New

Wireless Sensing Clamp
Hydraulic Single Acting
Swing Clamp / Link Clamp

Hyd. Lock / Spring Release

Swing Clamp
model **LGM**

Link Clamp
model **LJM**

Wirelessly Detect Unclamp Position

No External Power Supply

Required for Sensor

KOSMEK
Harmony in Innovation

NEW

Hyd. Lock / Spring Release

PAT.P.

Wireless Sensing Clamp

Hydraulic Single Acting Swing Clamp
model **LGM**

Hydraulic Single Acting Link Clamp
model **LJM**

Wirelessly Detect Unclamp Position

No External Power Supply Required for Sensor

Individual Detection

Separate unclamp detection is possible for each clamp.

Waterproof Rating

Equivalent to IPX7

※ Shows the protection level of the sensor.

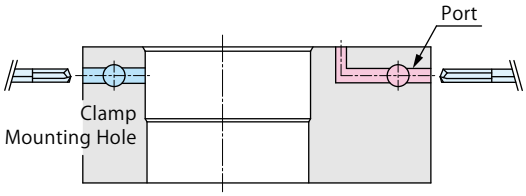
Response Time
0.1sec.

Quick Response※

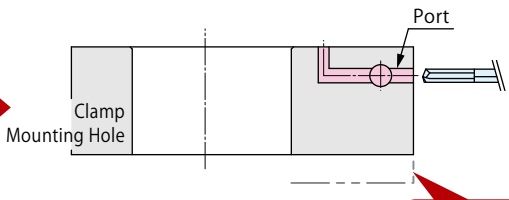
※ Compared with our conventional air sensing clamps.

Minimized Number of Ports

Solution to fixture port shortage.



With Wireless Sensing



Conventional Fixture※：Multiple Ports

Hydraulic Port × 1, Air Port × 1, (Vent Port × 1)

※Using our conventional air sensing clamp (model LJV)

Air port is not required.

Hydraulic Port × 1

Enables a thinner and lighter fixture.

Lower Design・Fixture Cost

Design & machining costs for sensing ports are not required.

※ Image compared with our conventional air sensing clamps.

With Wireless Sensing

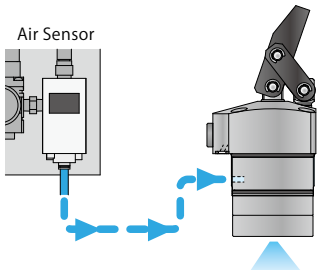
Conventional※ sensing function needed design and machining costs for ports.

Fixture is simplified.

※ For conventional models, please see the “Changes in Sensing Clamps” .

Zero Air Consumption

Detect unclamp position via wireless communication.

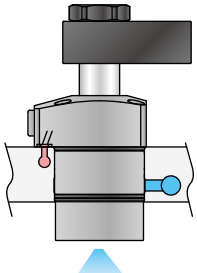
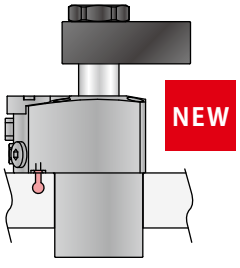


With Wireless Sensing

Consumes air for detection.

※Using our conventional air sensing clamp

Detects wirelessly, zero air consumption.

Changes in Sensing Clamps	Conventional Air Sensor Model	Wireless Sensing Model
Model		 NEW **No Air Port**
Air Consumption	Low	**Zero**

Please contact us when considering the wireless sensing clamp.

Wireless Sensing Swing Clamp

Hydraulic Single Action

Model LGM

Hyd. Lock / Spring Release

Wirelessly Detect Unclamp Position. Number of Ports is Reduced.

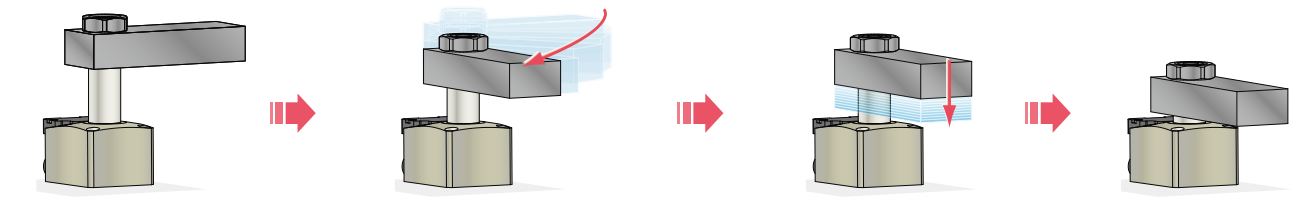
No External Power Supply Required for Sensor

PAT.P.

Detects unclamp position wirelessly.

Receiver	Repeater	Clamp
Position : Outside Machine	Position : Near Fixture Inside the Processing Machine	Position : Fixture

Action Description



Before Swing (Unclamped State)

The lever descends as it swings. (Swing Stroke Range)

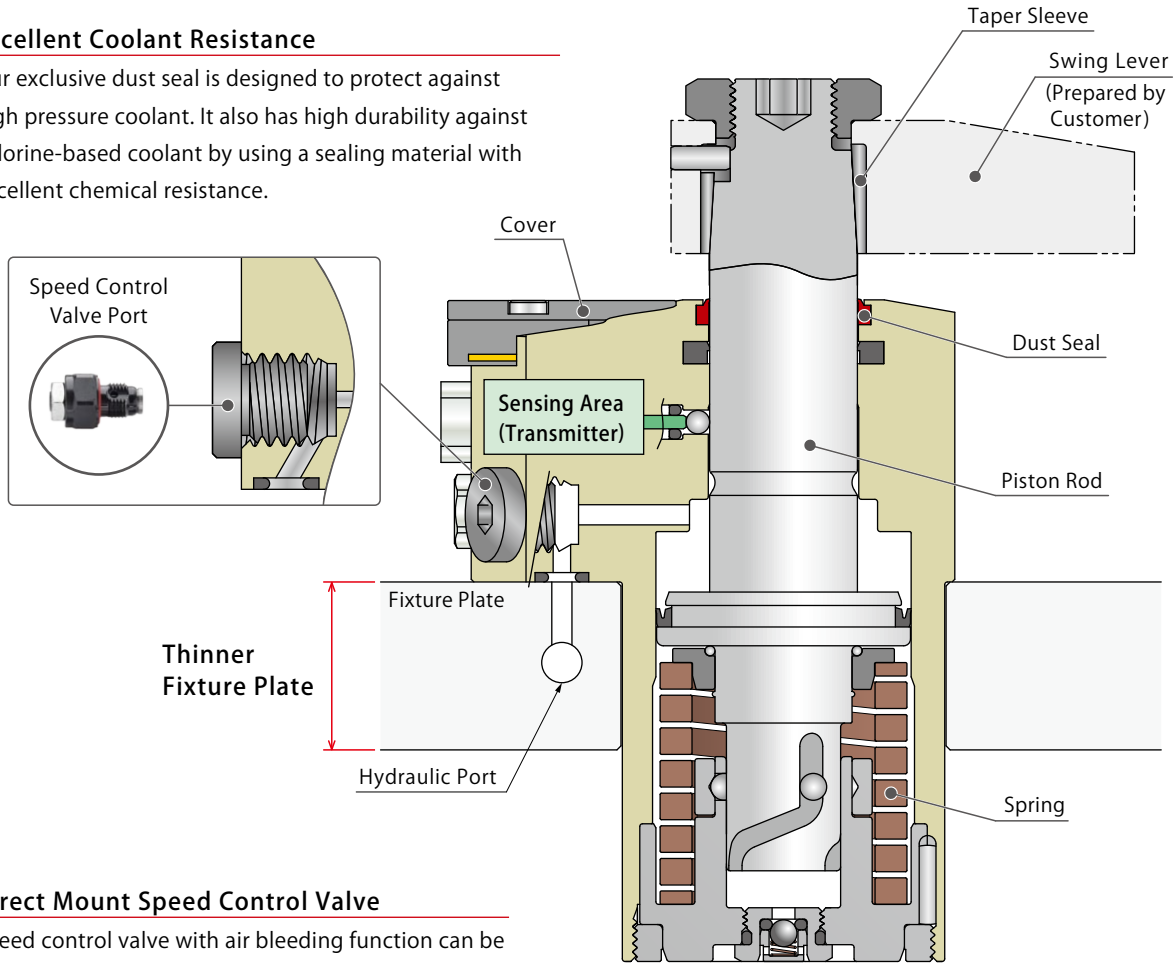
After swing completion, it descends vertically. (Vertical Stroke Range)

Action completed (Clamped State)

Cross Section ※ This drawing shows Model LGM-C□-B□.

Excellent Coolant Resistance

Our exclusive dust seal is designed to protect against high pressure coolant. It also has high durability against chlorine-based coolant by using a sealing material with excellent chemical resistance.

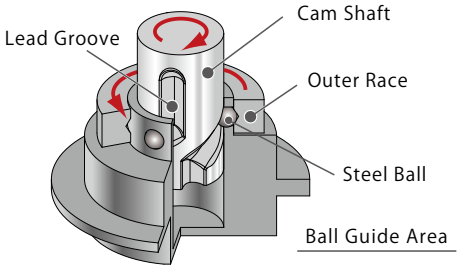


Direct Mount Speed Control Valve

Speed control valve with air bleeding function can be directly mounted to the product.
(Speed control valve is sold separately.)

High Speed and High Endurance with Rotation Mechanism

The resistance created by the swing action is minimized by having the outer race rotates in accordance with the steel ball movement. High endurance is achieved by enlarging rod diameter which decreases torque and by using bigger steel balls and making the lead groove wider. (Position repeatability for swing is within ±0.5°.)

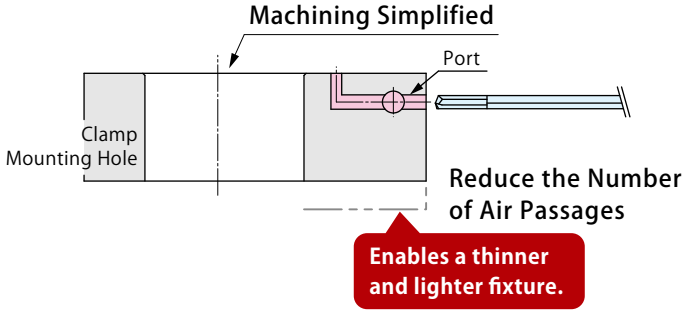


Zero Air Consumption

Detects unclamp position via wireless communication. Unlike our conventional air sensing clamps, air for action confirmation is not required.

Minimized Number of Ports・Simple Machining

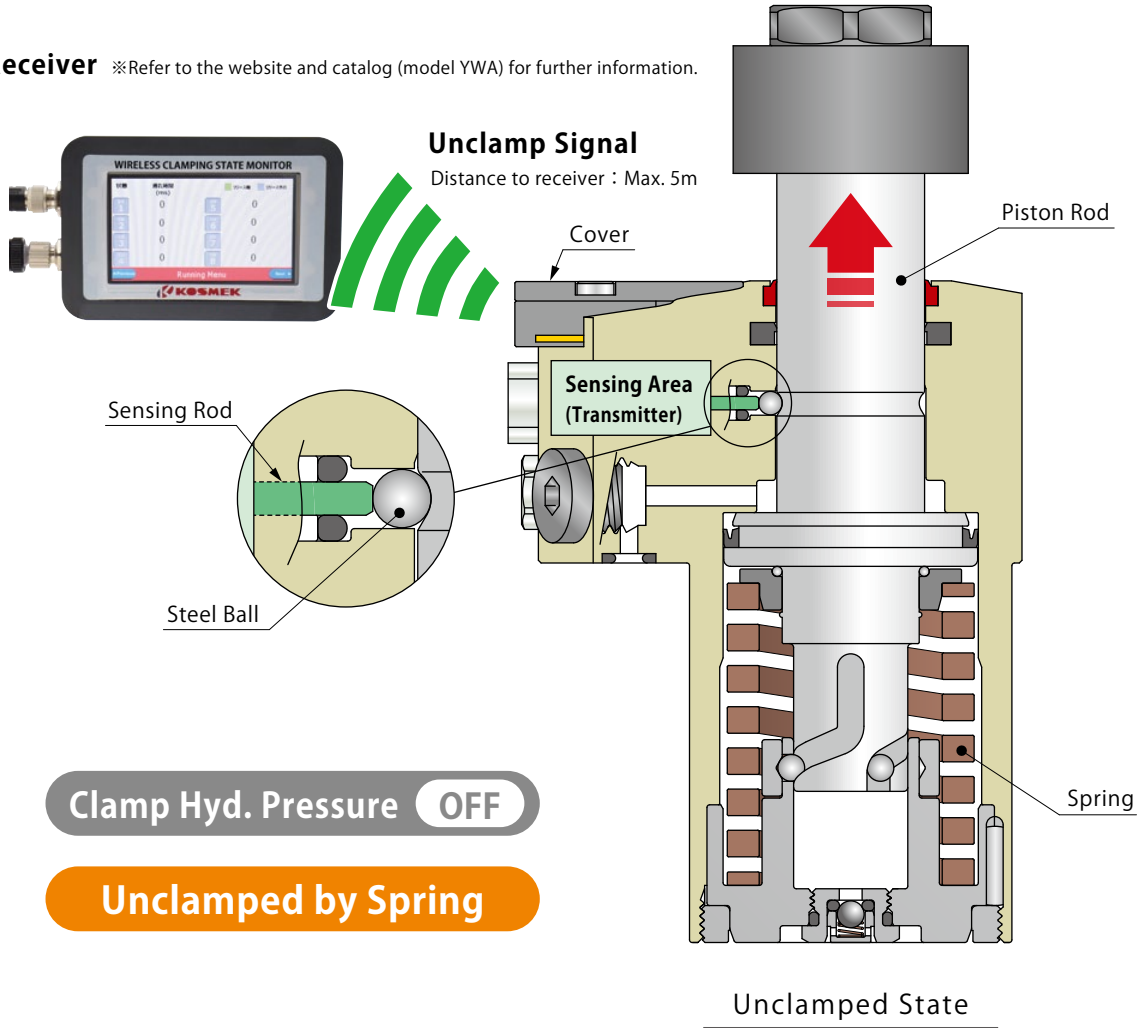
Integrating ports allows for reducing the number of ports for Rotary Joint and machining for air passage of fixture plate, and simplifying the machining of mounting hole, etc.



Action Description (Internal Structure) ※ The figure shows Model LGM-C□-B□.

Unclamp

Receiver ※Refer to the website and catalog (model YWA) for further information.



■ Unclamp (During Hydraulic Pressure Supply OFF)

When hydraulic supply is turned off, the piston rod ascends vertically by spring (Vertical Stroke Range).

↓

After vertical action is completed, the piston rod ascends as it swings.

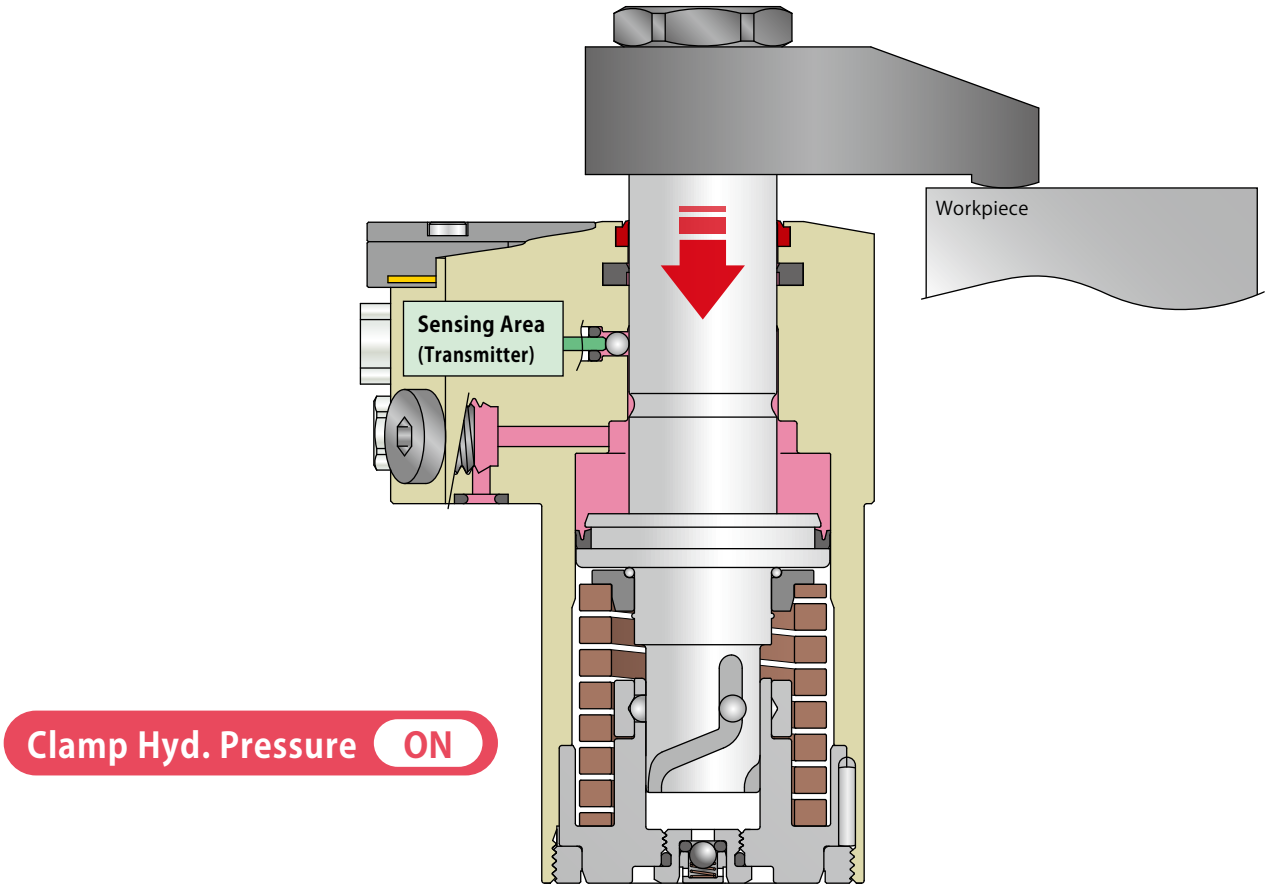
↓

When the piston rod pushes the sensing rod via the steel ball at the end of unclamp stroke, an unclamp signal is transmitted from the sensing area.

Connecting Multiple Wireless Sensing Clamps

When using multiple wireless sensing clamps, provide an unclamp operating time difference of 100msec (0.1 sec.) or more.
Please check the operating time at the receiver, and adjust the operating time with the speed control valve if it is within 100msec.
Otherwise, signals cannot be received properly due to radio interference.

Clamp



Clamped State

■ Clamp (During Hydraulic Pressure Supply to Clamping Port)

The piston rod descends as it swings (Swing Stroke Range).

↓

After swing action is completed, the piston rod descends vertically to clamp the workpiece.

※ Make sure to clamp a workpiece within the vertical stroke range.

Model No. Indication

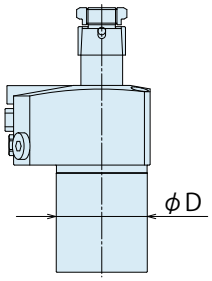
LGM 048 0 - C R - B03

1 2 3 4 5

1 Body Size

048 : ϕD=48mm
055 : ϕD=55mm
065 : ϕD=65mm
075 : ϕD=75mm

※ Outer diameter (ϕD) of the cylinder.



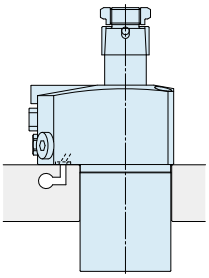
2 Design No.

0 : Revision Number

3 Piping Method

C : Gasket Option (With G Thread Plug)

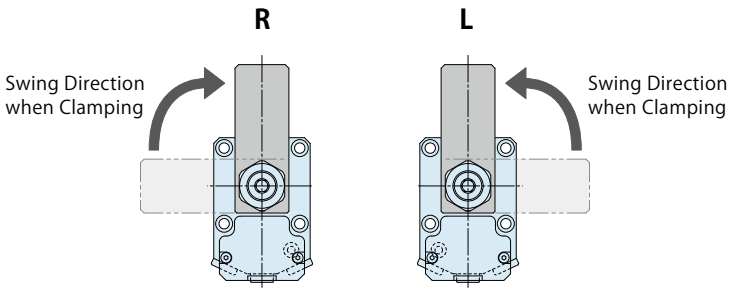
※ Speed control valve (BZL) is sold separately.
Please refer to P. 35.



With G Thread Plug
Able to attach speed control valve

4 Swing Direction when Clamping

R : Clockwise
L : Counter-Clockwise



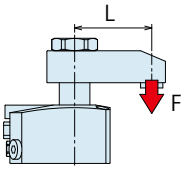
5 Available Country : Frequency

※ There are restrictions on countries where the product can be used according to radio regulations. Please follow the regulatory requirements of each country.

B03 : United States
B01 : Japan
B02 : China

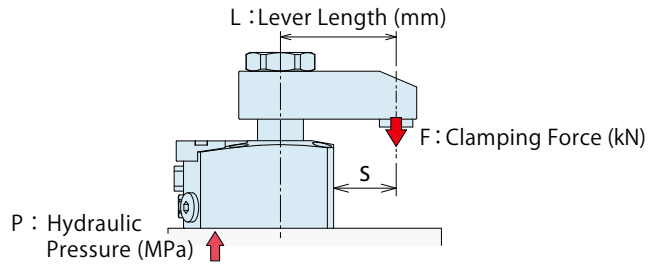
Specifications

Model No.			LGM0480-C□-B□	LGM0550-C□-B□	LGM0650-C□-B□	LGM0750-C□-B□
Cylinder Area for Clamping		cm^2	7.5	10.3	14.2	21.3
Cylinder Inner Diameter ※1		mm	38	44	52	63
Rod Diameter ※1		mm	22	25	30	35.5
Clamping Force ※2 (Calculation Formula)		kN	$F=\frac{P-1.09}{1.45+0.0044\times L}$	$F=\frac{P-1.22}{1.07+0.0033\times L}$	$F=\frac{P-1.22}{0.77+0.0020\times L}$	$F=\frac{P-0.97}{0.51+0.0012\times L}$
Full Stroke		mm	14	16.5	18	21.5
Swing Stroke (90°)		mm	6	6.5	8	9.5
Vertical Stroke		mm	8	10	10	12
Swing Angle Accuracy			90° ±3°			
Swing Complete Position Repeatability			±0.5°			
Return Spring Force	max.	kN	0.89	1.41	1.75	2.26
	min.		0.59	0.83	1.08	1.43
Max. Operating Pressure		MPa	7			
Min. Operating Pressure ※3		MPa	2.5			
Withstanding Pressure		MPa	10.5			
Operating Temperature		℃	0 ~ 70 (Sensing Area: ~ 60℃)			
Usable Fluid			General Hydraulic Oil Equivalent to ISO-VG-32			
Wireless Sensing (Unclamp Confirmation)	Frequency		5 When selecting **B03**：902MHz Band 5 When selecting **B01**：920MHz Band 5 When selecting **B02**：868MHz Band			
	Distance to Receiver		Max. 5m ※4			
	Sensing Position		ON from 15° swing angle before the unclamp end stroke.			
	Waterproof Rating		Equal to IPX7 (When the cover of the sensing area is completely closed.)			



Notes : ※1. Clamping force cannot be calculated from the cylinder inner diameter and rod diameter. Please refer to the clamping force calculation formula and the clamping force curve.
※2. F：Clamping Force (kN), P：Supply Hydraulic Pressure (MPa), L：Distance between the piston center and the clamping point (mm).
※3. Minimum pressure to operate the clamp without load.
※4. The maximum distance when there is no obstruction. Check the radio wave strength displayed on the receiver and consider the installation of the repeater. (Recommended Threshold Value：-85dBm)
1. Please refer to the external dimensions for cylinder capacity and product weight.

Clamping Force Curve



Applicable Model

LGM □ **0** - **C** R L - B03 B01 B02

1 **Body Size**

(Ex.) In case of LGM0480 :
When supply hydraulic pressure P is 5.0MPa and lever length L is 50mm, clamping force becomes about 2.3kN.

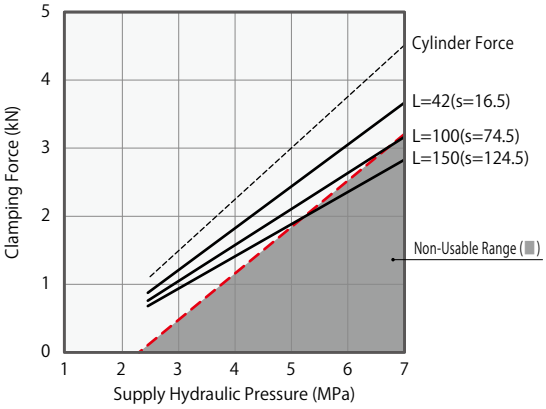
Notes :

1. Tables and graphs show the relationship between the clamping force (kN) and supply hydraulic pressure (MPa).
2. Cylinder force (when L=0) cannot be calculated from the formula of clamping force.
3. Lever with a large inertia sometimes does not work depending on supply hydraulic pressure, lever mounting position, etc.
4. Values in below charts indicate clamping force when the lever locks a workpiece in horizontal position.
5. The clamping force varies depending on the lever length. Set the suitable supply hydraulic pressure based on the lever length.
6. Clamping force in the non-usable range may cause damage and fluid leakage.
7. The tables and graphs are only for reference. The exact results should be calculated based on the clamping force calculation formula.

※1. F：Clamping Force (kN), P：Supply Hydraulic Pressure (MPa), L：Lever Length (mm).

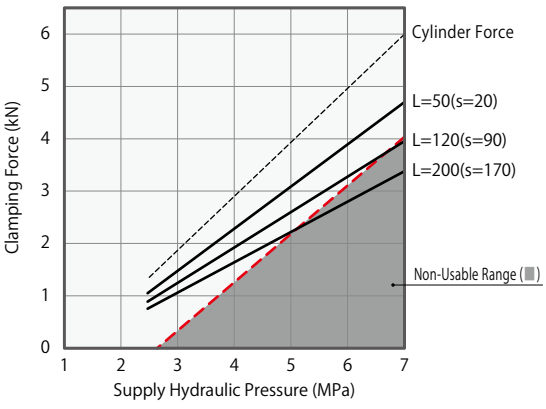
LGM0480 Clamping Force Calculation Formula ※1 (kN) $F = (P-1.09) / (1.45+0.0044\times L)$

Hydraulic Pressure (MPa)	Cylinder Force (kN)	Clamping Force (kN) Lever Length L (mm) L=50	L=60	L=70	L=80	L=100	L=120	L=140	L=150	Max. Lever Length (L) (mm)
7	4.4	3.5	3.5	3.4	3.3					89
6.5	4.0	3.2	3.2	3.1	3.0	2.9				100
6	3.7	2.9	2.9	2.8	2.7	2.6				114
5.5	3.3	2.6	2.6	2.5	2.5	2.3	2.2			132
5	2.9	2.3	2.3	2.2	2.2	2.1	2.0	1.9	1.9	150
4.5	2.5	2.0	2.0	1.9	1.9	1.8	1.7	1.7	1.6	150
4	2.2	1.7	1.7	1.7	1.6	1.5	1.5	1.4	1.4	150
3.5	1.8	1.4	1.4	1.4	1.3	1.3	1.2	1.2	1.1	150
3	1.4	1.1	1.1	1.1	1.1	1.0	1.0	0.9	0.9	150
2.5	1.0	0.8	0.8	0.8	0.8	0.8	0.7	0.7	0.7	150
Max. Operating Pressure (MPa)		7.0	7.0	7.0	7.0	6.5	5.8	5.3	5.1	



LGM0550 Clamping Force Calculation Formula ※1 (kN) $F = (P-1.22) / (1.07+0.0033\times L)$

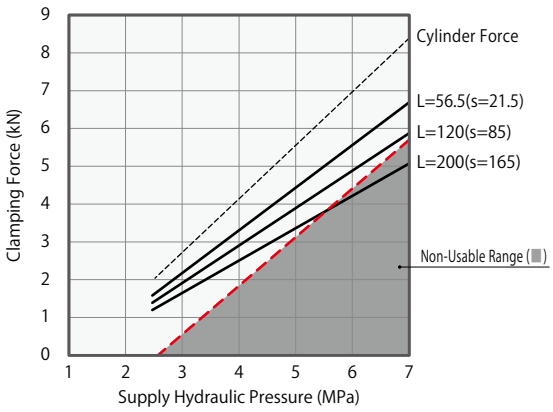
Hydraulic Pressure (MPa)	Cylinder Force (kN)	Clamping Force (kN) Lever Length L (mm) L=50	L=60	L=80	L=100	L=120	L=140	L=160	L=200	Max. Lever Length (L) (mm)
7	5.9	4.7	4.6	4.3	4.1					102
6.5	5.4	4.3	4.2	4.0	3.8					115
6	4.9	3.9	3.8	3.6	3.4	3.3				132
5.5	4.4	3.5	3.4	3.2	3.1	2.9	2.8			156
5	3.9	3.1	3.0	2.8	2.7	2.6	2.5	2.4		188
4.5	3.3	2.7	2.6	2.5	2.3	2.2	2.1	2.1	1.9	200
4	2.8	2.3	2.2	2.1	2.0	1.9	1.8	1.7	1.6	200
3.5	2.3	1.9	1.8	1.7	1.6	1.6	1.5	1.4	1.3	200
3	1.8	1.4	1.4	1.3	1.3	1.2	1.2	1.1	1.0	200
2.5	1.3	1.0	1.0	1.0	0.9	0.9	0.8	0.8	0.7	200
Max. Operating Pressure (MPa)		7.0	7.0	7.0	7.0	6.4	5.8	5.4	4.9	



LGM0650

Clamping Force Calculation Formula ※1 (kN) $F = (P-1.22) / (0.77+0.0020 \times L)$

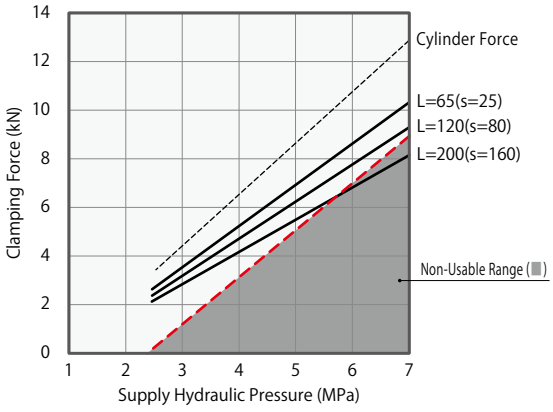
Hydraulic Pressure (MPa)	Cylinder Force (kN)	Clamping Force (kN) Lever Length L (mm) L=50	L=60	L=80	L=100	L=120	L=140	L=160	L=200	Max. Lever Length (L) (mm)
7	8.3	6.6	6.5	6.2	6.0	5.7				126
6.5	7.6	6.1	5.9	5.7	5.4	5.2	5.0			142
6	6.9	5.5	5.4	5.1	4.9	4.7	4.6	4.4		163
5.5	6.2	4.9	4.8	4.6	4.4	4.2	4.1	3.9		191
5	5.5	4.3	4.3	4.1	3.9	3.7	3.6	3.5	3.2	200
4.5	4.8	3.8	3.7	3.5	3.4	3.3	3.1	3.0	2.8	200
4	4.1	3.2	3.1	3.0	2.9	2.8	2.7	2.6	2.4	200
3.5	3.4	2.6	2.6	2.5	2.4	2.3	2.2	2.1	2.0	200
3	2.6	2.1	2.0	1.9	1.8	1.8	1.7	1.6	1.5	200
2.5	1.9	1.5	1.4	1.4	1.3	1.3	1.2	1.2	1.1	200
Max. Operating Pressure (MPa)		7.0	7.0	7.0	7.0	7.0	6.6	6.1	5.4	



LGM0750

Clamping Force Calculation Formula ※1 (kN) $F = (P-0.97) / (0.51+0.0012 \times L)$

Hydraulic Pressure (MPa)	Cylinder Force (kN)	Clamping Force (kN) Lever Length L (mm) L=50	L=60	L=80	L=100	L=120	L=140	L=160	L=200	Max. Lever Length (L) (mm)
7	12.8	10.6	10.4	10.0	9.6	9.2				134
6.5	11.7	9.7	9.5	9.1	8.8	8.5	8.2			150
6	10.7	8.8	8.6	8.3	8.0	7.7	7.4	7.2		171
5.5	9.6	8.0	7.8	7.5	7.2	6.9	6.7	6.5	6.0	199
5	8.6	7.1	6.9	6.7	6.4	6.2	5.9	5.7	5.4	200
4.5	7.5	6.2	6.1	5.8	5.6	5.4	5.2	5.0	4.7	200
4	6.4	5.3	5.2	5.0	4.8	4.6	4.5	4.3	4.0	200
3.5	5.4	4.4	4.4	4.2	4.0	3.9	3.7	3.6	3.4	200
3	4.3	3.6	3.5	3.4	3.2	3.1	3.0	2.9	2.7	200
2.5	3.2	2.7	2.6	2.5	2.4	2.3	2.3	2.2	2.0	200
Max. Operating Pressure (MPa)		7.0	7.0	7.0	7.0	7.0	6.8	6.3	5.5	

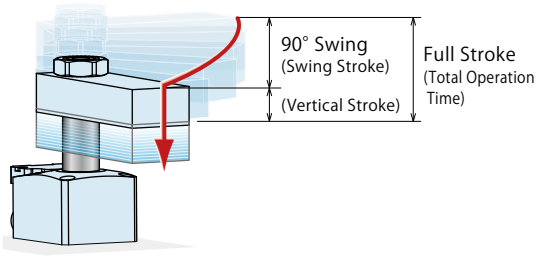


Allowable Swing Time Graph

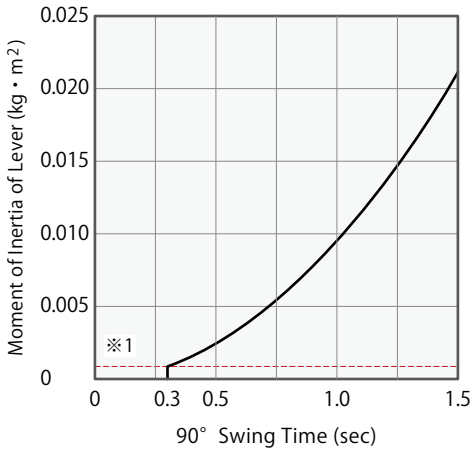
Adjustment of Swing Time

The graph shows allowable swing time against the moment of inertia of a lever.
An operation time should be longer than the operation time shown in the graph.

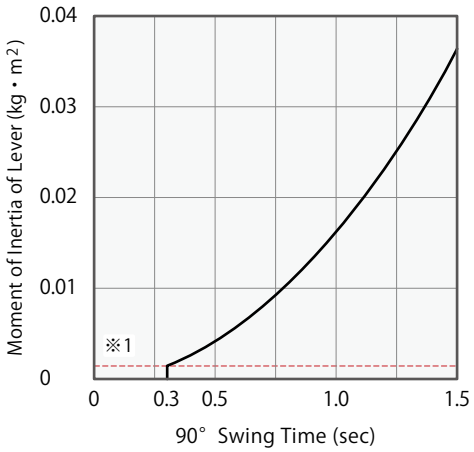
Excessive action speed can reduce stopping accuracy and damage internal components.



LGM0480



LGM0550



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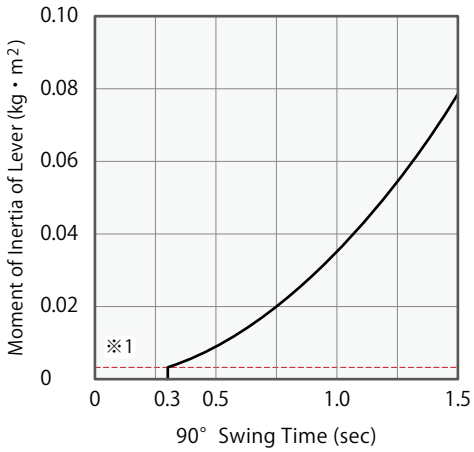
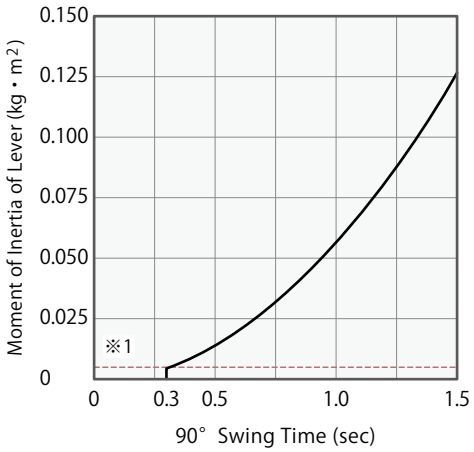


LGM0750



Notes :

※1. It shows the moment of inertia of material lever (LZ□-LE2).

※2. For any moment of inertia of a lever, the minimum 90° swing time should be 0.3 sec or more.

1. The graph shows the allowable action time in regard to the moment of inertia of lever when the piston rod operates at constant speed.
2. There may be no lever swing action with large inertia depending on supply hydraulic pressure, oil flow and lever mounting position.
3. Please adjust the 90° swing time against the moment of inertia of lever to be longer than the indicated time in the above graphs.
4. For speed adjustment of clamp lever, please use meter-out flow control valve.
   In case of meter-in control, the clamp lever may be accelerated by its own weight during swinging motion (clamp mounted horizontally) or the piston rod may be moving too fast. Please refer to P.40 for speed control of the hydraulic cylinder.
5. Excessive swing speed can reduce stopping accuracy and damage the internal components.
6. Please contact us if operational conditions differ from those shown on the graphs.

(How to read the allowable swing time graph)

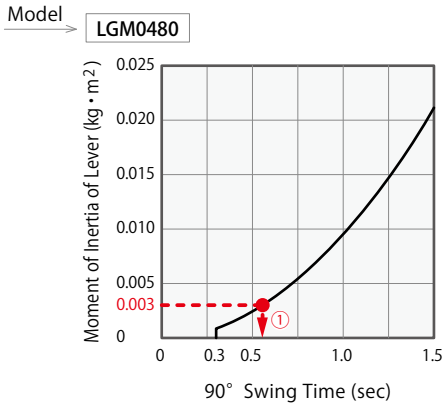
In case of LGM0480

The moment of inertia of a lever : 0.003kg・m²

① 90° Swing Time : About 0.56 sec or more

② Total Operation Time : About 1.30 sec or more

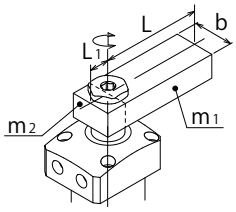
1. The total operation time on the graph represents the allowable operation time when fully stroked.
2. The total operation time should be calculated with the calculation formula.



How to Calculate the Moment of Inertia (Estimated)

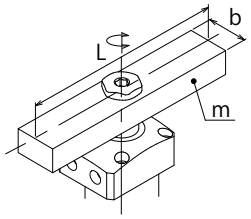
I : Moment of Inertia (kg・m²) L,L_1,L_2,K,b : Length (m) m,m_1,m_2,m_3 : Mass (kg)

① For a rectangular plate (cuboid), the rotating shaft is vertically on one side of the plate.



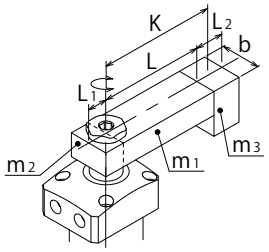
$$I = m_1 \frac{4L^2+b^2}{12} + m_2 \frac{4L_1^2+b^2}{12}$$

② For a rectangular plate (cuboid), the rotating shaft is vertically on the gravity center of the plate.



$$I = m \frac{L^2+b^2}{12}$$

③ Load is applied on the lever front end.



$$I = m_1 \frac{4L^2+b^2}{12} + m_2 \frac{4L_1^2+b^2}{12} + m_3K^2 + m_3 \frac{L_2^2+b^2}{12}$$

Calculation Formula of Total Operation Time

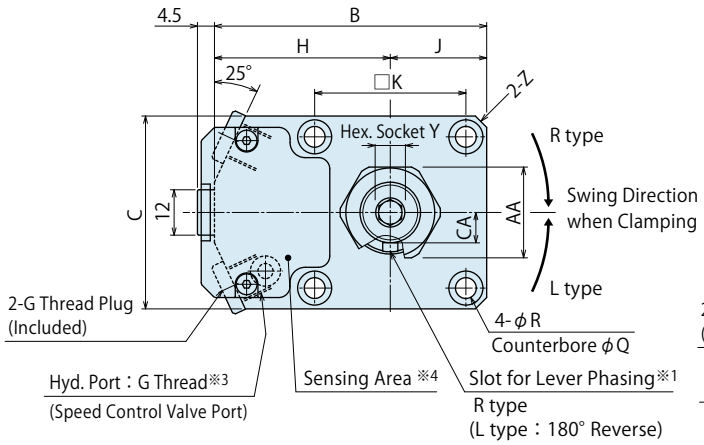
$$\text{Total Operation Time (sec)} = 90^\circ \text{ Swing Time (sec)} \times \frac{\text{Full Stroke (mm)}}{\text{Swing Stroke (mm)}}$$

External Dimensions

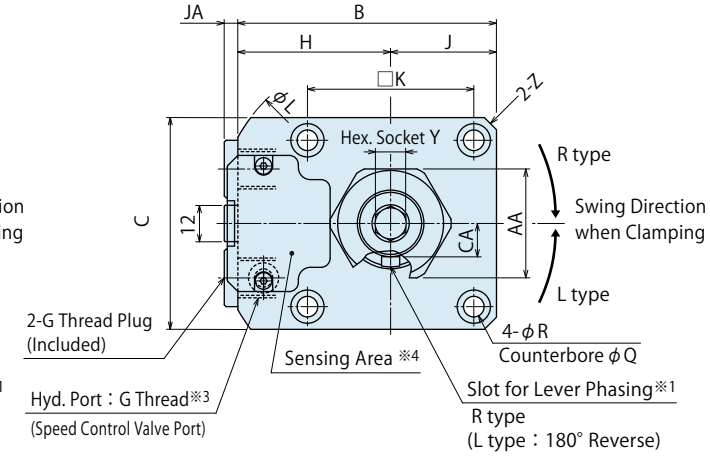
C：Gasket Option (With G Thread Plug)

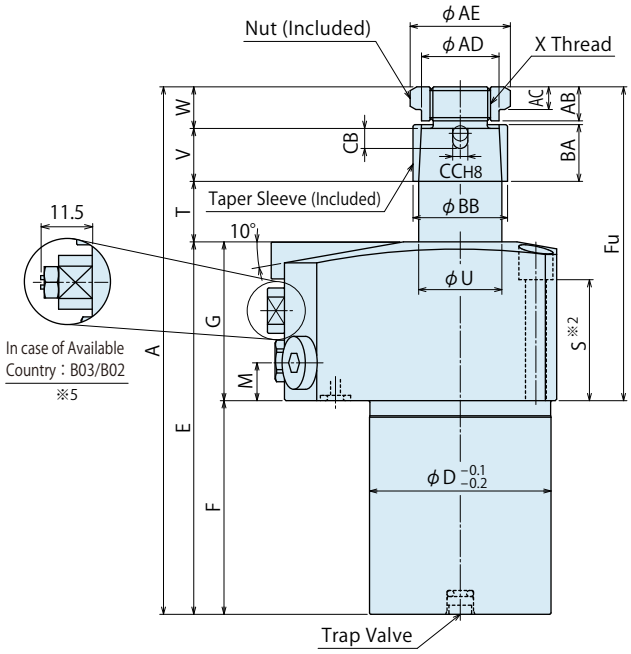
※ The drawing shows the unclamped state of LGM-CR-B□.

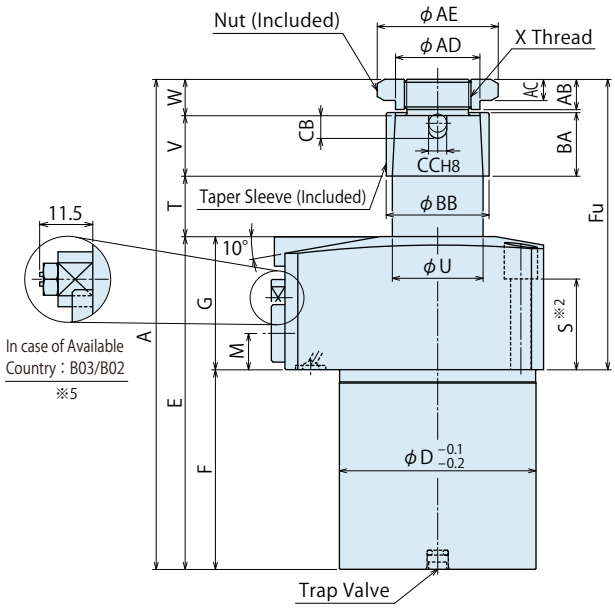
LGM0480-C□-B□ / LGM0550-C□-B□

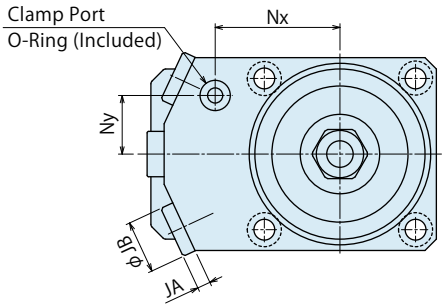


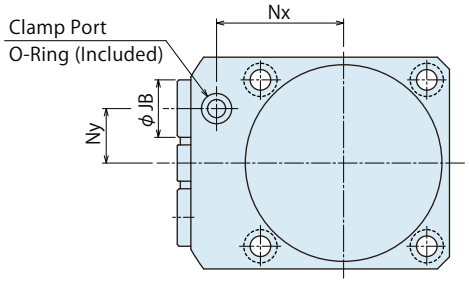
LGM0650-C□-B□ / LGM0750-C□-B□











Notes :

※1. The slot for lever phasing faces the port side when clamped.

※2. Mounting bolts are not provided. Please prepare them according to the mounting height referring to dimension 'S'.

※3. Speed control valve is sold separately. Please refer to P.35. It is necessary to provide an unclamp operation time difference of at least 100 msec. For adjusting the unclamp operation, please use a speed control valve (meter-out).

※4. Do not cover the top surface of the sensing area with metal objects (chips, sludge, etc.). It may obstruct radio wave transmission.

※5. Please refer to P.17 “Notes for Design 2) Radio Regulations” .

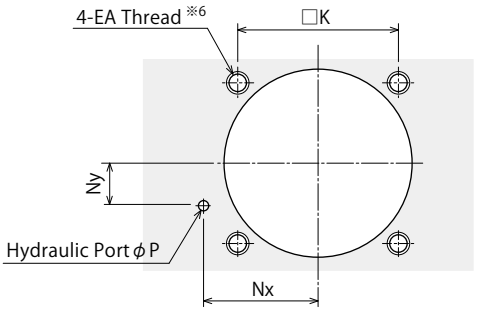
Model No. Indication

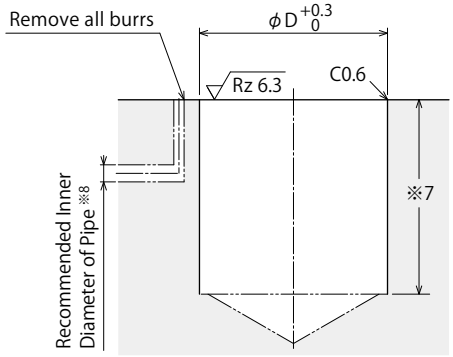
(Format Example：LGM0550-CR-B03、LGM0750-CL-B03)

LGM 048 0 – C R L – B03 B01 B02

1 Body Size
2 Design No.
3 Piping Method
4 Swing Direction when Clamping
5 Available Country：Frequency

Machining Dimensions of Mounting Area





Notes：

※6. EA tapping depth of the mounting bolt should be decided according to the mounting height referring to dimension 'S'.

※7. The depth of the body mounting hole ϕD should be decided according to the mounting height referring to dimension 'F'.

External Dimensions and Machining Dimensions for Mounting

(mm)

Model No.	LGM0480-C□-B□	LGM0550-C□-B□	LGM0650-C□-B□	LGM0750-C□-B□
Full Stroke	14	16.5	18	21.5
Swing Stroke (90°)	6	6.5	8	9.5
Vertical Stroke	8	10	10	12
A	139.5	154	162	185.5
B	72	78	85.5	93.3
C	51	60	70	80
D	48	55	65	75
E	98.5	103.5	110	122
F	56.5	61.5	66	78
Fu	83	92.5	96	107.5
G	42	42	44	44
H	46.5	48	50.5	53.3
J	25.5	30	35	40
K	40	47	55	63
L	–	–	116	122
M	10	10	12	12
Nx	33	34.5	42	45
Ny	15.5	16	18	19
P	3	3	5	5
Q	9	10.5	11	14
R	5.5	6.8	6.8	9
S	32	30	30	27
T	16	18.5	20	23.5
U	22	25	30	35.5
V	14	20	20	26
W	11	12	12	14
X (Nominal × Pitch)	M16×1.5	M18×1.5	M22×1.5	M28×1.5
Y	6	8	10	10
Z (Chamfer)	C3	C3	C4	C5
AA	24	30	36	41
AB	9	10	10	12
AC	6	7	7	8
AD	20.5	22.9	27.9	32.8
AE	26.5	33	40	45
BA	15	21	21	27
BB	25	28	34	40
CA	8	9	11	14
CB	5.3	5.3	7.5	7.5
CC	4 +0.018 0	4 +0.018 0	6 +0.018 0	6 +0.018 0
EA (Nominal × Pitch)	M5×0.8	M6×1	M6×1	M8×1.25
JA	3.5	3.5	4.5	4.5
JB	14	14	19	19
Hyd. Port：G Thread	G1/8	G1/8	G1/4	G1/4
O-ring	OR NBR-90 P5-N	OR NBR-90 P5-N	OR NBR-90 P7-N	OR NBR-90 P7-N
Inner Diam. of Pipe ※8	ϕ6	ϕ6	ϕ8	ϕ8
Clamp Cylinder Capacity cm³	10.6	17	25.5	45.7
Weight ※9 kg	1.7	2.3	3.5	4.6

Notes：

※8. This is for reference. Adjust it depending on the number of clamps and/or the length of the pipe.

※9. It shows the weight of single swing clamp including taper sleeve and nut.

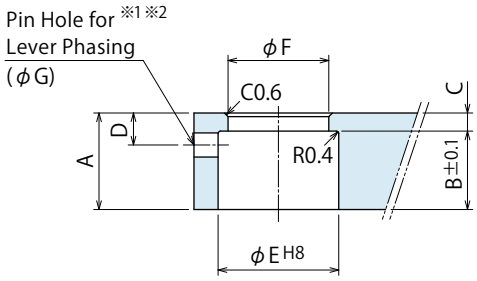
Taper Lock Lever Design Dimensions

※ Reference for designing a taper lock swing lever.

Corresponding Model No.

LGM [ ] 0 - C [R / L] - [B03 / B01 / B02]

1 Body Size



(mm)

Corresponding Model No.	LGM0480-C□-B□	LGM0550-C□-B□	LGM0650-C□-B□	LGM0750-C□-B□
A	19	25	25	32
B	15	21	21	27
C	4	4	4	5
D	6.3	6.3	7.5	8.5
E	$25^{+0.033}_{0}$	$28^{+0.033}_{0}$	$34^{+0.039}_{0}$	$40^{+0.039}_{0}$
F	$20.6^{+0.15}_{0}$	$23^{+0.15}_{0}$	$28^{+0.15}_{0}$	$32.9^{+0.20}_{0}$
G	4	4	6	6

Notes :

1. Swing lever should be designed with its length according to performance curve.
2. If the swing lever is not in accordance with the dimension shown above, performance may be degraded and damage can occur.

※1. The pin hole (φG) for determining the lever phase should be added, if necessary.

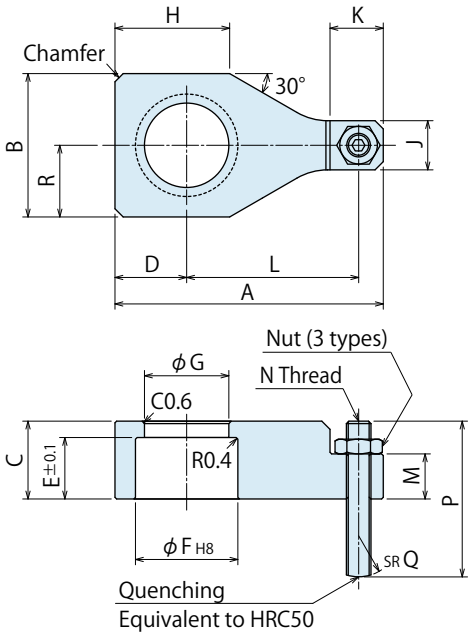
※2. Phasing pin is not included. Prepare it separately.

Accessory：Material Swing Lever for Taper Lock Lever

Model No.

LZ 048 0 – LE1

- 048: Size (Refer to the table.)
- 0: Design No. (Revision Number)



(mm)

Model No.	LZ0481-LE1※3	LZ0550-LE1	LZ0650-LE1	LZ0750-LE1
Corresponding Model No.	LGM0480	LGM0550	LGM0650	LGM0750
A	65.5	77	91.5	105
B	35	38	50	58
C	19	25	25	32
D	17.5	19	25	29
E	15	21	21	27
F	$25^{+0.033}_{0}$	$28^{+0.033}_{0}$	$34^{+0.039}_{0}$	$40^{+0.039}_{0}$
G	$20.6^{+0.15}_{0}$	$23^{+0.15}_{0}$	$28^{+0.15}_{0}$	$32.9^{+0.20}_{0}$
H	28	34	40	47
J	12	17	19	22
K	13	17	22	25
L	42	50	56.5	65
M	11	15	13	16
N	M6×1	M8×1.25	M10×1.5	M12×1.75
P	38	42	47	52
Q	10	15	20	30
R	17.5	19	25	29
Chamfer	C1	C1	C3	C4

Notes：

1. Material : S45C　Surface Finishing：Alkaline Blackening
2. When determining the phase, refer to taper lock lever design dimensions for each model for the additional machining.

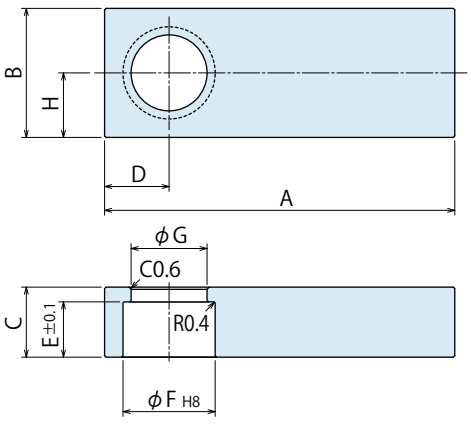
※3. The design number is 1 only for LZ048.

Accessory：Material Swing Lever for Taper Lock Lever

Model No.

LZ 048 0 – LE2

- 048: Size (Refer to the table.)
- 0: Design No. (Revision Number)



(mm)

Model No.	LZ0481-LE2※4	LZ0550-LE2	LZ0650-LE2	LZ0750-LE2
Corresponding Model No.	LGM0480	LGM0550	LGM0650	LGM0750
A	95	100	120	125
B	35	38	50	58
C	19	25	25	32
D	17.5	19	25	29
E	15	21	21	27
F	$25^{+0.033}_{0}$	$28^{+0.033}_{0}$	$34^{+0.039}_{0}$	$40^{+0.039}_{0}$
G	$20.6^{+0.15}_{0}$	$23^{+0.15}_{0}$	$28^{+0.15}_{0}$	$32.9^{+0.20}_{0}$
H	17.5	19	25	29

Notes：

1. Material : S45C　Surface Finishing：Alkaline Blackening
2. If necessary, the front end should be additionally machined and finished.
3. When determining the phase, refer to taper lock lever design dimensions for each model for the additional machining.

※4. The design number is 1 only for LZ048.

Cautions

Notes for Design

1) Check Specifications

- Please use each product according to the specifications.

2) Radio Regulations

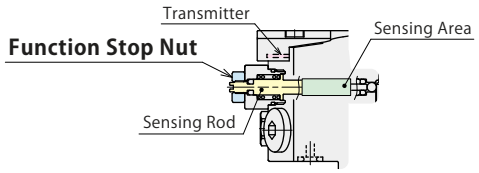
- There are restrictions on countries where the product can be used according to radio regulations. Please follow the regulatory requirements of each country. LGM□-C□-B03 can be used in United States.

Regarding LGM□-C□-B03/B02

- At shipment, the signal transmission is in a disabled state, with the function stop nut attached. When enabling signal transmission, please remove the "function stop nut" before use.

Signal Transmission Function OFF Setting

- If it is absolutely necessary to operate this product in a country other than the available country, please disable the signal transmission function using the following settings.
  By attaching the "function stop nut" and fixing the sensing rod to prevent movement, the signal transmission function can be stopped.



※ 5 Available Country : B01 does not support this function.
(Please contact us separately if necessary.)

3) Notes for Circuit Design

- Please read "Notes on Hydraulic Cylinder Speed Control Unit" for proper hydraulic circuit design. Improper circuit design may lead to malfunctions and damages. (Refer to P.40)

4) Swing lever should be designed to make the moment of inertia small.

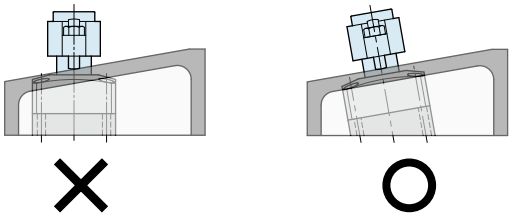
- Large moment of inertia will degrade the lever's stopping accuracy and cause undue wear to the clamp. Additionally, the clamp may not function, depending on supplied air pressure and lever mounting position.
- Set the swing time after the moment of inertia is calculated.
  Refer to "Allowable Swing Time Graph" and make sure to operate clamps within the allowable operation time.

5) Protect the exposed area of the piston rod when using on a welding fixture.

- If spatter attaches to the sliding surface it could lead to malfunction and fluid leakage.

6) When clamping on a sloped surface of the workpiece

- Make sure the clamping surface and the mounting surface of the clamp are parallel.



Notes for Usage

1) Do not cover the top surface of the sensing area with metal objects (chips, sludge, etc.). It may obstruct radio wave transmission. The cover is made of plastic material and should be protected from chips.

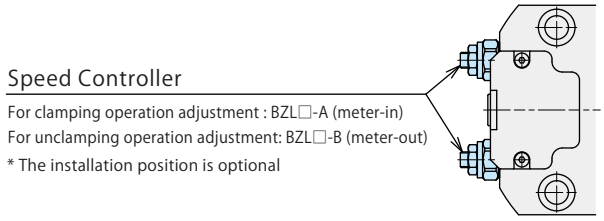
Installation Notes

1) Check the Usable Fluid

- Please use the appropriate fluid by referring to the Hydraulic Fluid List (P.39).

2) Swing Speed Adjustment

- Adjust the speed following "Allowable Swing Time Graph". If the clamp operates too fast the parts will be worn out leading to premature damage and ultimately complete equipment failure.
- Please make sure to release air from the circuit before adjusting speed. It will be difficult to adjust the speed accurately with air mixed in the circuit.
- Turn the speed control valve gradually from the low-speed side (small flow) to the high-speed side (large flow) to adjust the speed.
- When using multiple wireless sensing clamps / linear cylinders, provide an operating time difference of 100msec or more. Simultaneous operation may cause radio interference, which may result in failure to receive unclamp signals properly. For adjusting the unclamp operation, please use a speed control valve (meter-out).
- For clamping speed adjustment, install a speed control valve (meter-in) for each clamp.
- To adjust the speed of both unclamping and clamping operations, install one speed control valve BZL□-A (meter-in) and one BZL□-B (meter-out) on the two G-thread sections of the clamp body, respectively. Installation position is flexible; speed adjustment is possible regardless of which side it is installed to. Furthermore, when adjusting either the unclamping or clamping speed, it can be adjusted regardless of the installation position.



3) Installation of the Product

- When mounting the clamp, use hexagonal socket bolts as multiple bolt holes for mounting (with tensile strength of 12.9) and tighten them with the torque shown in the table below. Tightening with greater torque than recommended can dent the seating surface or break the bolt.

Model No.	Mounting Bolt Size	Tightening Torque (N·m)
LGM0480	M5×0.8	6.3
LGM0550	M6×1	10
LGM0650	M6×1	10
LGM0750	M8×1.25	25

4) Installation / Removal of the Swing Lever

- Oil or debris on the tightened parts of the lever, taper sleeve or piston rod may cause the rod to loosen. Please clean them thoroughly before installation.
- Tighten the tightening bolt of swing lever with the torque shown below. Tightening with greater torque than recommended can damage the bolt and lever tightening function.

LGM Standard：Taper Lock Lever

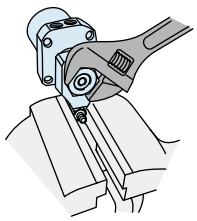
Model No.	Thread Size	Tightening Torque (N·m)
LGM0480	M16×1.5	37 ~ 45
LGM0550	M18×1.5	59 ~ 71
LGM0650	M22×1.5	93 ~ 112
LGM0750	M28×1.5	147 ~ 177

- In case of Using LGM Standard (Taper Lock Lever)

If the piston rod is subjected to excessive torque or shock, the rod or the internal mechanism may be damaged. Observe the following points to prevent such shock.

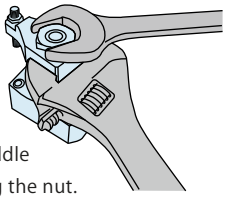
Installation Procedure

① With a clamp positioned to a jig, determine the lever position, and tighten the nut for fixing the lever (temporal tightening).



② Remove the clamp from the jig, fix the lever with a machine vise etc., and tighten the nut.

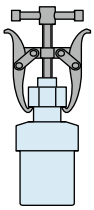
③ If tightening the nut with the clamp positioned to the jig, use a wrench to the hexagon part of piston rod, or fix the lever with a spanner. It is best to bring the lever to the middle of the swing stroke before tightening the nut.



Removal Procedure

① While the clamp is on the jig or vise, use a hex wrench to bring the lever to the middle of the swing stroke and then loosen the nut.

② Loosen the nut after securing the lever two or three turns then remove the lever with a puller without any rotational torque applied on the piston rod.



5) Initial Connection Settings for the Receiver

During setup, it is necessary to perform the initial connection settings between the clamp and the receiver. (For detailed instructions, refer to the instruction manual of receiver YWA.)

6) Cautions for Repeater Installation

The maximum distance between the clamp and the receiver is 5 meters. Check the radio wave strength displayed on the receiver and consider the installation of the repeater.
(Recommended Threshold：−85dBm)
It is recommended to install the repeater in locations such as the upper part inside the processing machine, where it is less likely to be exposed to coolant or chips.

Guidelines for Repeater Installation

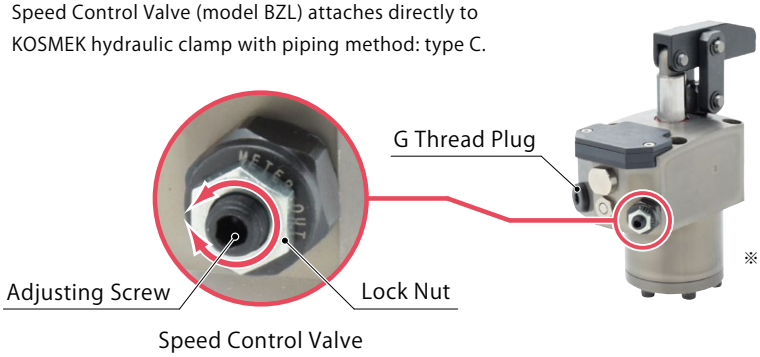
① When the receiver cannot be installed at a height of 2 meters or more.
② When there is a radio wave obstruction between the clamp and the receiver.
③ When the clamp and the receiver are more than 3 meters apart.

※ Please refer to P.39 for common cautions. • Installation Notes • Hydraulic Fluid List • Notes on Hydraulic Cylinder Speed Control Circuit • Notes on Handling • Maintenance/Inspection • Warranty

Speed Control Valve (For Low Pressure)

Directly Mounted to Clamps / Cylinders

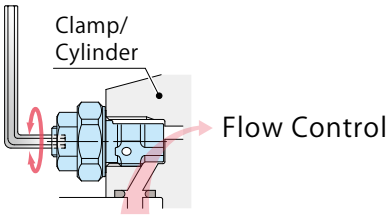
Speed Control Valve (model BZL) attaches directly to KOSMEK hydraulic clamp with piping method: type C.



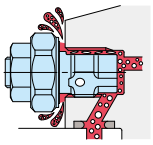
※ The picture shows a link clamp (model LKM).

Action Description

Control the flow with a wrench. Able to change the operating speed of a clamp/cylinder individually.



Able to release the air in the circuit by loosening the Speed Control Valve.



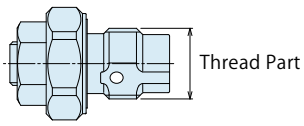
Model No. Indication (Speed Control Valve for Low Pressure)

BZL 0 10 1 - B

1 2 3

1 G Thread Size

10 : Thread Part G1/8A Thread
20 : Thread Part G1/4A Thread



2 Design No.

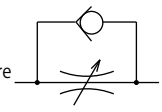
1 : Revision Number

3 Control Method

B : Meter-out
A : Meter-in

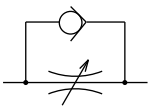
B

Circuit Symbol : Meter-out



A

Circuit Symbol : Meter-in



Specifications

Model No.		BZL0101-B	BZL0201-B	BZL0101-A	BZL0201-A
Max. Operating Pressure	MPa	7			
Withstanding Pressure	MPa	10.5			
Control Method		Meter-out		Meter-in	
G Thread Size		G1/8A	G1/4A	G1/8A	G1/4A
Cracking Pressure	MPa	0.12		0.04	
Max. Passage Area	mm^2	2.6	5.0	2.6	5.0
Usable Fluid	℃	0 ~ 70			
Operating Temperature		General Hydraulic Oil Equivalent to ISO-VG-32			
Tightening Torque for Main Body	N·m	10	25	10	25
Weight	g	12	26	12	26

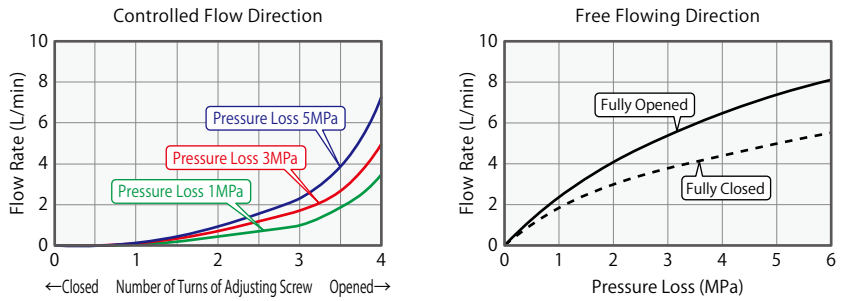
Notes : 1. It must be mounted with recommended torque. Because of the structure of the metal seal, if mounting torque is insufficient, the flow control valve may not be able to adjust the flow rate.
2. Do not attach a used BZL to other clamps/cylinders. Flow control will not be made because the bottom depth difference of G thread makes metal seal insufficient.

Applicable Products

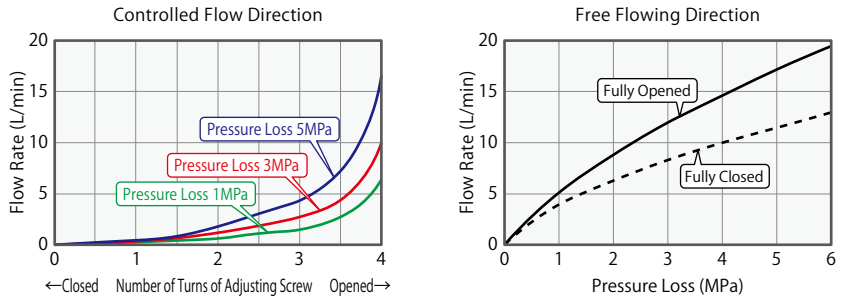
Model No.	LGM (Single Action) Swing Clamp	LJM (Single Action) Link Clamp
BZL0101-□	LGM0480-C□-B□ LGM0550-C□-B□	LJM0480-C□-B□ LJM0550-C□-B□
BZL0201-□	LGM0650-C□-B□ LGM0750-C□-B□	LJM0650-C□-B□ LJM0750-C□-B□

Flow Rate Graph <Hydraulic Fluids ISO-VG32 (25 ~ 35℃) >

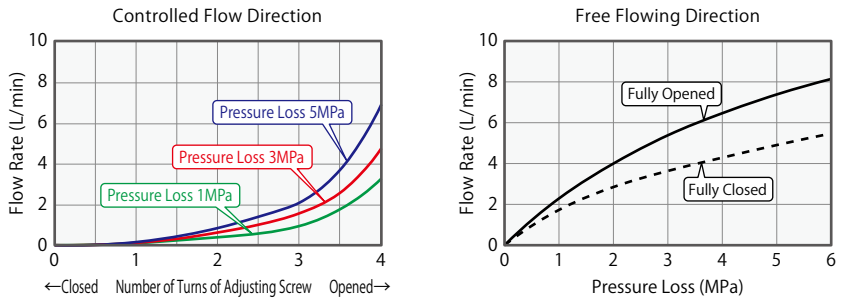
BZL0101-B : Meter-out



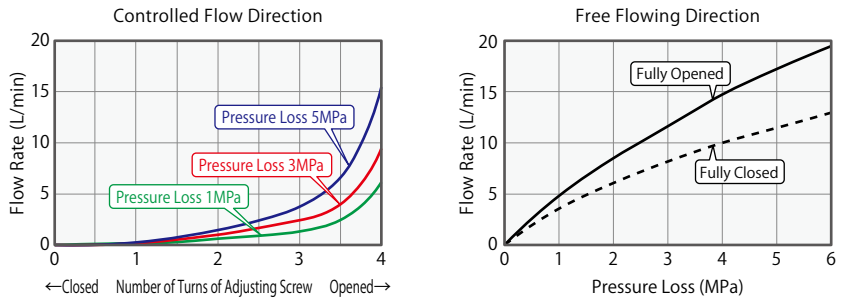
BZL0201-B : Meter-out



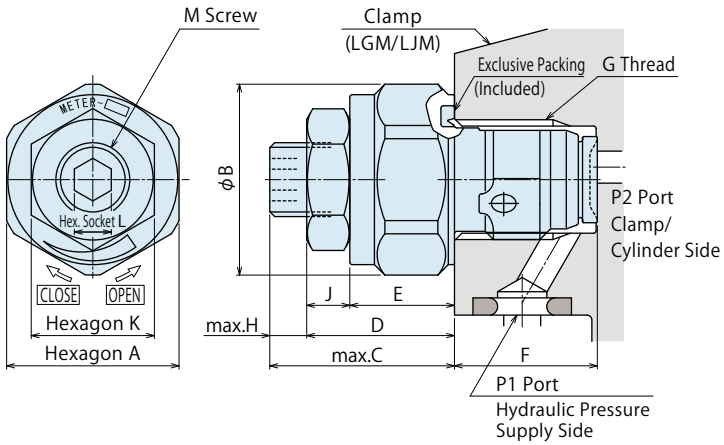
BZL0101-A : Meter-in



BZL0201-A : Meter-in



External Dimensions



(mm)

Model No.	BZL0101-□	BZL0201-□
A	14	18
B	15.5	20
C	15	16
D	12	13
E	8.5	9.5
F	(11.6)	(15.1)
G	G1/8	G1/4
H	3	3
J	3.5	3.5
K	10	10
L	3	3
M (Nominal×Pitch)	M6×0.75	M6×0.75

Notes

1. Please read "Notes on Hydraulic Cylinder Speed Control Unit" for proper hydraulic circuit design.
   Improper circuit design may lead to malfunctions and damages. (Refer to P.40)
2. It is dangerous to release the air under high pressure. It must be done under lower pressure.
   (For reference : the minimum operating range of the product within the circuit.)

Cautions

Installation Notes (For Hydraulic Series)

1) Check the Usable Fluid

- Please use the appropriate fluid by referring to the Hydraulic Fluid List.

2) Procedure before Piping

- The pipeline, piping connector and fixture circuits should be cleaned by thorough flushing.
- The dust and cutting chips in the circuit may lead to fluid leakage and malfunction.
- There is no filter provided with Kosmek's product except for a part of valves which prevents foreign materials and contaminants from getting into the circuit.

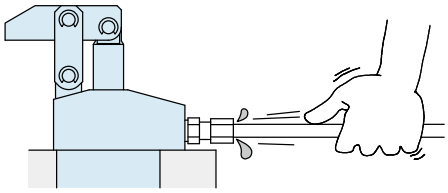
3) Applying Sealing Tape

- Wrap with tape 1 to 2 times following the screw direction.
- Pieces of the sealing tape can lead to oil leakage and malfunction.
- Please implement piping construction in a clear environment to prevent anything getting in products.

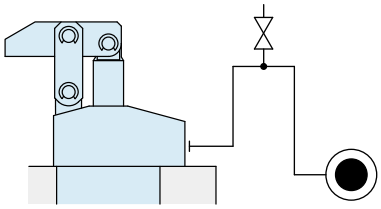
4) Air Bleeding of the Hydraulic Circuit

- If the hydraulic circuit has excessive air, the action time may become very long. If air enters the circuit after connecting the hydraulic port or under the condition of no air in the oil tank, please perform the following steps.

① Reduce hydraulic pressure to less than 2MPa.
② Loosen the cap nut of pipe fitting closest to the clamp by one full turn.
③ Shake the pipeline to loosen the outlet of pipe fitting.
Hydraulic fluid mixed with air comes out.



④ Tighten the cap nut after bleeding.
⑤ It is more effective to release air at the highest point inside the circuit or at the end of the circuit.
(Set an air bleeding valve at the highest point inside the circuit.)



5) Checking Looseness and Retightening

- At the beginning of the machine installation, the bolt and nut may be tightened lightly. Check the looseness and re-tighten as required.

Hydraulic Fluid List

ISO Viscosity Grade ISO-VG-32

Maker	Anti-Wear Hydraulic Oil	Multi-Purpose Hydraulic Oil
Showa Shell Sekiyu	Tellus S2 M 32	Morlina S2 B 32
Idemitsu Kosan	Daphne Hydraulic Fluid 32	Daphne Super Multi Oil 32
JX Nippon Oil & Energy	Super Hyrando 32	Super Mulpus DX 32
Cosmo Oil	Cosmo Hydro AW32	Cosmo New Mighty Super 32
ExxonMobil	Mobil DTE 24	Mobil DTE 24 Light
Matsumura Oil	Hydol AW-32	
Castrol	Hyspin AWS 32	

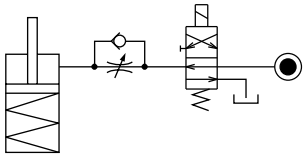
Note : Please contact manufacturers when customers require products in the list above.

Notes on Hydraulic Cylinder Speed Control Unit

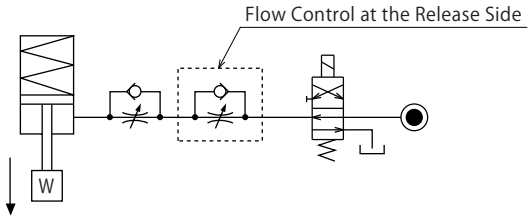
Please pay attention to the cautions below. Design the hydraulic circuit for controlling the action speed of hydraulic cylinder. Improper circuit design may lead to malfunctions and damages. Please review the circuit design in advance.

Speed Control Circuit for Single Acting Cylinder

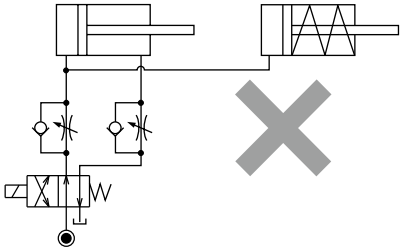
For spring return single acting cylinders, restricting flow during release can extremely slow down or disturb release action. The preferred method is to control the flow during the lock action only. It is also preferred to provide a flow control valve at each actuator which has limited action speed (swing clamp, hydraulic compact cylinder, etc.)



If the cylinder may be damaged by the load from the releasing action direction, provide the flow control valve to the releasing side as well. (Provide the flow control valve to the releasing side if the lever weight is applied during release action.)

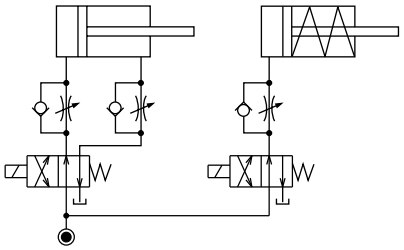


Single acting components should not be used in the same flow control circuit as the double acting components. The release action of the single acting cylinders may become erratic or very slow.

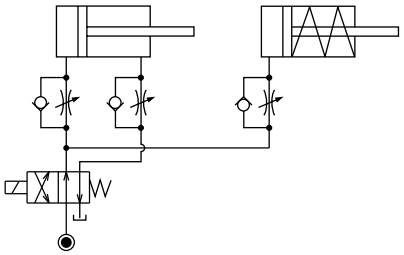


Refer to the following circuit when both the single acting cylinder and double acting cylinder are used together.

○ Separate the control circuit.



○ Reduce the influence of double acting cylinder control unit. However, due to the back pressure in tank line, single acting cylinder is activated after double acting cylinder works.



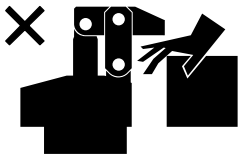
Cautions

Notes on Handling

1) It should be operated by qualified personnel.
- Machines and devices with hydraulic and pneumatic products should be operated and maintained by qualified personnel.

2) Do not operate or remove the product unless the safety protocols are ensured.
① Machines and devices can only be inspected or prepared when it is confirmed that the safety devices are in place.
② Before the product is removed, make sure that the above-mentioned safety devices are in place. Shut off the pressure and power source, and make sure no pressure exists in the air and hydraulic circuits.
③ After stopping the product, do not remove until the temperature drops.
④ Make sure there is no trouble/issue in the bolts and respective parts before restarting a machine or device.

3) Do not touch a clamp (cylinder) while it is working.
Otherwise, your hands may be injured due to clinching.



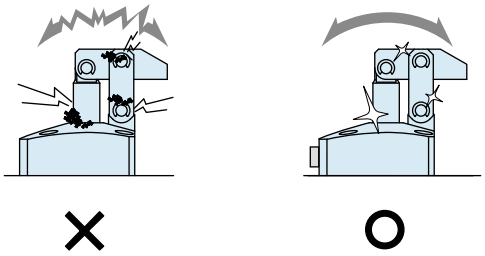
4) Do not disassemble or modify.
- If the equipment is taken apart or modified, the warranty will be voided even within the warranty period.

5) Do not cover the top surface of the sensing area with metal objects (chips, sludge, etc.).
- It may obstruct radio wave transmission. The cover is made of plastic material and should be protected from chips.

Maintenance and Inspection

1) Removal of the Machine and Shut-off of Pressure Source
- Before the machine is removed, make sure that safety devices and preventive devices are in place. Shut off the pressure and power source, and make sure no pressure exists in the air and hydraulic circuits.
- Make sure there is no abnormality in the bolts and respective parts before restarting.

2) Regularly clean the area around the piston rod.
- If it is used when the surface is contaminated with dirt, it may lead to packing seal damage, malfunctioning and fluid leakage.



3) If disconnecting by couplers, air bleeding should be carried out on a regular basis to avoid air mixed in the circuit.

4) Regularly tighten pipe line, mounting bolt, nut, snap ring, cylinder and others to ensure proper use.

5) Make sure the hydraulic fluid has not deteriorated.

6) Make sure there is a smooth action without an irregular noise.
- Especially when it is restarted after left unused for a long period, make sure it can be operated correctly.

7) The products should be stored in the cool and dark place without direct sunshine or moisture.

8) Please contact us for overhaul and repair.

Warranty

1) Warranty Period

- The product warranty period is 18 months from shipment from our factory or 12 months from initial use, whichever is earlier.

2) Warranty Scope

- If the product is damaged or malfunctions during the warranty period due to faulty design, materials or workmanship, we will replace or repair the defective part at our expense.
  Defects or failures caused by the following are not covered.

① If the stipulated maintenance and inspection are not carried out.
② If the product is used while it is not suitable for use based on the operator's judgment, resulting in defect.
③ If it is used or operated in an inappropriate way by the operator. (Including damage caused by the misconduct of the third party.)
④ If the defect is caused by reasons other than our responsibility.
⑤ If repair or modifications are carried out by anyone other than Kosmek, or without our approval and confirmation, it will void warranty.
⑥ Other caused by natural disasters or calamities not attributable to our company.
⑦ Parts or replacement expenses due to parts consumption and deterioration.
(Such as rubber, plastic, seal material and some electric components.)

Damages excluding from direct result of a product defect shall be excluded from the warranty.

Please refer to the separate catalog for the receiver and repeater.

Receiver

Model **YWA**

Repeater

Model **YWB**

Kosmek Website
https://www.kosmek.com/

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- For Further Information on Unlisted Specifications and Sizes, Please call us.
- Specifications in this Leaflet are Subject to Change without Notice.

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