Wireless Sensing Receiver • Repeater

Receiver Model YWA Repeater Model YWB



System Configuration Products Required for Wireless Sensing

Model No. Indication

Receiver



Classification

100: Standard Model

3 Available Country: Frequency

B02 : China

2 Design No.

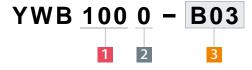
0: Revision Number

4 Monitor Display Language

E : EnglishJ : Japanese

C : Chinese (Simplified)

Repeater -



1 Classification

100: Standard Model

2 Design No.

0 : Revision Number

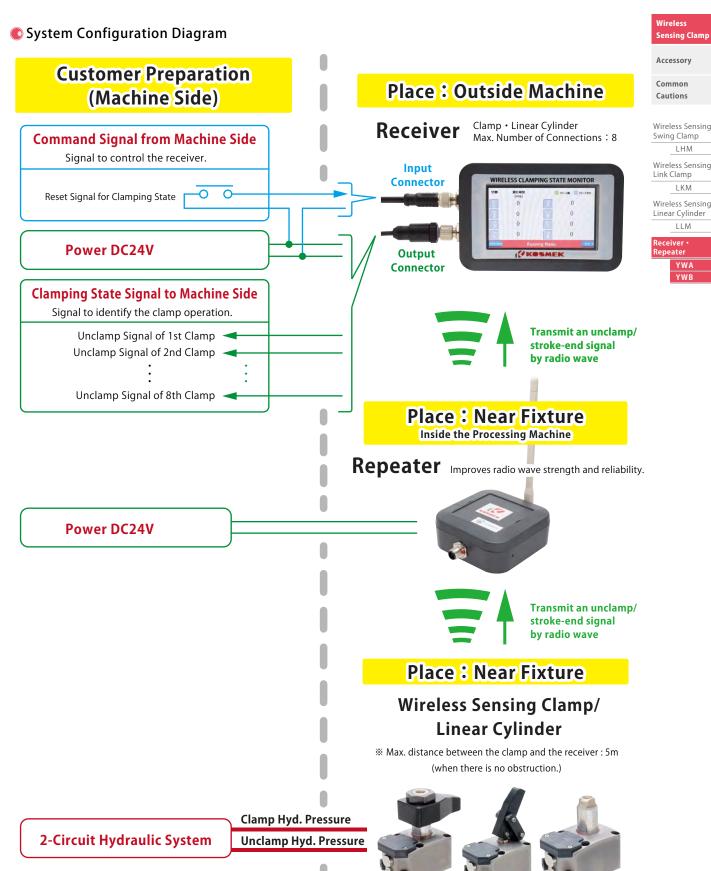
3 Available Country: Frequency

B03: United States

B01 : Japan **B02** : China

※ There are restrictions on countries where the product can be used according to radio regulations. Please follow the regulatory requirements of each country.





Wireless

Common

Cautions

LHM

LKM

HIM

Sensing Clamp Accessory

$lue{\mathbb{Q}}$ Specifications : Receiver model YWA1000-B \Box - \Box

This receiver receives unclamp and stroke-end confirmation signals from wireless sensing clamps, linear cylinders (model LHM / LKM / LLM), and repeater (model YWB) and displays them on a monitor and outputs them to an external device.



Clamping state, operating time, and radio wave condition can be checked on the monitor.

The output contact can be turned off and the operating time can be reset by switching the clamping state reset.

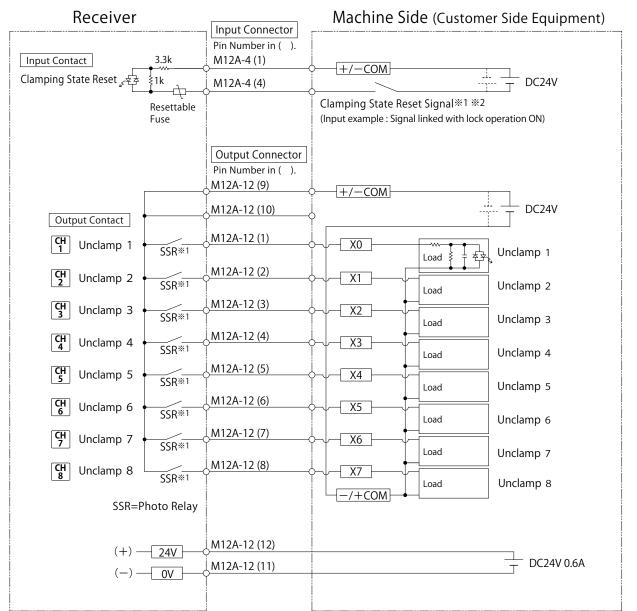
Model No.		YWA1000−B□−□	
		3 When selecting B03 : 902MHz Band	
Receiving Frequency		3 When selecting B01 : 920MHz Band	
		3 When selecting B02 : 868MHz Band	
Receiving Sensitivity		−85dBm(25°C)	
Number of Receivable Connections (Number of Wireless Sensing Clamps / Linear Cylinders Connected)		Up to 8 units	
Response Time		≦100msec (from wireless detection to state output)	
Number of Simultaneous Wireless Signals Received		1	
Power Supply		DC24V±20% 0.6A	
Operating Temperature and Humidity		-10°C ~ 60°C • 90% or less (at 40°C)	
Storage Temperature and Humidity		-20°C ~ 70°C ⋅ 90% or less (at 60°C)	
Clamping State Output	Number of Outputs	8 (M12 Coding A 12 pins)	
	Output Attributes	8-output collective common (PNP/NPN switchable)	
	Output Ratings	MAX DC24V±10% 0.45A	
	Output Protection	Built-in overvoltage and overcurrent protection elements	
Clamping State Reset Input	Number of Inputs	1 (M12 Coding A 4 pins)	
	Input Terminals	Operation-end reset input by the signal linked with lock operation ON	
	Input Attributes	External voltage input optocoupler (MAX DC24V)	
Weight		500 g (including mounting bracket)	

External Dimensions (unit:mm) 160 150 16.5 127 16.5 $4 - \phi 3.2$ WIRELESS CLAMPING STATE MONITOR 001 (KOSMEK $2 - \phi 5.2$ 1.7 1.2 Input Connector (150) 10 10 M12 Coding A 4 pins Male Mounting Bracket 2-M5×0.8×12 Hexagon Socket (3) (2) Pin Assignment Pre-assembled Washers and Bolt (Included) Input Connector 1 M12A-4 Regarding Connection Cable **Output Connector** Cables are not included. M12 Coding A 12 pins Male Please prepare the cables by referring to the table below. Cable-side Connector Shape Connected Reference: Cable Example Pin Assignment (Customer Prepared side) (Oil-resistant, Waterproof Connector) to: **Output Connector** Input Connector M12 Code A 4 pins Female SAC-4P- 5,0-PUR/M12FS (manufactured by Phoenix Contact) M12A-12

SAC-12P- 5,0-PUR/FS SCO (manufactured by Phoenix Contact)

M12 Code A 12 pins Female

Interface Diagram between Machine Tool and Receiver



Notes:

- 1. If the receiver power is turned OFF (in case of power failure), 'Unclamp 1-8' will be OFF (contact open). When power is restored, reactivate clamps or linear cylinders to resume operation.
- 2. If the clamps or linear cylinder inadvertently move from the operation ends, the corresponding unclamp signals will be turned OFF (contact open).
- ※1. When switching the clamping state reset signal (ON→OFF or OFF→ON), 'Unclamp 1-8' will be OFF (contact open). Also, the operating time of the receiver will be reset to "0".
- *2. The clamping state reset signal is required in this system to ensure proper operating detection.

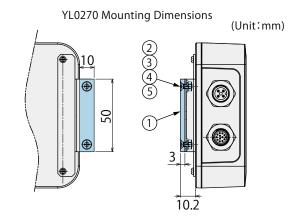


YWB

Accessory (Sold Separately : Wall-Mounted Magnet)



Model No.	No.	Name		Quantity
YL0270	1	Neodymium Magnet		2
	2	Phillips Head Countersunk Screw	M3×0.5×8	4
	3	Hex Nut	M3×0.5×8	4
	4	Spring Washer	M3 JIS	4
	(5)	Flat Washer	M3	4



System Configuration External Model No. Specifications Cautions Accessory Diagram Dimensions

Cautions for Receiver

1) Radio Regulations

There are restrictions on countries where the product can be used according to radio regulations. Please follow the regulatory requirements of each country. YWA1000-B03- \square can be used in United States.

2) Please read the instruction manual (IM-YWA001-00 E) carefully before designing and setting up. The instruction manual can be downloaded from Kosmek website (product page for LHM/LKM/LLM/YWA/YWB).

· Screen Display and Operation Method Please refer to the instruction manual for the screen display and operation method of the receiver.

Initial Connection Settings

Initial connection settings are required to connect the receiver with the wireless sensing clamp/linear cylinder. Please refer to the instruction manual for the setting method.



Initial Connection Settings Required

- Control Design and Electrical Circuit Design Please check the operation timing chart in the instruction manual and design the appropriate control and electrical circuit.
- Repeater Configuration

After completing the initial connection settings between the clamp/linear cylinder and the receiver, please proceed with the settings for the receiver and the repeater.

Please refer to the instruction manual for the configuration method.

- 3) Cautions for Repeater Installation
 - The maximum distance between the clamp and the receiver is 5 meters. Check the radio wave strength displayed on the receiver and consider the location of the repeater. (Recommended Threshold: -85dBm)
 - It is recommended to install the repeater in locations such as the upper part inside the processing machine, where it is less likely to be exposed to coolant or chips.

[Guidelines for Repeater Installation]

- When the receiver cannot be installed at a height of 2 meters or more.
- When there is a radio wave obstruction between the clamp/linear cylinder and the receiver.
- When the clamp/linear cylinder and the receiver are more than 3 meters apart.

* Please refer to P.61 for common cautions.

Notes on Handling

Maintenance/Inspection

Warrantv

Wireless Sensing Clami

Accessory

Common Cautions

Wireless Sensing Swing Clamp

LHM Wireless Sensing

Link Clamp LKM

Wireless Sensing Linear Cylinder

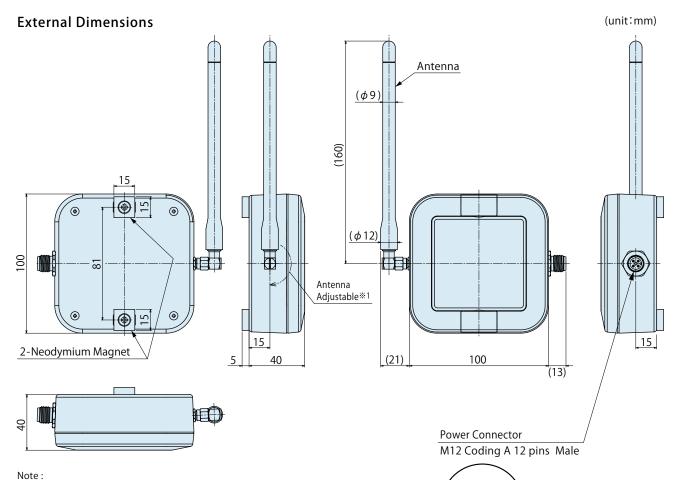
HIM

Specifications: Repeater model YWB1000-B

This repeater receives wireless signals for unclamp and stroke-end confirmation from the wireless sensing clamp (model LHM / LKM / LLM), amplifies the radio signal strength, and transmits them to the receiver (model YWA).

Model No.		YWB1000-B□	
Receiving Frequency		3 When selecting B03 : 902MHz Band	
		3 When selecting B01 : 920MHz Band	
		3 When selecting B02 : 868MHz Band	
Receiving Sensitivity		−85dBm(25°C)	
Number of Simultaneous Wireless Connections		1	
Operating Temperature and Humidity		$-10^{\circ}\text{C} \sim 60^{\circ}\text{C} \cdot 90\% \text{ or less (at } 40^{\circ}\text{C})$	
Storage Temperature and Humidity		−20°C ~ 70°C • 90% or less (at 60°C)	
Power Input	Connector	M12 Coding A 4 pins	
	Power	DC24V±20% 0.3A	
Weight		300g	
Waterproof Rating		Equivalent to IPX7	
		(when the housing is completely closed and a waterproof connector is attached)	





(2) 3

Pin Assignment **Power Connector**

M12A

*1. Loosen the nut to change the direction of the antenna.

Regarding Connection Cable

Cables are not included.

Please prepare the cables by referring to the table below.

Connected	Cable-side Connector Shape	Reference: Cable Example
to:	(Customer Prepared side)	(Oil-resistant, Waterproof Connector)
Power Connector M12 Code A 4 pins Female		SAC-4P- 5,0-PUR/M12FS (manufactured by Phoenix Contact)

Wireless

Common

Cautions

Wireless Sensing

LHM

Wireless Sensing Link Clamp LKM Wireless Sensing Linear Cylinder

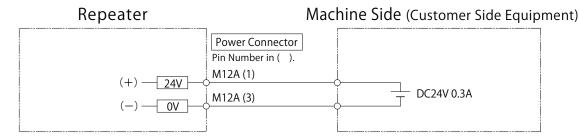
HIM

YWB

Swing Clamp

Sensing Clamp
Accessory

Interface Diagram of Repeater



Cautions for Repeater

1. Radio Regulations

There are restrictions on countries where the product can be used according to radio regulations. Please follow the regulatory requirements of each country. YWB1000-B03 can be used in United States.

2. Repeater Configuration

After completing the initial connection settings between the clamp/linear cylinder and the receiver, please proceed with the settings for the receiver and the repeater.

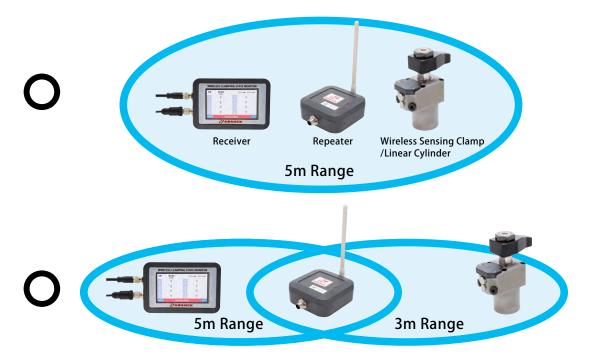
Please refer to the instruction manual of the receiver YWA (IM-YWA000-□E) for the configuration method.

3. Cautions for Repeater Installation

• The maximum distance between the clamp and the receiver is 5 meters. Check the radio wave strength displayed on the receiver and consider the location of the repeater. (Recommended Threshold: -85dBm) It is recommended to install the repeater in locations such as the upper part inside the processing machine, where it is less likely to be exposed to coolant or chips.

[Guidelines for Repeater Installation]

- When the receiver cannot be installed at a height of 2 meters or more.
- When there is a radio wave obstruction between the clamp/linear cylinder and the receiver.
- When the clamp/linear cylinder and the receiver are more than 3 meters apart.



Notes on Handling

· Maintenance/Inspection

Cautions

Notes on Handling

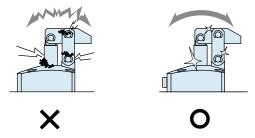
- 1) It should be operated by qualified personnel.
- Machines and devices with hydraulic and pneumatic products should be operated and maintained by qualified personnel.
- Do not operate or remove the product unless the safety protocols are ensured.
- ① Machines and devices can only be inspected or prepared when it is confirmed that the safety devices are in place.
- ② Before the product is removed, make sure that the above-mentioned safety devices are in place. Shut off the pressure and power source, and make sure no pressure exists in the air and hydraulic circuits.
- ③ After stopping the product, do not remove until the temperature drops.
- 4 Make sure there is no trouble/issue in the bolts and respective parts before restarting a machine or device.
- Do not touch a clamp (cylinder) while it is working.
 Otherwise, your hands may be injured due to clinching.



- 4) Do not disassemble or modify.
- If the equipment is taken apart or modified, the warranty will be voided even within the warranty period.

Maintenance and Inspection

- 1) Removal of the Machine and Shut-off of Pressure Source
- Before the machine is removed, make sure that safety devices and preventive devices are in place. Shut off the pressure and power source, and make sure no pressure exists in the air and hydraulic circuits.
- Make sure there is no abnormality in the bolts and respective parts before restarting.
- 2) Regularly clean the area around the piston rod.
- If it is used when the surface is contaminated with dirt, it may lead to packing seal damage, malfunctioning and fluid leakage.



- 3) If disconnecting by couplers, air bleeding should be carried out on a regular basis to avoid air mixed in the circuit.
- 4) Regularly tighten pipe line, mounting bolt, nut, snap ring, cylinder and others to ensure proper use.
- 5) Make sure the hydraulic fluid has not deteriorated.
- 6) Make sure there is a smooth action without an irregular noise.
- Especially when it is restarted after left unused for a long period, make sure it can be operated correctly.
- The products should be stored in the cool and dark place without direct sunshine or moisture.
- 8) Please contact us for overhaul and repair.

Installation Notes (For Hydraulic Series) Hydraulic Fluid List Notes on Hyd. Cylinder Speed Control Circuit Notes on Handling Notes on Han

Warranty

- 1) Warranty Period
- The product warranty period is 18 months from shipment from our factory or 12 months from initial use, whichever is earlier.
- 2) Warranty Scope
- If the product is damaged or malfunctions during the warranty period due to faulty design, materials or workmanship, we will replace or repair the defective part at our expense.
 Defects or failures caused by the following are not covered.
- ① If the stipulated maintenance and inspection are not carried out.
- ② If the product is used while it is not suitable for use based on the operator's judgment, resulting in defect.
- ③ If it is used or operated in an inappropriate way by the operator.

 (Including damage caused by the misconduct of the third party.)
- ④ If the defect is caused by reasons other than our responsibility.
- ⑤ If repair or modifications are carried out by anyone other than Kosmek, or without our approval and confirmation, it will void warranty.
- ⑥ Other caused by natural disasters or calamities not attributable to our company.
- Parts or replacement expenses due to parts consumption and deterioration.
 (Such as rubber, plastic, seal material and some electric components.)

Damages excluding from direct result of a product defect shall be excluded from the warranty.

Wireless Sensing Clamp

Accessory

Common

Cautions

Installation Notes (For Hyd. Series)

Hydraulic Fluid List

Notes on Hyd. Cylinder

Speed Control Circuit

Notes on Handlin

Maintenance

Warranty