUS) | 2 |
| | (11) | Hexagon Socket Bolt $M4 \times 0.7 \times 10$ (SLIS) | 2 |

• External Option : Waterproof Electrode (Simple Waterproof Option)



• Pin Numbers







| i ili ivuilibei | | ~ | 5 | - | 5 | 0 | ' | 0 | | 10 | | 12 | 15 | 1.1 | 15 | 10 |
|-----------------|------|---------|--------|---------|--------|---------|-------|---------|--------|---------|-------|---------|--------|--------|--------|---------|
| Wire Color | Blue | White | Yellow | Brown | Green | Black | Red | Gray | Violet | Orange | Blue | Brown | Yellow | Black | Green | Gray |
| | L | | | | | | | | | | | | | | | |
| Тм | | ed Pair | Twist | ed Pair | Twiste | ed Pair | Twist | ed Pair | Twist | ed Pair | Twist | ed Pair | Twiste | d Pair | Twiste | -d Pair |
DC 24V

3A

10A

15

External Option : D-SUB Connector





1. Inform us with the model number shown above if you require an electrode only. (SWRZ0D0- : one set is one electrode.) Notes : 2. For SWR1200/SWR2300, SWRZ0Z0 is not required.

| Features Application Examples | Cross Section Action Description | Model No. Indication | Specifications Performance Curve | External Dimensions | External Options | Port Options Joint Specifications | Exclusive Cases | Cautions | |
|----------------------------------|-------------------------------------|-------------------------|-------------------------------------|------------------------|---------------------|--------------------------------------|--------------------|----------|------------------------|
| © Exter | nal Optio | n:Circula | ar Connect | tor (Conne | ector Base | d on JIS C | 5432) | | Locating + Clamp |

External Option Symbol: G Master Cylinder Tool Adapter



• Specifications

| Rated Value (per contact) | 2 | DC 24V 3A | | |
|------------------------------|-----------------------|------------------------------|--|--|
| Contact Resis | tance (Initial Value) | $100m\Omega$ or less | | |
| Total Currer | nt Capacity | 17A | | |
| Number of Po | oles (per electrode) | 15 | | |
| Woight %1 | Master Cylinder Side | Electrode 100g / Bracket 21g | | |
| weight ** | Tool Adapter Side | Electrode 120g / Bracket 21g | | |
| | | | | |

%1. Weight per electrode. Bracket weight shows the weight of SWRZ0E0.

Cautions • Others Robotic Hand Changer SWR Payload 3kg ~ 360 SWR0010

Locating

Support

Hand • Clamp

Valve • Coupler

Payload 0.5kg ~ 1kg Manual Robotic

and Changer SXR

neumatic ocation Clamp SWT

ompact Pneumatic ocation Clamp SWQ

igh-Power Pneumatic allet Clamp

WVS

| | | | | | | | | Ha |
|---|------|--|---|----------------|--|-------------------------------------|---|----------|
| Extern | al [| Dimensions | | | | | | Pn |
| | | Mas | ter Cylinder Side | Tool Adapt | er Side | | | Lo |
| | | SWR0250-M G SWR0500-M G SWR0750-M G | | | SWR0250-T- SWR0500-T- SWR0750-T- | G G G | | Co Lo |
| | | 515 515 1 1 | | | 52.5 | | | |
| () () () () () () () () () () () () () (| | Se Compatible v Connecto | vith SRCN2A21-16P (Pin)(JAE) r based on JIS C 5432 | | | Compatible with S Connector base | 6 5 6 5 6 6 5 6 6 5 6 6 6 6 6 6 6 6 6 6 6 6 6 | |
| SWR1200-MA SWR2300-MA | F-G | * Unlisted dimensions are the same as t | he drawing above. | SWR12 SWR23 | 200-T -G | ed dimensions are the | same as the drawing above. | |
| | | |) | | 252 | eeee 2 eee 8 3 | | |
| Model No. | No. | Name | Quantity | Model No. | No. Name | | Quantity | |
| | 1 | Electrode (Master Side) | 1 | | 8 Electrode (Too | ol Side) | 1 | |
| SWRZ0G0-M | 2 | Parallel Pin ϕ 3×8 B Type (SUS) | 2 | SWRZ0G0-T | ② Parallel Pin | ϕ 3 \times 8 B Type (SUS | 5) 2 | |
| | 3 | Hexagon Socket Bolt M4×0.7×40 (SUS) | 4 | | 3 Hexagon Socket Bo | t M4×0.7×40 (SU | 5) 4 | |
| | (4) | Bracket (Common for Master/Tool Side) | 1 | | (4) Bracket (Commo | on for Master/Tool Sid | e) 1 | |
| SWRZ0E0 | (5) | Parallel Pin ϕ 3×6 B Type (SUS) | 1 | SWRZ0E0 | 5 Parallel Pin | ϕ 3 × 6 B Type (SUS | b) 1 | |
| | 6 | Hexagon Socket Bolt $M3 \times 0.5 \times 10$ (SUS) | 2 | | Hexagon Socket Bol | t M3×0.5×10 (SU | b) <u>2</u> | |
| | (7) | Hexagon Socket Bolt $M4 \times 0.7 \times 12$ (SUS) | 2 | | UV Hexagon Socket Bo | t M4×0.7×12 (SU | 5) 2 | |

Notes: 1. Inform us with the model number shown above if you require an electrode only. (SWRZ0G0- : one set is one electrode.) 2. For SWR1200/SWR2300, SWRZ0E0 is not required.

© External Option : Compact Electric Power Transmission

External Option Symbol : K







Tool Adapter

model SWR 0-T-

Extensible Options : Resin Connector, Solder Terminal

• Specifications

| Rated Value (per contact) | 2 | AC/DC 200V 5A | |
|---------------------------------|--------------------------|---|--|
| Total Currer | nt Capacity | 12A | |
| Number of Po | les (per electrode) | 4 | |
| W/-:-b+%1 | Master Cylinder Side | Electrode 17g Bracket for SWR0030-M:10g | |
| weight®i | Tool Adapter Side | Electrode 13g Bracket for SWR0030-T : 8g | |
| Cable with Ap (Sold Separate | plicable Terminal Iy) | SWZ0K0-CL (Refer to P.55) | |

%1. Weight per electrode.

Bracket weight shows the weight of SWRZ0S0- \Box .

• Extensible Options Additional electrode can be extended to the option : K.



Κ

UT Model No. for

Extensible Optio

• Applicable Cable

The cable with applicable terminal and applicable terminal are not included. Please prepare the cable with applicable terminal (SWZ0K0-CL⁽¹⁾) on P.55 or design it yourself referring to the applicable terminal on P.55.

External Dimensions (SWR0070/SWR0120/SWR0250/SWR0500/SWR0750/SWR2300)



Notes : 1. Inform us with the model number shown above if you require an electrode only. (SWRZOK0-□ : one set is one electrode.) For SWRZOK0-M / SWRZOK0-T, the bolt and bolt cover marked with %2 are not included.

 The electrode probe on master side strokes 1.5mm (※3) when connecting with SWR. When fixing the cable, make sure there is enough space for the probe operation.

- 3. The electrode stays connected when released, because its connecting stroke requires 1.5mm which is longer than SWR lift stroke.
- %4. The optional cable and terminal are not included in the electrode. Please prepare them separately.



2. The electrode probe on master side strokes 1.5mm (\times 3) when connecting with SWR. When fixing the cable, make sure there is enough space for the probe operation.

3. The electrode stays connected when released, because its connecting stroke requires 1.5mm which is longer than SWR lift stroke.

%4. The optional cable and terminal are not included in the electrode. Please prepare them separately.

WVS

© External Option : Cable with Terminal for Compact Electric Power Transmission



** A crimp tool for crimping the applicable terminal (TA35T) is required when preparing a cable by yourself referring to this drawing.

[Notes on Wire/Cable Procedure and Wiring]

Make sure to fix the wire and cable so that they are not pulled while a robot is moving or turning around.
 External force should not be applied on the connector part since it leads to breaking of wire, detaching of connector and contact failure.
 However, the electrode probe on master side strokes 1.5mm when connecting with SWR. When fixing the cable, make sure there is enough space for the probe to stroke.



As for Compact Electric Power Transmission option, the electrode probes on both master cylinder and tool adaptor are exchangeable.
 The electrode probes will be fallen out if pushed from the cable connecting side with power stronger than a certain level.
 In case the electrode probes are pushed out after connecting the cable, make sure to push them back from the seating surface side before use.

| Features Application Examples | Cross Section Action Description | Model No. Indication | Specifications Performance Curve | External Dimensions | External Options | Port Options Joint Specifications | Exclusive Cases | Cautions | |
|----------------------------------|-------------------------------------|-------------------------|-------------------------------------|------------------------|---------------------|--------------------------------------|--------------------|----------|--|
| | | | | | | | | | |
| | | | | | | | | | |

MEMO

Locating

Hand • Clamp

Valve • Coupler

Cautions • Others

Robotic Hand Changer

Manual Robotic Hand Changer SXR

Pneumatic Location Clamp SWT Compact Pneumatic Location Clamp SWQ High-Power Pneumatic Pallet Clamp WVS

SWR Payload 3kg ~ 360kg

SWR0010 Payload 0.5kg ~ 1kg

Support

+ Clamp Locating

• External Option : Power Transmission Option (Connector Based on MIL-DTL-5015)



• Specifications

| Rated Value (per contact) | 2 | AC/DC 200V 5A | | |
|------------------------------|----------------------|------------------------------|--|--|
| Total Currer | nt Capacity | 24A | | |
| Number of Po | oles (per electrode) | 8 | | |
| Waight %1 | Master Cylinder Side | Electrode 140g / Bracket 21g | | |
| weight ** | Tool Adapter Side | Electrode 150g / Bracket 21g | | |

%1. Weight per electrode.

Bracket weight shows the weight of SWRZ0E0.





Notes: 1. Inform us with the model number shown above if you require an electrode only. (SWRZ0E0- : one set is one electrode.) 2. For SWR1200/SWR2300, SWRZ0E0 is not required.

| Features Application Examples | Cross Section Action Description | Model No. Indication | Specifications Performance Curve | External Dimensions | External Options | Port Options Joint Specifications | Exclusive Cases | Cautions | |
|----------------------------------|-------------------------------------|-------------------------|-------------------------------------|------------------------|---------------------|--------------------------------------|--------------------|----------|--|
| | | | | | | | | | |

© External Option: High Current Transmission Option (Connector Based on MIL-DTL-5015)





Specifications

| | Rated Value (per contact) | 2 | AC/DC 200V 13A | | |
|---|------------------------------|----------------------|------------------------------|--|--|
| - | Total Currer | nt Capacity | 57A | | |
| | Number of Po | oles (per electrode) | 10 | | |
| | Woight %1 | Master Cylinder Side | Electrode 280g / Bracket 24g | | |
| | weight | Tool Adapter Side | Electrode 210g / Bracket 24g | | |

%1. Weight per electrode.

Bracket weight shows the weight of SWRZ0H0.



Locating

Hand · Clamp

Valve • Coupler

Support

+ Clamp Locating

Manual Robotic Hand Changer SXR

Pneumatic Location Clamp SWT

Compact Pneumatic Location Clamp SWQ

High-Power Pneumation Pallet Clamp

WVS

External Dimensions Master Cylinder Side Tool Adapter Side SWR0250-M**-H** SWR1200-MAF-H SWR0250-T**-H** SWR1200-T**-H** SWR0500-M**-H** SWR2300-MAF-H SWR0500-T**-H** SWR2300-T**-H** SWR0750-M□-H SWR0750-T**-H** 2 ŵ <u>f</u>it £ **Φ**Φ Φ¢ ÷ ťĽ đ 0000 (2) (2) $\circ \circ \circ \circ$. chalchal Ć -55 55 0 ÌO 89.3 89.3 (6 3 8 58 58 ۲ Φ Φ (7) MS Connector MS Connector MS3102A18-1P MS3102A18-1S 40.1 40 0.5 LC 0.5 ſ 42.4

| Model No. | No. | Name | Quantity | Model No. | No. | Name | Quantity |
|-----------|------------|---|----------|------------|-------------------------|---|----------|
| | 1 | Electrode (Master Side) | 1 | | 8 Electrode (Tool Side) | | 1 |
| SWRZ0H0-M | 2 | Parallel Pin ϕ 3×8 B Type (SUS) | 2 | SWRZ0H0-T | 2 | Parallel Pin ϕ 3×8 B Type (SUS) | 1 |
| | 3 | Hexagon Socket Bolt M4 \times 0.7 \times 60 (SUS) | 4 | | 3 | Hexagon Socket Bolt M4 \times 0.7 \times 60 (SUS) | 4 |
| | 4 | Bracket (Common for Master/Tool Side) | 1 | 1 | 4 | Bracket (Common for Master/Tool Side) | 1 |
| | 5 | Parallel Pin ϕ 3 × 6 B Type (SUS) | 1 | CIMIDZOLIO | 5 | Parallel Pin ϕ 3×6 B Type (SUS) | 1 |
| SWRZUHU | 6 | Hexagon Socket Bolt M3 \times 0.5 \times 10 (SUS) | 2 | SWRZUHU | 6 | Hexagon Socket Bolt M3 \times 0.5 \times 10 (SUS) | 2 |
| | \bigcirc | Hexagon Socket Bolt M4×0.7×12 (SUS) | 2 | | 0 | Hexagon Socket Bolt M4 \times 0.7 \times 12 (SUS) | 2 |

Note: 1. Inform us with the model number shown above if you require an electrode only. (SWRZOHO- : one set is one electrode.)

External Option : Servo Electrode

Specifications

| | | Contact A | for Power Supply | |
|-------------------------|-----------------|------------|------------------------------------|---|
| External Option Symbol: | F01 / F02 / F05 | | Rated Value | AC / DC 240V |
| | | | | 20A %1 %2 |
| Master Cylinder | Tool Adapter | | Number of Poles (per electrode) | 6 |
| | | Contact B | for Signal | |
| FUD | FUD | | Rated Value | DC 24V |
| | | | (per contact) | 3A |
| • | 0. 000 | | Number of Poles | 17 (for Signal) + |
| | | | (per electrode) | 1 (for Functional Ground) |
| | | | Total Current Capacity | 10A |
| 0 | | Cable Spec | ifications | Refer to the following table. |
| | | Leed Wine | In case of - F01 | 1m |
| 0 | | Lead Wire | In case of – F02 | 2m |
| | | | In case of - F05 | 5m |
| | 50.00 | W/a:ab4%2 | Master Cylinder Side | Electrode -F01 : 750g / -F02 : 1030g -F05 : 1850g Bracket : 32g |
| | | weight*3 | Tool Adapter Side | Electrode -F01 : 710g / -F02 : 990g -F05 : 1810g Bracket : 32g |
| | | | | |

※1. Depending on the operating environment of a customer, the cable for power supply may become hot. Refer to the following conditions, and check if the maximum temperature in the operating environment combined with the temperature rise is safe before using the product.
 After 5 minutes of use with all 6 poles at 50% usage rate of 20A (5 sec. ON/ 5 sec. OFF), the cable temperature rise is Δt= about 20°C.

• After 5 minutes of use with all 6 poles at 100% usage rate of 20A and continuous current, the cable temperature rise is Δ t=about 40°C.

%2. When supplying power for more than 5 minutes, reduce the current per electrode to suppress the temperature rise.

- Example 1. Using multiple electrodes can reduce the current per pole.
- Example 2. Suppress the surface temperature of cable coating installed in areas easily touched by people to below 60°C.
- %3. Weight per electrode. Bracket weight shows the weight of SWRZ0F0.



| Contact A Cable for | HIFLON SD/2586 6C×15AWG Black NISSEI ELECTRIC Conductor Cross-Sectional Area : 2.0 mm ² (AWG15) | Weight:188g /m (Weight per meter) | | | | | | | |
|------------------------|--|-----------------------------------|------------|-------------|------------|----------|------------|------------|--|
| Power Supply | Number of Cores : 6 | Pin Number Wire Color | 1 Brown | 2 Yellow | 3 Green | 4 Red | 5 White | 6 Black | |
| | | | | | | | | | |

| Contact B | HIFLON SD-SB/20276 10P×23AWG Black (w | ith Shield) |
|---------------------|---|---|
| Cable for Signal | NISSEI ELECTRIC Conductor Cross-Sectional Area : 0.3mm ² (AWG23) Cable Rated Value Temp : 80°C Voltage : 30V | Weight:119g /m (Weight per meter) Number of Cores:20 |

| Pin Number | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 | 16 | 17 | 18(FG) | Not Used | Not Used |
|------------|-----------------|----------------|------------------|----------------|---------------|-----------------|--------|---------------|--------|--------|--------|--------|--------|---------|--------|--------|--------|---------|------------------|----------------|
| Wire Color | Yellow/ Blue | Yellow/ Red | Yellow/ Black | White/ Blue | White/ Red | White/ Black | Pink | Light Blue | Violet | Gray | Orange | Blue | Brown | Yellow | Green | Red | White | Black | Orange/ Black | Orange Blue |
| | | | | | | | | | | | | | | | | | | | | |
| | Twiste | ed Pair | Twiste | ed Pair | Twiste | ed Pair | Twiste | ed Pair | Twiste | d Pair | Twiste | d Pair | Twiste | ed Pair | Twiste | d Pair | Twiste | ed Pair | Twiste | ed Pair |

• Pin Numbers and Wire Colors



Notes: 1. Inform us with the model number shown above if you require an electrode only. (SWRZOF0-: one set is one electrode.) 2. For SWRZOF0-: 01/02/05 the lead wire length is different from its shown in the specifications.

(SWRZ0F0-_01:Lead Wire Length 1m, SWRZ0F0-_02:Lead Wire Length 2m, SWRZ0F0-_05:Lead Wire Length 5m)

© External Option : Compact Waterproof Electrode (Noncontact Waterproof Option) IP67



Notes: 1. Inform us with the model number shown above if you require an electrode only. (SWRZO W 0-0 : one set is one electrode.)

^{2.} SWR1200 has a bracket. Please contact us for further information.

 $^{\%3.\,}$ The tightening torque for M3 mounting bolts marked with %3 should be 0.63 N \cdot m.



Wiring Color

| Electrode for Tool | Adapter side | ÷ | Electrode for Master Cylinder side | | | | |
|------------------------|--------------|---|------------------------------------|--------|--|--|--|
| Output + 12V | White | ÷ | Input +24V | White | | | |
| Output 0V | Blue | ÷ | Input 0V | Blue | | | |
| Polarity Switching POL | Black | ÷ | INZONE | Black | | | |
| Input 1 (SI1) | Brown | | Output 1 (SO1) | Brown | | | |
| Input 2 (SI2) | Red | ÷ | Output 2 (SO2) | Red | | | |
| Input 3 (SI3) | Yellow | | Output 3 (SO3) | Yellow | | | |
| Input 4 (SI4) | Green | 1 | Output 4 (SO4) | Green | | | |

Bending Radius of Cable

The minimum bending radius for the sensors are 50mm.

% Do not pull the cable with excessive force.



Attention for Installation

(Read this section thoroughly before installation.)

- Ensure the power is switched off during installation or maintenance operations.
- Use a regulated power supply, e.g. switch-model type. Simpler power supplies, such as a full-wave rectification type, will cause the permissible ripple rating to be exceeded and may cause malfunction.
- Do not put metal objects between electrodes during operation. Failure to do so may cause heat generation, ignition, or malfunction.
- Ensure correct connections by referencing the wiring diagram.
- To avoid malfunction caused by induction noise, cable should be kept apart from motor or other power cable.
- The control communication device in the product may affect electronic devices and medical devices. Persons wearing pacemakers should stay away from this product.
- In order to avoid influence of surrounding metal, or to avoid mutual influence between parallel-mounted sensors, keep the minimum free zone as described on the right.



The information above is quoted from B & Plus K.K. Remote System User's Guide (No.T315201G). Please contact B & Plus K.K. (TEL 81(0)-493-71-5160) for further information about electrodes (Model No. SWRZ0W0-M-/ SWRZ0W0-T-

External Option : Waterproof Electrode (Noncontact Waterproof Option) IP67

| Externa | l Op | otion Symbol : V/V5/VX/VX5 |] | | • Spec | cifications | | |
|----------------------------------|----------------------|---|--|----------|--|--|-------------------------------------|-----------------|
| | | | | | Number o | f Signals (per electrode) | 12 | |
| Maste | er Cyl | inder V Tool Adap | ter | | Protectio | on Grade ^{%1} | IP67 | |
| model SWR | | 0-M□- VX model SWR |]0-T□- | V | | | PUR Ø 8.6 | |
| | | VX5 | | | Cable | | 2×0.5mm ² +13×0.18 | mm ² |
| | | | For b | oth | | Master Cylinder Side | 2m | |
| | | V/V5: NPN | NPN | and PNP. | Cable | -V Tool Adapter Side | 1m | |
| | | VA/ VA3 • PNP | | | Length | - VX | 2m | |
| | | | | | | - V5 / VX5 | 5m | |
| | E | | | | | Master Cylinder Side - V / VX | Electrode + Bracket 1 Cable 210g | 30g |
| | | | 6 | | Weight ^{%2} | Master Cylinder Side - V5 / VX5 | Electrode + Bracket 1 Cable 525g | 30g |
| | | | | | | Tool Adapter Side – V | Electrode + Bracket 1 Cable 105g | 30g |
| | | | | | ※1. Prote ※2. Weig | ection grade of the ele ht per electrode. | ectrode part. | |
| • External | l Di | mensions | dor Sido | Tool A | daptor Sid | 10 | | |
| | | Master Cylin | | | | | | |
| SWR0250- SWR0500- SWR0750- |)-M_)-M_)-M_ | -V/V5/VX/VX5 SWR1200-MAF-V/V5/ -V/V5/VX/VX5 SWR2300-MAF-V/V5/ -V/V5/VX/VX5 | /VX/VX5 /VX/VX5 | | SWR0250- SWR0500- SWR0750- | -T -V SWR1200 -T -V SWR2300 -T -V | D-T -V D-T -V | |
| Bracket Part | t e e e | Electrode Master Side (Included) NPN ① PNP ③ Consider the phasing (cable drawing direction) when mounting the electrode. | Green LED Orange LED 2 **4 | | Electrode - Consider the direction) with | Tool Side (Included) ⑦ e phasing (cable drawing hen mounting the electrode | Bracke | t Part |
| Model No. | No. | Name | Quantity | Model No | o. No. Na | ame | | Quantity |
| SWRZUNO | | Electrode (Master Side) NPN | 1 | | Ele | ectrode (Tool Side) | | 1 |
| -M/M05 | | Made by B & Plus RS12E-422N-PU-02/05 | | SWRZ0V0- | -T Ma | ade by B & Plus RS12T-4 | 22-PU-01 | 1 |
| | (2) | Hexagon Socket Bolt M4×0.7×12 (SUS)* | 4 2 | | 8 He | exagon Socket Bolt 🛛 🛽 🔊 | //4×0.7×12 (SUS) | 2 |

2 Notes: 1. Inform us with the model number shown above if you require an electrode only. (SWRZO V 🗆 0- 🗆 : one set is one electrode.) 2. For SWRZ0V0-M/M05 and SWRZ0VX0-M/M05, cable length of -M is 2m, and cable length of -M05 is 5m.

1

2

1

2

(4)

5

6

SWRZ0V0

Bracket (Common for Master/Tool Side)

M3×0.5×8 (SUS)

M4×0.7×8 (SUS)

Hexagon Socket Bolt

Hexagon Socket Bolt

1

2

2

*3. Even if the mounting phase of electrode on master and tool sides is different, signals can be transmitted.

Determine the mounting phase of electrodes based on the cable drawing direction.

%4. The tightening torque for M4 mounting bolts marked with %4 should be 1.5 N • m.

M4×0.7×12 (SUS)*4

M3×0.5×8 (SUS)

M4×0.7×8 (SUS)

Electrode (Master Side) PNP

Hexagon Socket Bolt

Hexagon Socket Bolt

Hexagon Socket Bolt

Made by B & Plus RS12E-422P-PU-02/05

Bracket (Common for Master/Tool Side)

SWRZ0VX0

-M/M05

SWRZ0V0

3

2

(4)

(5)

6

| Features Application Examples | Cross Section Action Description | Model No. Indication | Specifications Performance Curve | External Dimensions | External Options | Port Options Joint Specifications | Exclusive Cases | Cautions | |
|----------------------------------|-------------------------------------|-------------------------|-------------------------------------|------------------------|---------------------|--------------------------------------|--------------------|----------|--|
| | | | | | | | | | |

🜑 Details and Notes on External Option:Noncontact Waterproof Electrode



- Use a regulated power supply, e.g. switch-model type. Simpler power supplies, such as a full-wave rectification type, will cause the permissible ripple rating to be exceeded and may cause malfunction.
- Do not put metal objects between electrodes during operation. Failure to do so may cause heat generation, ignition, or malfunction.
- Ensure correct connections by referencing the wiring diagram.
- apart from motor or other power cable.
- The control communication device in the product may affect electronic devices and medical devices. Persons wearing pacemakers should stay away from this product.
- In order to avoid influence of surrounding metal, or to avoid mutual influence between parallel-mounted sensors, keep the minimum free zone as described on the right.



The information above is quoted from B & Plus K.K. Remote System User's Guide (No.T313A01Ue). Please contact B & Plus K.K. (TEL 81(0)-493-71-5160) for further information about electrodes (Model No. RS12E-422 - PU-02/05 and RS12T-422-PU-01).

Wiring Color

| Electrode for To | ol Adapter side | Electrode for Mas | Electrode for Master Cylinder side | | | | |
|------------------------|-----------------|-------------------|------------------------------------|--|--|--|--|
| Output + 12V | White | Input +24V | White | | | | |
| Output 0V | Pale blue | Input 0V | Pale blue | | | | |
| Polarity Switching POL | Black | INZONE | Black | | | | |
| Input 1 (SI1) | Brown | Output 1 (SO1) | Brown | | | | |
| Input 2 (SI2) | Red | Output 2 (SO2) | Red | | | | |
| Input 3 (SI3) | Orange | Output 3 (SO3) | Orange | | | | |
| Input 4 (SI4) | Yellow | Output 4 (SO4) | Yellow | | | | |
| Input 5 (SI5) | Green | Output 5 (SO5) | Green | | | | |
| Input 6 (SI6) | Blue | Output 6 (SO6) | Blue | | | | |
| Input 7 (SI7) | Violet | Output 7 (SO7) | Violet | | | | |
| Input 8 (SI8) | Gray | Output 8 (SO8) | Gray | | | | |
| Input 9 (SI9) | Brown * | Output 9 (SO9) | Brown * | | | | |
| Input 10 (SI10) | Red * | Output 10 (SO10) | Red * | | | | |
| Input 11 (SI11) | Orange 🛪 🔳 🔳 | Output 11 (SO11) | Orange * | | | | |
| Input 12 (SI12) | Yellow * | Output 12 (SO12) | Yellow * | | | | |

* is the line where = is printed on the core wire of each color. The unused lines are green *, blue *, and violet *.

Bending Radius of Cable

The minimum bending radius for the sensors are 50mm.

* Do not pull the cable with excessive force.



- operations.

- To avoid malfunction caused by induction noise, cable should be kept

61R

K

Locating

-Clamp

© External Option : Ground Electrode



Activity Ratio

Activity ratio shows the ratio of load time when welding with rated capacity to the prescribed period (10 minutes in JIS standard). Make sure that the activity ratio does not exceed 50% which is the rated activity ratio of the ground electrode (SWRZ0T0).

Activity Ratio (%) =
$$\frac{\text{Welding Time (min.)}}{\text{Prescribed Period (10 min.)}} \times 100$$
 Allowable
Activity Ratio (%) = $\frac{(\text{Rated Capacity 500 (A)})^2}{(\text{Operating Current(A)})^2} \times \frac{\text{Rated Capacity Ratio 50 (%)}}{(\text{Activity Ratio 50 (%)})}$

In case of Ground Electrode (SWRZ0T0) :

- Ex.1) When welding with 500A, because the activity ratio is 50%, it can be operated for 5 minutes and needs to be suspended for 5 minutes in a 10-minute period.
- Ex.2) When welding with 390A, the activity ratio is 78% so it can be operated for about 8 minutes and needs to be suspended for about 2 minutes in a 10-minute period.
- Ex.3) Unable to be operated when exceeding the rated capacity 500A. Please contact us.

Notes for Usage

The stroke of the ground electrode (SWRZOTO) is larger than the lifting stroke (detaching stroke) of SWR. When not pressing with a robot, SWR tilts during connecting operation so that connection may not be completed. Press not to tilt until SWR reaches the released (lifted) position by using a robot, etc.

| Application Examples Action Description Indication Penominalite Curve Dimensions Options Joint Specifications Cases |
|---|
|---|



%2. In case of SWR0500/0750, only one parallel pin (⑦) is used.

External Option : Ethernet Electrode

External Option Symbol:L

Master Cylinder model SWR - 0-M - L





Tool Adapter

model SWR 0-T-L

Specifications

| Rated Value | 2 | DC 30V 0.5A | | | | |
|--------------|----------------------|--|--|--|--|--|
| Number of P | oles (per electrode) | 4 | | | | |
| Connector | | M12 D-code 4 poles (female) (based on IEC61076-2-101) | | | | |
| Ethernet App | licable Standard | 100BASE-TX %3 | | | | |
| Transmissic | on Speed | 100Mbps **3 | | | | |
| Category | | CAT5 | | | | |
| | | EtherNet/IP | | | | |
| | | EtherCAT | | | | |
| Applicable | Fieldbus | PROFINET | | | | |
| | | Modbus TCP | | | | |
| | | CC-Link IE Field Network Basic **2 | | | | |
| | Master Cylinder | Electrode:106g | | | | |
| ₩ | Side | Bracket:16g | | | | |
| weight*1 | Tool Adapter | Electrode:96g | | | | |
| | Side | Bracket: 16g | | | | |
| | | | | | | |

%1. Weight per electrode. Bracket weight shows the weight of SWRZ0E0.

%2. Cannot be used with a fieldbus that requires a communication speed of 1Gbps such as CC-Link IE.

⑦ Hexagon Socket Bolt M4×0.7×12 (SUS)

2

※3. In the case transmission speed of Ethernet applicable standard 1000BASE-T (transmission speed : 1 Gbps) is required, please contact us.

• External Dimensions (SWR0250/SWR0500/SWR0750)

⑦ Hexagon Socket Bolt M4×0.7×12 (SUS)

| | | Master Cylinder Side | | Tool Adapter Side | | | | | | |
|-----------|-----|---|------------------|-------------------|-----------|---------------|---|--------------------|--|--|
| SWR0250 | -M | -L SWR0500-M - L SWR | R0750-M L | | SWR02 | 250- | T-L SWR0500-T-L SW | VR0750-T -L | | |
| | | | | | | (15.5) 27 5 6 | | | | |
| Model No. | No. | Name | Quantity | | Model No. | No. | Name | Quantity | | |
| | 1 | Electrode (Master Side) | 1 | | | 8 | Electrode (Tool Side) | 1 | | |
| SWRZ0L0-M | 2 | Parallel Pin ϕ 3×8 B Type (SUS) | 2 | 1 5 | SWRZ0L0-T | 2 | Parallel Pin ϕ 3×8 B Type (SUS) | 2 | | |
| | 3 | Hexagon Socket Bolt M4 \times 0.7 \times 25 (SUS) | 4 | | | 3 | Hexagon Socket Bolt M4 \times 0.7 \times 25 (SUS) | 4 | | |
| | 4 | Bracket (Common for Master/Tool Side) | 1 | | | 4 | Bracket (Common for Master/Tool Side) | 1 | | |
| SWRZOFO | 5 | Parallel Pin ϕ 3 × 6 B Type (SUS) | 1 | | SWRZOFO | 5 | Parallel Pin ϕ 3 × 6 B type (SUS) | 1 | | |
| JWNZUEU | 6 | Hexagon Socket Bolt M3 × 0.5 × 10 (SUS) | 2 | | JWILLOLU | 6 | Hexagon Socket Bolt M3×0.5×10 (SUS) | 2 | | |

Notes: 1. Inform us with the model number shown above if you require an electrode only. (SWRZOLO- : one set is one electrode.)

2

| Features Application Examples | Cross Section Action Description | Model No. Indication | Specifications Performance Curve | External Dimensions | External Options | Port Options Joint Specifications | Exclusive Cases | Cautions | K | |
|----------------------------------|-------------------------------------|-------------------------|-------------------------------------|------------------------|---------------------|--------------------------------------|--------------------|---------------------|----------|-----------------------------------|
| • Extern | al Dimen | sions(SW | R1200/SW | VR2300) | | | | | | Locating + Clamp |
| | Ma | ister Cylinder | Side | | | То | ol Adapter Si | de | | Locating |
| 5 | 5WR1200-M -L | (| 5WR2300-MAF -L | | | SWR1200-T- | L | SWR2300-T -L | - | Hand • Clamp |
| TYT | | | ₽ <u> </u> | | | Ψ | | | Ψ] | Support |
| | | | | | | | | | | Valve • Coupler |
| 2 | Ø | b | | | the second | # | Ø Ø | | . / | Cautions • Others |
| 27.5 | | | | Z. | | | 27.5 | | _ | Robotic Hand Changer |
| (15.5) | | 3 | | | | | | | 3) B) | SWR Payload 3kg ~ 360kg |
| | | → | | | | | < | 51 | | SWR0010 Payload 0.5kg ~ 1kg |
| | | • • | | | | <u>ب</u> | ⊕ | | | Manual Robotic Hand Changer |
| | | (| | | | 0.5 | | | | SXR |
| | | | 0.5 | | | | ···· ··· b. , | | | Pneumatic Location Clamp |
| | L | لـر | | | | | | | | SWT |

| Model No. | No. | Name | Quantity |
|-----------|-----|---|----------|
| | 1 | Electrode (Master Side) | 1 |
| SWRZ0L0-M | 2 | Parallel Pin ϕ 3×8 B Type (SUS) | 2 |
| | 3 | Hexagon Socket Bolt M4 \times 0.7 \times 25 (SUS) | 4 |

| 1. 101 SWITZ00/SWITZ500, SWITZ0E01SHOTTEQUIED. | Notes: | 1. | For | SWR1200/SWR2300, | SWRZ0E0 is not required. |
|--|--------|----|-----|------------------|--------------------------|
|--|--------|----|-----|------------------|--------------------------|

| Model No. | No. | Name | Quantity |
|-----------|-----|---|----------|
| | 8 | Electrode (Tool Side) | 1 |
| SWRZ0L0-T | 2 | Parallel Pin ϕ 3×8 B Type (SUS) | 2 |
| | 3 | Hexagon Socket Bolt M4 \times 0.7 \times 25 (SUS) | 4 |

Compact Pneumatic Location Clamp SWQ High-Power Pneumatic Pallet Clamp WVS

• External Option : Air Joint (3-Port Option (1 Port Rc1/8))

Extensible Options : Resin Connector, Solder Terminal

External Option Symbol: R



Specifications

| Port Size | | Rc1/8 | M5 | | |
|----------------------|----------------------|--|--------------------|--|--|
| Number of | Ports | 1 | 2 | | |
| Operating | SWR0070 or larger | max. 0.7MPa (Va | acuum Available) | | |
| Pressure | SWR0030 | max. 0.5MPa (Va | acuum Available) | | |
| Withstandi | ng Pressure | 1.11 | ИРа | | |
| Min. Passag | je Area | 28.3mm ² | 3.1mm ² | | |
| Operating 1 | [emperature | 0 ~ 70°C | | | |
| Usable Flui | d | Dry Air | | | |
| | Pressure at 0.7 MPa | 0.13 kN | 0.04kN | | |
| Reaction Force | Pressure at 0.5 MPa | 0.10 kN | 0.03kN | | |
| (per port) | Pressure at P MPa | 0.154×P+0.019 kN | 0.047×P+0.008 kN | | |
| Weight ^{※1} | Master Cylinder Side | Air Joint 51g Bracket for SWR0030-M : 10g | | | |
| | Tool Adapter Side | Air Joint 25g Bracket for SWR0030-T : 8g | | | |

%1. Weight per joint.

Bracket weight is the weight of SWRZ0S0- \Box .

• Extensible Options Additional electrode can be extended to the option : R .



| | Model No. for Extensible Option | | | | | | | |
|---------------------------------------|---------------------------------|-------------|-------------|-------------|-------------|-------------|--|--|
| Extensible Electrode | SWR 0030 | SWR 0070 | SWR 0120 | SWR 0250 | SWR 0500 | SWR 0750 | | |
| J : Resin Connector | | JR | JR | JR2 | JR2 | JR2 | | |
| B:Solder Terminal | N/A | BR | BR | BR2 | BR2 | BR2 | | |
| CO :Cable with Solder Terminal | | C0□R | C0□R | CO R2 | CO R2 | C0 🗆 R2 | | |

* Please contact us for detailed dimensions for extensible options.

• External Dimensions (SWR0070/SWR0120/SWR0250/SWR0500/SWR0750)



Note: 1. Inform us with the model number shown above if you require an air joint only. (SWRZORO- \Box : one set is one air joint.) For SWRZORO-M / SWRZORO-T, the bolt marked with ≥ 2 is not included.

| Features Application Examples | Cross Section Action Description | Model No. Indication | Specifications Performance Curve | External Dimensions | External Options | Port Options Joint Specifications | Exclusive Cases | Cautions | | SMEK |
|----------------------------------|-------------------------------------|-------------------------|-------------------------------------|------------------------|---------------------|--------------------------------------|--------------------|---------------------|-----------------|------------------------|
| • Extern | al Dimens | ions (SWR | 0030) | | | | | | • | Locating + Clamp |
| | | | Master Cy | ylinder Side | Tool A | dapter Side | | | | Locating |
| SWR0030- | M -R * Mou | ınt SWRZ0S0-M, | only in case of S | WR0030-M-R. | SWR | 0030-T -R % | Mount SWRZ0S | 0-T, only in case c | of SWR0030-T-R. | Hand • Clamp |
| | 2-Air Port M5×0.8 Thread | | 7) 2 | | | 2-Air Port M5×0.8 Threa | d | | | Support |
| | 20 4 | | | | | 20 4 | | • 4 6 | | Valve • Coupler |
| | <u>v</u> 1 Air Davi | | T a | " القبب | | 1 Air Dout | | 4 | S | Cautions • Others |

1-Air Port

Seating Surface

Model No.

SWRZORO-T

_ %2

SWRZ0S0-T

No.

4

2

3

8

6

Rc1/8 Thread

ŝ

Joint (Tool Side)

Bracket (Tool Side)

Parallel Pin

Parallel Pin

Name

(3)

φ 1.5 × 4 B Type (SUS)

 ϕ 2 \times 6 B Type (SUS)

Quantity

1

2

2

1

1

1

16.3 16.3

42

• ●

Hexagon Socket Bolt M3 \times 0.5 \times 20 (SUS)

 \bigcirc Hexagon Socket Bolt M3×0.5×6 (SUS)

1-Air Port

Seating Surface

Model No.

SWRZ0R0-M

_ %2

SWRZ0S0-M

Note :

Rc1/8 Thread

21

 \sim

Parallel Pin

Parallel Pin

Joint (Master Side)

Bracket (Master Side)

No. Name

1

2

3

5

6

0

16.3 16.3

42

Hexagon Socket Bolt M3 \times 0.5 \times 20 (SUS)

Hexagon Socket Bolt M3 \times 0.5 \times 6 (SUS)

 ϕ 1.5 × 4 B Type (SUS)

 ϕ 2 \times 6 B Type (SUS)

Quantity

1

2

2

1

1

1

For SWRZ0R0-M / SWRZ0R0-T / SWRZ0S0-M / SWRZ0S0-T, the bolt marked with %2 is not included.

1. Inform us with the model number shown above if you require an air joint only. (SWRZOR0- \Box : one set is one air joint.)

Robotic Hand Changer

SWR Payload 3kg ~ 360

SWR0010

Payload 0.5kg ~ 1kg

Manual Robotic Hand Changer

SXR

Location Clamp

Pneumatic

SWQ

High-Power Pneumatic Pallet Clamp

WVS

© External Option : Air Joint (4-Port, Solder Terminal Extensible Option)

Extensible Options : Resin Connector, Solder Terminal



Specifications

| Number of | Ports | 4 | | | | |
|------------------------|----------------------|--|--|--|--|--|
| Operating I | Pressure | max. 1.0MPa (Vacuum Available) | | | | |
| Withstandi | ng Pressure | 1.5MPa | | | | |
| Min. Passag | je Area | 2.0mm ² (Equal to ϕ 1.6) | | | | |
| Operating ⁻ | Femperature | 0 ~ 70℃ | | | | |
| Usable Flui | d | Dry Air | | | | |
| | Pressure at 1 MPa | 0.03 kN | | | | |
| Reaction Force | Pressure at 0.5MPa | 0.02 kN | | | | |
| (per port) | Pressure at P MPa | 0.027×P+0.004 kN | | | | |
| Waight %1 | Master Cylinder Side | Joint 43g | | | | |
| weight ** | Tool Adapter Side | Joint 26g | | | | |

%1.Weight per joint.

• Extensible Options Additional electrode can be extended to the option : P .





Notes : 1. Inform us with the model number shown above if you require an air joint only. (SWRZOP0-□ : one set is one air joint.) For SWRZOP0-M / SWRZOP0-T, the bolt marked with %2 is not included.

2. Please contact us for SWR1200.

External Option : Air Joint

External Option Symbol: Q



External Dimensions

5

6

7

SWRZ0Z0

Parallel Pin

 ϕ 3 \times 8 B Type (SUS)

Hexagon Socket Bolt M3 \times 0.5 \times 10 (SUS)

Hexagon Socket Bolt M4 \times 0.7 \times 12 (SUS)





Specifications

| | Number of | Ports | 2 | | | |
|--|------------------------------|----------------------|---|--|--|--|
| | Operating I | Pressure | max. 1.0MPa (Vacuum Available | | | |
| | Withstandi | ng Pressure | 1.5MPa | | | |
| | Min. Passag | je Area | 12.6mm ² (Equal to ϕ 4) | | | |
| | Operating 7 | Femperature | 0 ~ 70℃ | | | |
| | Usable Flui | d | Dry Air | | | |
| | | Pressure at 1 MPa | 0.13 kN | | | |
| | Reaction Force (per port) | Pressure at 0.5MPa | 0.07 kN | | | |
| | | Pressure at P MPa | 0.117×P+0.01 kN | | | |
| | Weight ^{%1} | Master Cylinder Side | Joint 70g / Bracket 17g | | | |
| | | Tool Adapter Side | Joint 60g / Bracket 17g | | | |
| | | | | | | |

%1.Weight per joint.

Bracket weight is the weight of SWRZ0Z0.



Valve • Coupler

Cautions • Others

Rol Hai

| ootic nd Changer | | | | | | |
|---------------------|-----------------------------------|--|--|--|--|--|
| | SWR Payload 3kg ~ 360kg | | | | | |
| | SWR0010 Payload 0.5kg ~ 1kg | | | | | |

Manual Robotic Hand Change SXR

Pneumatic Location Clamp SWT

> Compact Pneumatic Location Clamp SWQ

> > WVS



(5)

6

7

SWRZ0Z0

Parallel Pin

 ϕ 3 \times 8 B Type (SUS)

Hexagon Socket Bolt M3×0.5×10 (SUS)

Hexagon Socket Bolt M4 \times 0.7 \times 12 (SUS)

1

2

2

2 Notes: 1. Inform us with the model number shown above if you require an air joint only. (SWRZ0Q0-D: one set is one air joint.) 2. Please contact us for SWR1200.

1

2

66

Port Option

Master Cylinder Model No.



• Port Option Symbol | A : With Air Blow Port

When connecting, there is moderate clearance between the taper reference surface and seating surface that enables high accuracy. This allows for effective cleaning with air blow, contamination prevention and longer operational life.



• Port Option Symbol **F** : With Seat Check Port

Close contact check detects secure connection of the master cylinder and the tool adapter. This prevents a connection error of robotic hand changer.

Close contact check is conducted with the air catch sensor. (Air catch sensor must be installed separately.)



In case of using a 2-position solenoid valve, make sure to select the solenoid valve for operating SWR that supplies air pressure to the lock port side when it is not magnetized. Refer to "2) Air Pressure Circuit Reference" on P.77 for the detail.





Notes : ※2. For SWR0500/0750/1200/2300, ★O-ring is installed to the master cylinder side.

- Refer to the Joint Structure on External Dimensions (P.31 ~ P.34) for the structure of the check valve option.
 - %3. For SWR0070 ~ SWR0750, a check valve is installed to the master cylinder side only.
 - Since there is no check valve for the tool adapter side, the joint option symbol of SWR0030-T ~ SWR0750-T is Blank. #4. For SWR1200, SWR2300 with the check valve option, since the master cylinder has a check valve and the tool adapter side has a simple check valve, the joint option symbol of SWR1200-T, SWR2300-T is S.

• 3kg Payload • 6 Air Port Model SWRY0010



Slight increase in size enables to install 6 air ports in 3kg payload robotic hand changer.



- **R** : Air Joint (3 Ports)
- **U01** : Simple Waterproof Electrode (16 Poles Cable Length 1m)
- **U02** : Simple Waterproof Electrode (16 Poles Cable Length 2m)
- W : Noncontact Waterproof Electrode Compact Model (Number of Signals: 4•NPN)
- WX : Noncontact Waterproof Electrode Compact Model (Number of Signals: 4•PNP) **1 **1. The option symbol 'WX' is only for master cylinder. The option symbol of the tool adapter is 'W' for both NPN/PNP.

Specifications

| Payload | kg | 3 | | |
|---------------------|-----------------------|----------------|--|--|
| Repeatability | mm | 0.003 | | |
| Lift Stroke (Detach | ning Stroke) mm | 0.8 | | |
| Allowable Static | Bending | 5 | | |
| Moment N·m | Twisting | 12 | | |
| | Max. | 1.0 | | |
| Air Pressure | Min. | 0.4 | | |
| MPa | Withstanding Pressure | 1.5 | | |
| Operating Tem | perature °C | 0 ~ 70 | | |
| Usable Fluid | | Dry Air | | |
| Weight | Master Side | 85 | | |
| (Main Body) g | Tool Side | 60 | | |
| Air Port | · | M3×0.5×6 Ports | | |

% Refer to P.37 ~ P.64 for the specifications of the external options.

Performance Curve



Compact Pneumatic

Location Clamp

High-Power Pneumati Pallet Clamp

WVS

SWRY0010 External Dimensions

• External Dimensions (without External Option)





SWRY0010 External Dimensions

• External Dimensions of External Options

* Refer to P.71 for unlisted dimensions.



| Features Application Examples | Cross Section Action Description | Model No. Indication | Specifications Performance Curve | External Dimensions | External Options | Port Options Joint Specifications | Exclusive Cases | Cautions | |
|----------------------------------|-------------------------------------|-------------------------|-------------------------------------|------------------------|---------------------|--------------------------------------|--------------------|----------|------------------------|
| | | | | | | | | | Locating + Clamp |
| | | | | | | | | | Locating |
| | | | | | | | | | |

Master Cylinder SWRY0010-M-W

% Refer to P.59 for the detailed electrode specifications.



Electrode W/WX





Compact Model



Robotic Hand Changer SWR Payload 3kg ~ 360kg

Hand • Clamp

Valve • Coupler

Cautions • Others

Support

SWR0010 Payload 0.5kg ~ 1kg

Manual Robotic Hand Changer SXR

Pneumatic Location Clamp SWT

Compact Pneumatic Location Clamp SWQ

High-Power Pneumatic Pallet Clamp

WVS

- **Exclusive Cases** * A Part of Exclusive Case Examples. Please contact us for further information.
- With Center Hole







Disconnected

Connected

Center hole is provided for photoelectric detection and various purposes.



Cautions

Notes for Design

- 1) Check Specifications
- Please use each product according to the specifications.
- Operating Air Pressure as follows : SWR0030, SWRY0010 : Max. 1.0 MPa and Min. 0.4MPa SWR0070 ~ SWR1200 : Max. 1.0 MPa and Min. 0.35MPa SWR2300 : Max. 0.7 MPa and Min. 0.35MPa
- 2) Air Pressure Circuit Reference
- SWR remains locked (keeps holding a tool) with mechanical lock (spring for maintain). However, for safety, when using a 2-position solenoid valve, make sure to select the solenoid valve for operating SWR that supplies air pressure to the lock port side when it is not magnetized. If air is supplied to the release port when the switch of solenoid valve is turned off, it is very dangerous since SWR may drop the tool (hand).



- 3) Operating Environment (External Option (Electrode))
- Do not use the product in the environment with water vapor liquid • scattering of chemicals • explosion • gas with causticity. Also, using in the environment with cutting chips • cutting fluid • dust • spatter scattering may lead to continuity error of electrode. We offer IP67-Compatible Noncontact Waterproof Electrode for the environment with water • vapor • liquid • cutting chips.
- Electrification of Electrodes while Connecting/Disconnecting (External Option (Electrode))
- If connecting/disconnecting robotic hand changer while energized (hot swapping), there will be a discharge phenomenon (spark phenomenon) between the electrodes opposing each other. The tips of contact probes and electrode bars will be severely worn down due to the phenomenon, and the basis metal might be melted due to oxidation or abrasion of gold-plating leading to conduction failure. Electricity should be shut off while connecting/disconnecting the robotic hand changer.

In case of continuous electrification with more than 40 \sim 60% of rated current, it is recommended to use multiple electrodes in a line. (In order to improve durability of contact probes.)

- 5) Note for Single Use of SWR Robotic Hand Changer
- Applying withstanding pressure without mounting on a robot or a plate leads to damage on the product. Make sure to supply air after setting SWR on a robot or a plate.
- 6) Hand Changing (Attaching/Detaching) in a Horizontal Position
- When connecting/disconnecting the Robotic Hand Changer in a horizontal position, make sure not to apply excessive moment on master cylinder. Please select an appropriate size of model cosidering robot payload with allowance fully taken into consideration. When connecting, make sure the tool side has no lifting or tilting that is larger than the allowable position offset range. Also, do not fix it completely on the tool stand, and make a margin (clearance) within the allowable position offset range. Otherwise, this will affect repeatability.

Installation Notes

- 1) Please supply filtered clean dry air.
- Make sure to supply filtered clean dry air.
- Oil supply with a lubricator etc. is unnecessary.
- 2) Preparation for Piping
- The pipeline, piping connector and fixture circuits should be cleaned and flushed thoroughly.

The dust and cutting chips in the circuit may lead to fluid leakage and malfunction.

There is no filter provided with this product for prevention of contaminants in the air circuit.

3) Applying Sealing Tape

When using sealing tape, wrap with it 1 to 2 times following the screwing direction.

When piping, be careful that contaminant such as sealing tape does not enter in products. Pieces of the sealing tape can cause air leaks and malfunction.

- 4) Notes on Wire/Cable Procedure and Wiring (External Options (Electrode))
- Make sure to fix the wire and cable so that they are not pulled while a robot is moving or turning around.

External force should not be applied on the connector part since it leads to breaking of wire, detaching of connector and contact failure.



 When allocating each electric signal, imperceptible signal and power signal should be apart. Otherwise noise will be propagated from power signal to imperceptible signal.
 Also it is the same for wire and cable of external options (electrode).
 Make sure to keep imperceptible signal from power signal.

| Features Application Examples | Cross Section Action Description | Model No. Indication | Specifications Performance Curve | External Dimensions | External Options | Port Options Joint Specifications | Exclusive Cases | Cautions | |
|----------------------------------|-------------------------------------|-------------------------|-------------------------------------|------------------------|---------------------|--------------------------------------|--------------------|----------|----------------|
| | | | | | | | | | ria nony in in |

5) Installation/Removal of Master Cylinder/Tool Adapter

Please follow the tightening torque below.

When mounting, use the attached pins and tighten them with bolts evenly not to incline the master cylinder and tool adapter.

| Model No. | | Bolt Size | No. of Bolts | Tightening Torque (N·m) |
|-----------|------------|------------------|--------------|-------------------------|
| | SWR0030-M | $M3 \times 0.5$ | 4 | 1.3 |
| Ī | SWRY0010-M | $M3 \times 0.5$ | 3 | 1.3 |
| der | SWR0070-M | $M3 \times 0.5$ | 4 | 1.3 |
| /lin | SWR0120-M | M4 	imes 0.7 | 4 | 3.2 |
| Ś | SWR0250-M | M5 	imes 0.8 | 4 | 6.3 |
| ste | SWR0500-M | $M6 \times 1$ | 4 | 10 |
| Ma | SWR0750-M | M6 	imes 1 | 6 | 10 |
| | SWR1200-M | M8 × 1.25 | 6 | 25 |
| | SWR2300-M | $M10 \times 1.5$ | 6 | 50 |
| | SWR0030-T | M3 	imes 0.5 | 4 | 1.3 |
| | SWRY0010-T | $M3 \times 0.5$ | 3 | 1.3 |
| er | SWR0070-T | M4 	imes 0.7 | 4 | 3.2 |
| apti | SWR0120-T | M4 	imes 0.7 | 4 | 3.2 |
| Adi | SWR0250-T | M5 	imes 0.8 | 4 | 6.3 |
| 0 | SWR0500-T | $M6 \times 1$ | 4 | 10 |
| Ĕ | SWR0750-T | $M6 \times 1$ | 6 | 10 |
| | SWR1200-T | M8 × 1.25 | 6 | 20 |
| | SWR2300-T | M10 	imes 1.5 | 6 | 50 |

Do not lose attached pins for installation/removal of the master cylinder/tool adapter.

If not using attached pins, moment quality may not be secured.

6) Installation of Optional Electrode

For electrode installation, apply screw lock glue (equivalent to 1401 made by ThreeBond) on the tip of the mounting bolt and tighten it with the tightening torque shown below.

- M3 Hexagon Socket Bolt : 0.5N m
- ・M4 Hexagon Socket Bolt:1.5N・m
- 7) Test Run Method
- If supplying a large amount of air just after installation, action time will be extremely fast leading to severe damage on

robotic hand changer. Set the speed controller (Meter-in) and gradually supply air pressure.

| 8) | Allowable | Offset | while | Teaching |
|----|-----------|--------|-------|----------|
|----|-----------|--------|-------|----------|



Tool adapter and tool placing stand should have space within the range of allowable offset.

1 Allowable Position Offset in Horizontal Direction

② Allowable Position Offset in Tilt Direction

Allowable Offset θ

 $\theta = 1.5 \deg$

 $\theta = 1.5 \deg$

 $\theta = 1.5 \deg$

 $\theta = 1.5 \deg$

 $\theta = 1.2 \deg$

 $\theta = 1.0 \deg$

 $\theta = 1.0 \deg$

 $\theta = 0.9 \deg$

 $\theta = 0.6 \deg$

| Model No. | Allowable Offset Amm |
|-----------|----------------------|
| SWR0030 | ±0.8 mm |
| SWRY0010 | ±0.8 mm |
| SWR0070 | ±0.8 mm |
| SWR0120 | ±0.8 mm |
| SWR0250 | ±1.0 mm |
| SWR0500 | ±1.3 mm |
| SWR0750 | ±1.3 mm |
| SWR1200 | ±2.0 mm |
| SWR2300 | ±2.0 mm |
| | |

Model No.

SWR0030

SWRY0010

SWR0070

SWR0120

SWR0250

SWR0500

SWR0750

SWR1200

SWR2300



1) Horizontal Position Offset

Pneumatic Location Clamp

Manual Robotic Hand Changer

SXR

Robotic Hand Changer

SWR Payload 3kg ~ 360

SWR0010 Payload 0.5kg ~ 1kg

SWT Compact Pneumatic

Location Clamp SWQ

High-Power Pneumati Pallet Clamp WVS

0 0

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000

2 Tilt Position Offset

3 Allowable Position Offset in Rotation Direction

| Model No. | Allowable Offset $	heta$ |
|-----------|--------------------------|
| SWR0030 | $\theta = \pm 3 \deg$ |
| SWRY0010 | $\theta = \pm 3 \deg$ |
| SWR0070 | $\theta = \pm 3 \deg$ |
| SWR0120 | $\theta = \pm 3 \deg$ |
| SWR0250 | $\theta = \pm 2 \deg$ |
| SWR0500 | $\theta = \pm 2 \deg$ |
| SWR0750 | $\theta = \pm 2 \deg$ |
| SWR1200 | $\theta = \pm 2 \deg$ |
| SWR2300 | $\theta = \pm 1.5 \deg$ |



③ Rotation Position Offset

Continuing "Installation Notes" on the Next Page



Locating + Clamp Locating

Cautions

- Installation Notes (Continued)
- Most Suitable Gap between Master Cylinder and Tool Adapter Just Before Connection (When Setting)
- The gap between master cylinder and tool adapter when connecting should be within the range of [Lift Stroke]~[Lift Stroke+0.5mm] shown on P.25. It may not be able to connect with more than the lift stroke + 0.5mm.
- 10) Most Suitable Gap between Tool Adapter and Tool Placing Stand Just Before Disconnection
- The gap between the tool adapter and tool stand when detaching should be more than [Lift Stroke] shown on P.25.
 - Tool adapter is forcibly detached with detaching (lifting) function of the master cylinder.
 - It is recommended to install cushioning mechanism between the tool adapter and tool stand.



- 11) Connection Method for -B : Solder Terminal (External Option (Electrode))
- For solder terminal option, the electric signal pin, wire and cable of both master cylinder and tool adapter are connected with soldering. Remove the continuity prevention cover before soldering. At this time, if removing the press-fitted housing of the electric signal pin, install it as shown in the following drawing [Mounting Height] considering the height from seating surface.



【Mounting Height】

Model : SWR0030/0070/0120/0250/0500/0750/1200/2300 % Make sure not to tilt, and adjust the height of both ends of the housing.



Soldering condition should be : 280° C, within 3 seconds. Make sure the outer diameter is ϕ 1.6mm after soldering. If it exceeds ϕ 1.6mm the continuity prevention cover cannot be installed. [Recommended Wire Diameter]

Use wires with AWG26 size or smaller diameter. If you need electric current more than allowable flowing current of AWG26, use wires within the rated value of electrode. At this time, soldering hole and attached continuity prevention cover cannot be used. If required, insulate them with a thermal contraction tube etc.

Before installing the continuity prevention cover, apply screw lock glue (equivalent to 1401 made by ThreeBond) on the tip of M3 hexagon socket bolt.

Tightening Torque of M3 Hexagon Socket Bolt : 0.5N • m

12) Connection Method for -D/E/G/H/J/L : Connector (External Option (Electrode))

- A Connector must be fully inserted into the electrode. As for -D/E/ G/H/L options, make sure to screw up the connector. If a connector is not fully inserted or screwed up, it will cause contact failure.
- 13) Notes for using -K : Compact Electric Power Transmission (External Option (Electrode))
- As for Compact Electric Power Transmission option, the electrode probes on both master cylinder and tool adaptor are exchangeable. The electrode probes will be fallen out if pushed from the cable connecting side with power stronger than a certain level.
 In case the electrode probes are pushed out after connecting the cable, make sure to push them back from the seating surface side before use.



Cautions

- Maintenance Inspection
- 1) Removal of the Product and Shut-off of Pressure Source
- Before removing the product, make sure that the safety devices are in place. Shut off the pressure and power source and make sure no pressure exists in the air and hydraulic circuits.
- Make sure there is no trouble/issue in the bolts and respective parts before restarting.
- 2) Cleaning of Master Cylinder Tool Adapter
- If using the product when the taper reference surface or seat check surface of master cylinder/tool adapter are contaminated with dirt, it may lead to locating accuracy failure, malfunction or air leakage. (Do not apply grease on the taper reference surface.)



- 3) Regularly examine and retighten piping, mounting bolts and wires to ensure proper use.
- 4) Make an inspection before use and regularly.
- If there is dirt or dust on the electric contact part, electric signal is hard to conduct. Wipe it out with a cloth soaked in an organic solvent such as IPA.
- If there is a contact failure while in use, make an inspection mainly of the electricity connection part and clean it out. If the contact probe of master cylinder has abnormality, it has to be replaced. When installing an electrode after removing it, check the mounting height of -B : Solder Terminal connection method on P.79.



- 5) Make sure to supply filtered clean dry air.
- 6) Make sure there is smooth action and no air leaks.
- Especially when it is restarted after left unused for a long period, make sure it can be operated properly. If there is air leak while connecting, please contact us for overhaul and repair.
- 7) The products should be stored in the cool and dark place without direct sunshine or moisture.
- 8) Please contact us for overhaul and repair.



-Clamp

Locating

Hand · Clamp

Support

Valve • Coupler

Cautions • Others

Robotic Hand Changer SWR

SWR0010 Payload 0.5kg ~ 1kg

Manual Robotic Hand Change SXR

Pneumatic Location Clamp SWT

Compact Pneumatic Location Clamp SWQ

High-Power Pneumati Pallet Clamp WVS
Cautions

- Notes on Handling
- 1) It should be operated by qualified personnel.
- The hydraulic machine and air compressor should be operated and maintained by qualified personnel.
- 2) Do not operate or remove the product unless the safety protocols are ensured.
- ① The machine and equipment can only be inspected or prepared when it is confirmed that the safety devices are in place.
- ② Before the product is removed, make sure that the above-mentioned safety devices are in place. Shut off the pressure and power source, and make sure no pressure exists in the air and hydraulic circuits.
- ③ After stopping the product, do not remove until the temperature drops.
- ④ Make sure there is no trouble/issue in the bolts and respective parts before restarting the machine or equipment.
- Do not touch a clamp (cylinder) while it is working.
 Otherwise, your hands may be injured.



- 4) Do not disassemble or modify.
- If the equipment is taken apart or modified, the warranty will be voided even within the warranty period.

Maintenance and Inspection

- 1) Removal of the Machine and Shut-off of Pressure Source
- Before removing the product, make sure that the safety devices are in place. Shut off the pressure and power source and make sure no pressure exists in the air and hydraulic circuits.
- Make sure there is no trouble/issue in the bolts and respective parts before restarting.
- 2) Regularly clean the area around the piston rod and plunger.
- If it is used when the surface is contaminated with dirt, it may lead to packing seal damage, malfunctioning, fluid leakage.



- Regularly clean the reference surfaces (taper reference surface and seating surface) of locating products (SWT/SWQ/SWP/VRA/ VRC/VX/VXE/VXF/WVS/VWH/VWM/VWK).
- Locating products (except VRA/VRC/VX/VXE/VXF and SWR without air blow port) can remove contaminants with the cleaning function. When installing a workpiece or a pallet, make sure there are no contaminants such as thick sludge.
- Continuous use with dirt on components will lead to locating failure, fluid leakage and malfunction.



- 4) Regularly tighten pipe, mounting bolt, nut, snap ring, cylinder and others to ensure proper use.
- 5) Make sure the hydraulic fluid has not deteriorated.
- 6) Make sure there is a smooth action without an irregular noise.
- Especially when it is restarted after left unused for a long period, make sure it can be operated correctly.
- The products should be stored in the cool and dark place without direct sunshine or moisture.
- 8) Please contact us for overhaul and repair.

Warranty



Locating

Warranty

- 1) Warranty Period
- The product warranty period is 18 months from shipment from our factory or 12 months from initial use, whichever is earlier.
- 2) Warranty Scope
- If the product is damaged or malfunctions during the warranty period due to faulty design, materials or workmanship, we will replace or repair the defective part at our expense.
 Defects or failures caused by the following are not covered.
- ① If the stipulated maintenance and inspection are not carried out.
- ② Failure caused by the use of the non-confirming state at the user's discretion.
- ③ If it is used or operated in an inappropriate way by the operator.
 (Including damage caused by the misconduct of the third party.)
- 4 If the defect is caused by reasons other than our responsibility.
- (5) If repair or modifications are carried out by anyone other than Kosmek, or without our approval and confirmation, it will void warranty.
- ⑥ Other caused by natural disasters or calamities not attributable to our company.
- ⑦ Parts or replacement expenses due to parts consumption and deterioration.

(Such as rubber, plastic, seal material and some electric components.)

Damages excluding from direct result of a product defect shall be excluded from the warranty.

Clamp Locating

Hand • Clamp

Support

Valve • Coupler

Cautions • Others

Cautions Installation Notes Maintenance/ Inspection Warranty

Company Profile Company Profile

> Our Products History

Index Search by Alphabetical Order

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